



STANFORD

Lecture 14

MAC GDFEs and Design Measures

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Announcements & Agenda

■ Announcements

- PS7 – last homework – nominally due end of week before dead week, but accepted on Monday also
 - Basically have 2 weeks from today, counts double
- Section 5.4
- 2023: will skip L13's (ZF/MMSE Convergence p 31-35),

■ Agenda

- MAC and GDFE Comparison (Sec 5.4.1)
- Tonal MAC with DMT (Section 5.4.2)
 - Tonal GDFE
 - SWF
- Designs with weighted sums (Section 5.4.3)

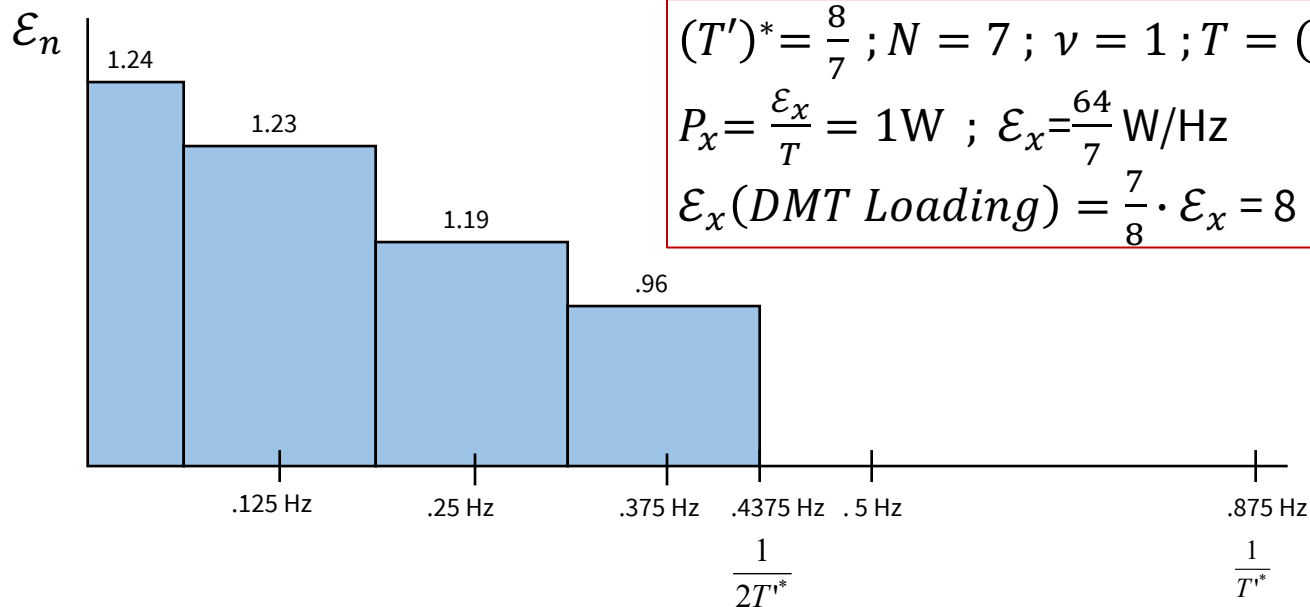
■ Problem Set 7 = PS7 (due May 28)

1. 5.16 A tonal channel
2. 5.17 GDFE MAC Design
3. 5.18 Dual computations
4. 5.19 GDFE BC design via duality
5. 5.20 IC with/without GDFE



L13 conclusion

Resampled $1+.9D^{-1}$ Another way to match WF to singularity



$$(T')^* = \frac{8}{7} ; N = 7 ; \nu = 1 ; T = (N + \nu) \cdot (T')^* = \frac{64}{7} ;$$

$$P_x = \frac{\mathcal{E}_x}{T} = 1\text{W} ; \mathcal{E}_x = \frac{64}{7} \text{W/Hz}$$

$$\mathcal{E}_x(\text{DMT Loading}) = \frac{7}{8} \cdot \mathcal{E}_x = 8 \text{ W/Hz}$$

- No more zeroed bands



Resampled Design Matlab Commands

```
>> D=exp(j*[0:100]*(7/8)*.01*pi);
>> H7=sqrt(8/7)*(ones(1,101)+.9*D);
>> H7=[H7,conj(H7(101:-1:2))];
>> h7=real(iff(H7));
>> h=[h7(200:201),h7(1:5)] =
-0.1011 0.9393 1.1979 -0.0603 0.0394 -0.0292 0.0232
>> H=toeplitz([h(1),h(7:-1:2)]',h) =
-0.1011 0.9393 1.1979 -0.0603 0.0394 -0.0292 0.0232
0.0232 -0.1011 0.9393 1.1979 -0.0603 0.0394 -0.0292
-0.0292 0.0232 -0.1011 0.9393 1.1979 -0.0603 0.0394
0.0394 -0.0292 0.0232 -0.1011 0.9393 1.1979 -0.0603
-0.0603 0.0394 -0.0292 0.0232 -0.1011 0.9393 1.1979
1.1979 -0.0603 0.0394 -0.0292 0.0232 -0.1011 0.9393
0.9393 1.1979 -0.0603 0.0394 -0.0292 0.0232 -0.1011
>> H=sqrt(1/.181)*H;
>> J7=hankel([zeros(1,6),1]');
>> Q7=(1/sqrt(7))*J7*fft(J7);
>> rXX=diag([1.23,1.19,.96,.96,1.19,1.23,1.24]);
>> rxx=real(Q7'*rXX*Q7);
>> Phibar=lohc(rxx);
>> A=Phibar;
```

```
>> [snrGDFEu, GU, WU, S0, MSWMFU, b, bbar] = computeGDFE(H, A, 2,
8)
```

snrGDFEu = 9.1416 dB (higher, but at lower symbol rate)

GU =

1.0000	0.4783	-0.0492	-0.0074	0.0208	-0.0760	0.4583
0	1.0000	0.5663	-0.0507	-0.0100	0.0385	-0.2577
0	0	1.0000	0.5952	-0.0517	-0.0208	0.1470
0	0	0	1.0000	0.6049	-0.0463	-0.0833
0	0	0	0	1.0000	0.6042	-0.0105
0	0	0	0	0	1.0000	0.6074
0	0	0	0	0	0	1.0000

MSWMFU =

-0.0173	0.0040	-0.0050	0.0068	-0.0103	0.2054	0.1611
0.1971	-0.0222	0.0069	-0.0089	0.0125	-0.1032	0.1701
0.1583	0.2097	-0.0250	0.0095	-0.0127	0.0677	-0.0866
-0.0808	0.1539	0.2145	-0.0268	0.0118	-0.0445	0.0590
0.0559	-0.0786	0.1520	0.2166	-0.0283	0.0302	-0.0397
-0.0401	0.0562	-0.0788	0.1522	0.2163	-0.0258	0.0308
0.0724	-0.0769	0.0956	-0.1281	0.2194	0.1136	-0.0825

>> b' =

0.9313	0.8775	0.8700	0.8691	0.8690	0.8697	0.7970
--------	--------	--------	--------	--------	--------	--------

>> bbar = 1.6013

>> R=bbar*(7/8) = 1.4718 (bits/sec) > 1.3814 bits/sec (same as interp)

Also
7 Dimensions

Converges
On GU

(and WU
Not shown)

See also the two-band example in Section 5.3

- Tedious but could be helpful in following details for a multiband CDFE (e.g. – uplink carrier aggregation with multiple resource blocks in Cellular)



Some Final Comments

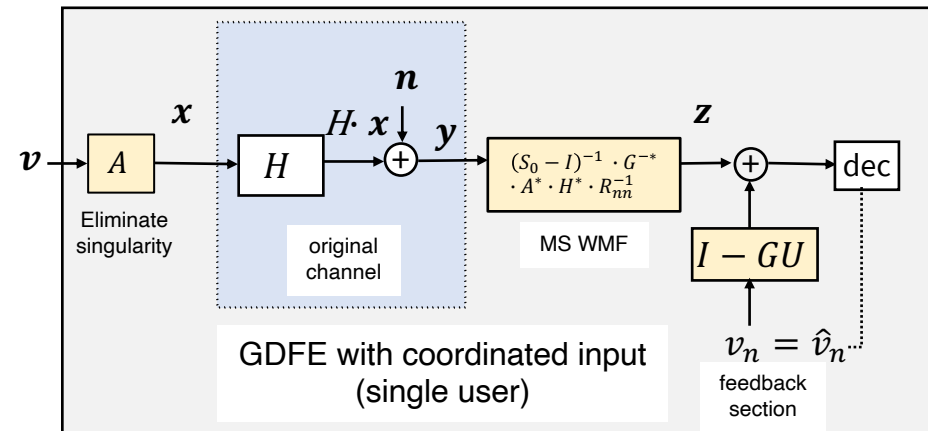
- The GDFE is canonical – capacity rate is reliably achievable with $\Gamma = 0$ (or capacity less shaping loss)
- GDFE can have error propagation (limited to \bar{N}) if $\Gamma > 0$ dB
 - Unless it is VC (\sim DMT), which is ML decoder uniquely among all GDFEs
 - Other GDFE's becoming increasingly less favorable performance relative to VC/DMT as gap grows
- The DMT form benefits from FFT algorithms so also more cost effective than the others
- By Separation Theorem, Coded-OFDM can capture the DMT benefits also without error propagation
 - But will rapidly lose performance relatively if input is not water filling
- The MMSE-DFE is limiting (stationary) case of the CDFE and can be canonical
 - Set of MMSE-DFE's for each of which PWC holds
 - Has unlimited error propagation (use precoder) and also degrades more rapidly for nonzero-gap codes

Eventual Global Conclusion: Use DMT (wireline) or C-OFDM (wireless) on almost all difficult single-user transmission systems



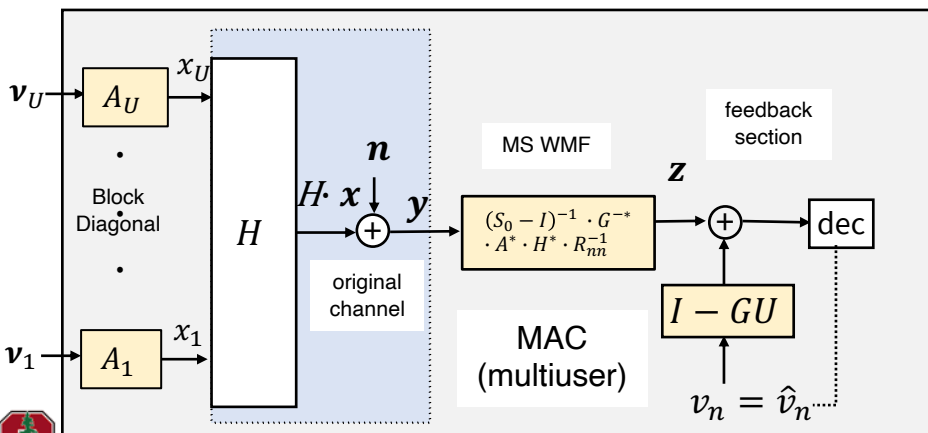
MAC and GDFE Comparison

The MMSE MAC vs MMSE GDFE



■ GDFE

- Designed for "single-user" H ; $A = R_{xx}^{1/2}$
- MMSE: $R_b^{-1} = R_{xx}^{-*/2} \cdot H^* \cdot R_{nn}^{-1} \cdot H \cdot R_{xx}^{-1/2} + I = G \cdot S_0 \cdot G^*$
- Canonical decision feedback (decisions correct)
- Input restriction $trace\{R_{xx}\} \leq \mathcal{E}_x$
- Rate does not depend on dimensional order (no err prop)



■ MAC

- Designed for block-diag $trace\{R_{xx}\} \leq \mathcal{E}_x$
 - only in energy-sum case
- Usually has input energies $trace\{R_{xx}(u)\} \leq \mathcal{E}_u$; separation locations; $A_u = R_{xx}^{1/2}(u)$; $A = R_{xx}^{1/2}$
- MMSE: $R_b^{-1} = R_{xx}^{-*/2} \cdot H^* \cdot R_{nn}^{-1} \cdot H \cdot R_{xx}^{-1/2} + I = G \cdot S_0 \cdot G^*$
- Canonical decision feedback (decisions correct)
 - by user – order is more important



A Scalar Example Revisited

■ MAC 80/60 channel

```
>> H=[80 60];
>> Rxx=0.5*eye(2); (equal energy both dim/users)
>> A=[sqrt(.5) 0' ; 0 sqrt(.5) ];
>> Lxu=[1 1];
>> cb=2;

>> [b, GU, WU, S0, MSWMFU] = mu_mac(H, A, Lxu , cb);

b = 5.8222 0.3218
GU = 1.0000 0.7500 MSWMFU = 0.0177
      0 1.0000      0.0236
S0 = 1.0e+03 *
      3.2010 0
      0 0.0016

>> sum(b) = 6.1440
>> 10*log10(2^(6.1440)-1) = 18.4334 dB
```

■ GDFE – remove singularity

```
>> [F,L,M]=svd(H);
>> [F,L,M]=svd(H)
F = 1
L = 100 0
M =
      0.8000 -0.6000
      0.6000 0.8000
>> 0.5*log2(1+ 0.5*L(1)^2) = 6.1440
```

All energy on pass space

```
>> 0.5*log2(1+ L(1)^2) = 6.64 > 6.144
```

- But input is $\mathbf{x} = \begin{bmatrix} .800 \\ .600 \end{bmatrix} \cdot v$
- v goes to both channel input dimensions (not MAC)
- All GDFE's with this input $R_{xx} = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$ perform same
 - And trivially have $G = 1$



Or use computeGDFE.m

```
>> [snrGDFEu, GU, WU, S0, MSWMFU, b, bbar,  
snrGLEu] = computeGDFE(H, A, cb)
```

```
snrGDFEu = 18.4334 dB
```

```
GU =  
1.0000 0.7500  
0 1.0000
```

```
WU =  
0.0003 0  
-1.3333 1.7783
```

```
S0 = 1.0e+03 *  
3.2010 0  
0 0.0016
```

```
MSWMFU =  
0.0177  
0.0236
```

```
b =  
5.8222  
0.3218
```

```
bbar = 3.0720  
snrGLEu = 16.8125 dB  
>> sum(b) = 6.1440
```

No Lx
input

```
>> [F,L,M]=svd(H);  
>> Lx=2;  
[snrGDFEu, GU, WU, S0, MSWMFU, b, bbar, snrGLEu] =  
computeGDFE(H, M(:,1), cb, Lx)
```

```
snrGDFEu = 19.9566
```

```
GU = 1  
WU = 1.0000e-04
```

```
S0 = 10001  
MSWMFU = 0.0100
```

```
b = 6.6439  
bbar = 3.3220
```

```
snrGLEu = 19.9566 (dB) – linear is same for VC
```

(same energy, but more going to best mode)

Not a MAC
A not diag

**Better to use mu_mac with a MAC,
Than to play with cb & Lx on computeGDFE,
which is really for single user GDFEs,**

Similarly: use computeGDFE on single user

Correct comparison with GDFE notes the A input has 2 real dimensions
VC resets the Lx to 2 as optional 4th computeGDFE input



MAC Loss

- MAC Loss – ratio of single-user capacity SNR to MAC maximum-rate-sum SNR (for $[H \quad R_{nn}]$)

$$\gamma_{MAC} \triangleq \frac{2^{2 \cdot \bar{c}} - 1}{2^{2 \cdot \bar{c}_{e-sum}} - 1}$$

- For the previous example $\gamma_{MAC} = \frac{2^{6.64} - 1}{2^{6.144} - 1} = 1.5 \text{ dB}$

- Clearly $0 \leq \gamma_{MAC} \leq 1$

See also *split-dimensionality* example in Section 5.4.1



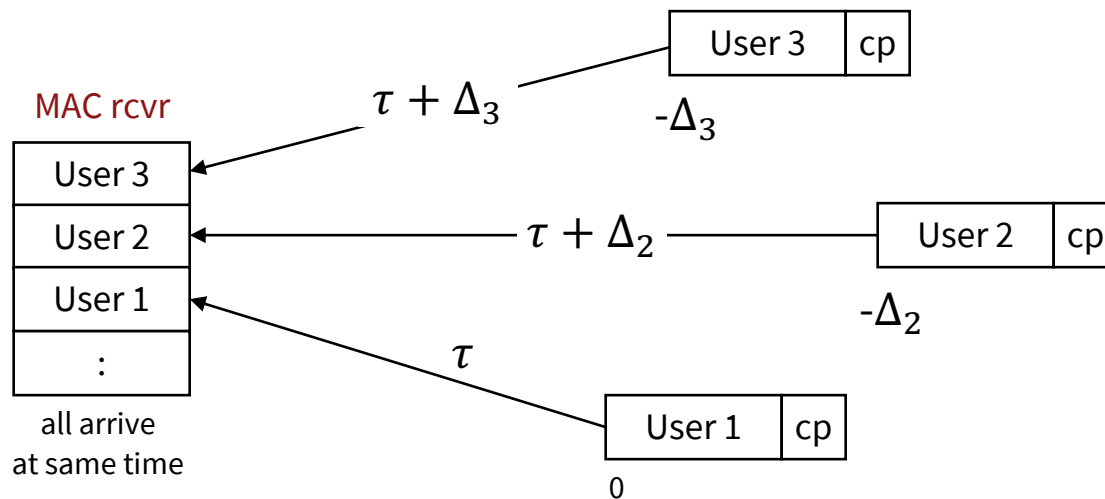
Tonal MAC (with DMT)

Section 5.4.2

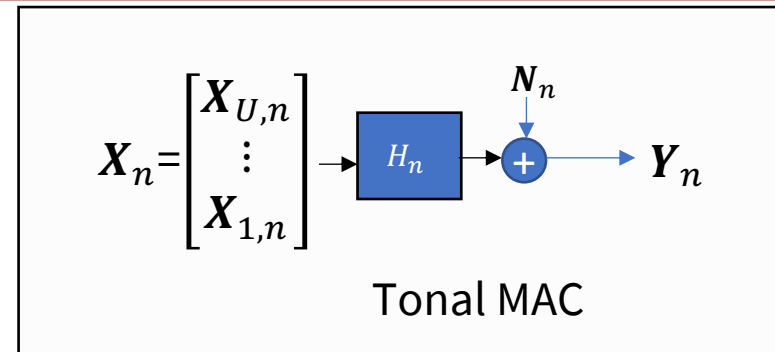
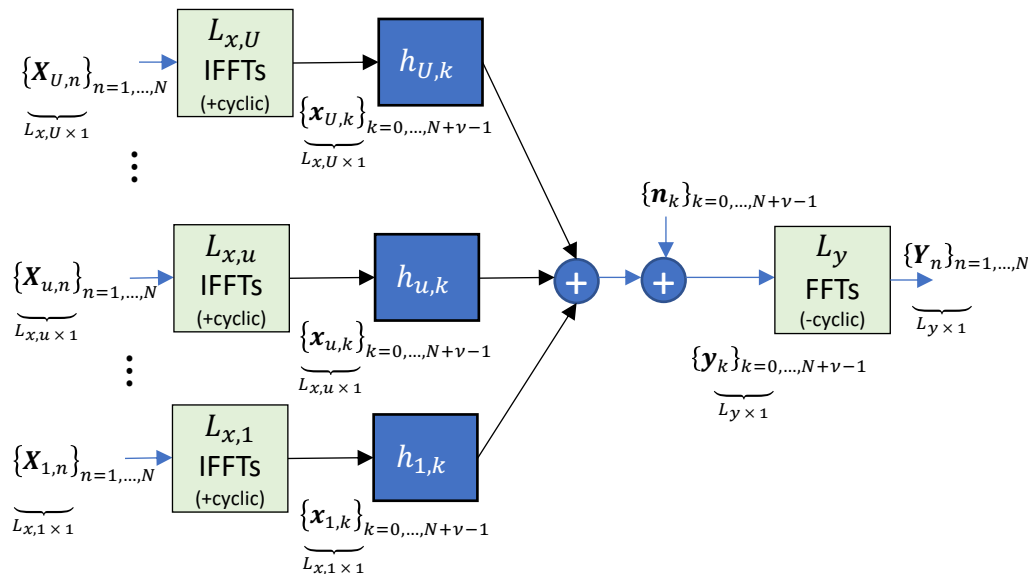
Note Section 5.4.1's two-user ISI-GDFE is interesting, but largely becomes superfluous with the tonal vector-DMT system.

Align Receiver DMT Symbols for MAC

- So far, examples have largely been space time (with a few antennas)
- In practice, there usually is also a temporal (time-freq) C-OFDM or DMT system **also** present.



Vector DMT/OFDM with MAC



$$R_{XX}(u, n) = \mathbb{E}[X_{u,n} \cdot X_{u,n}^*]$$

$$\sum_n \text{trace} \{R_{XX}(u, n)\} \leq \epsilon_u \quad \forall u = 1, \dots, U$$

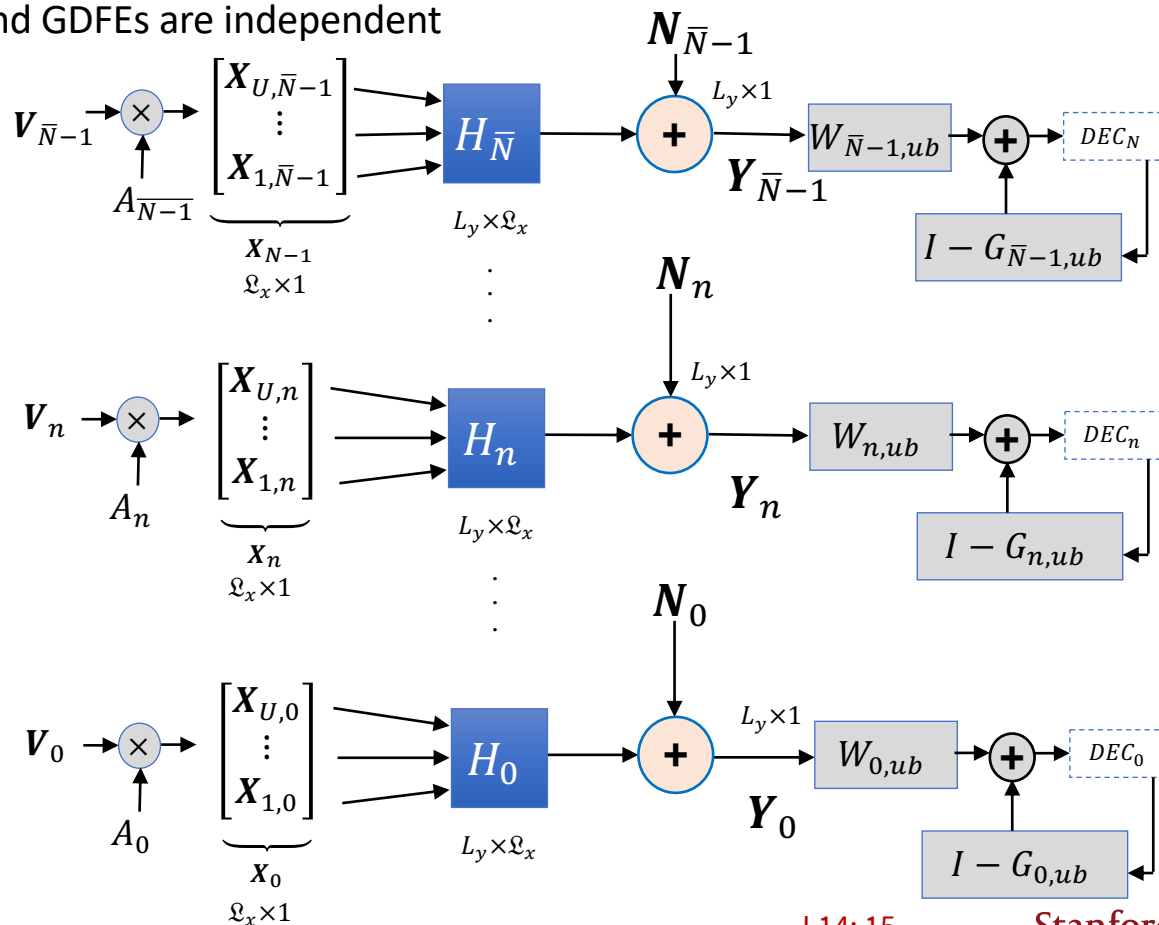
$$\text{Esum-MAC: } \sum_{u=1}^U \sum_{n=0}^{\bar{N}} \text{trace} \{R_{XX}(u, n)\} \leq \epsilon_x$$

- Symbol boundaries align through cyclic-extension (guard period) uses (even with different channel delays)
- Basically, an IFFT per transmit-antenna-user
- Discrete version of the MT MAC, indeed all SVD's, Cholesky's, and QR factorizations become "frequency-dependent" (in limit)



Tonal GDFEs with MAC

- Discrete tonal modulators and GDFEs are independent



- Put an “ n ” index on all the GDFE design equations

$$b_{u,\ell} = \sum_{n=0}^{N-1} b_{u,\ell,n}$$

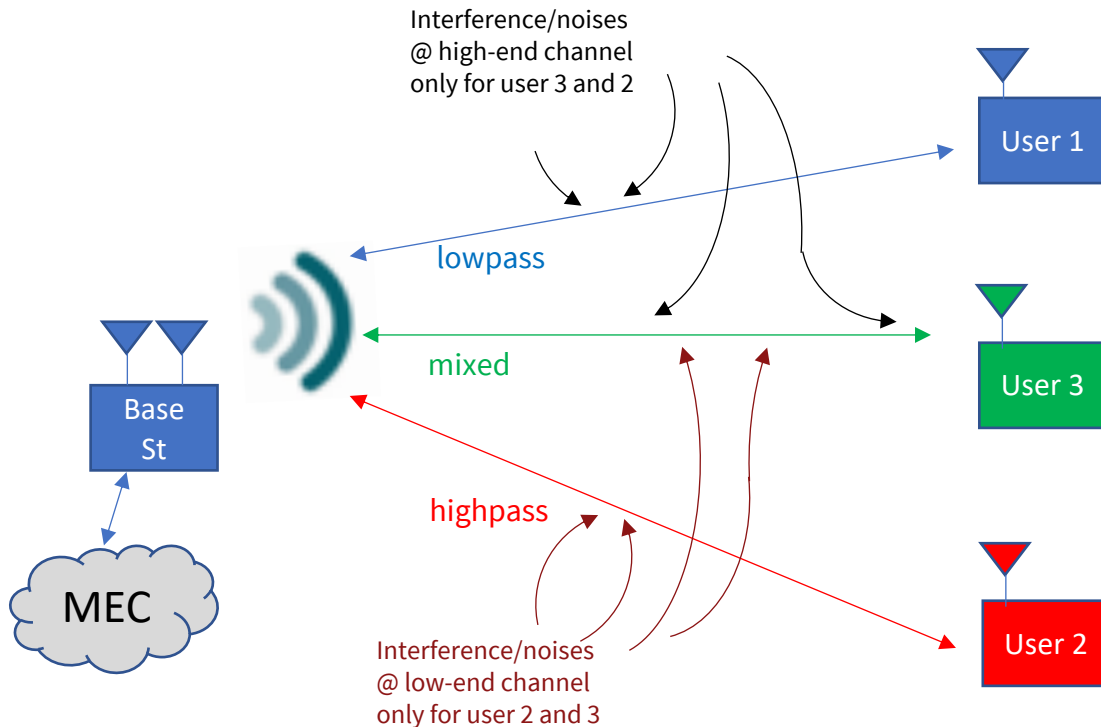
$$b_{u,n} = \sum_{\ell=1}^{L_{x,u}} b_{u,\ell,n}$$

$$b_u = \sum_{\ell=1}^{L_{x,u}} \sum_{n=0}^{N-1} b_{u,\ell,n}$$

$$b = \sum_{u=1}^U \sum_{\ell=1}^{L_{x,u}} \sum_{n=0}^{N-1} b_{u,\ell,n}$$



Example complex BB channel



More users than antennas

Allow up to 64 resource Blocks (tones) for each user, all in same channel

- Illustrates many effects

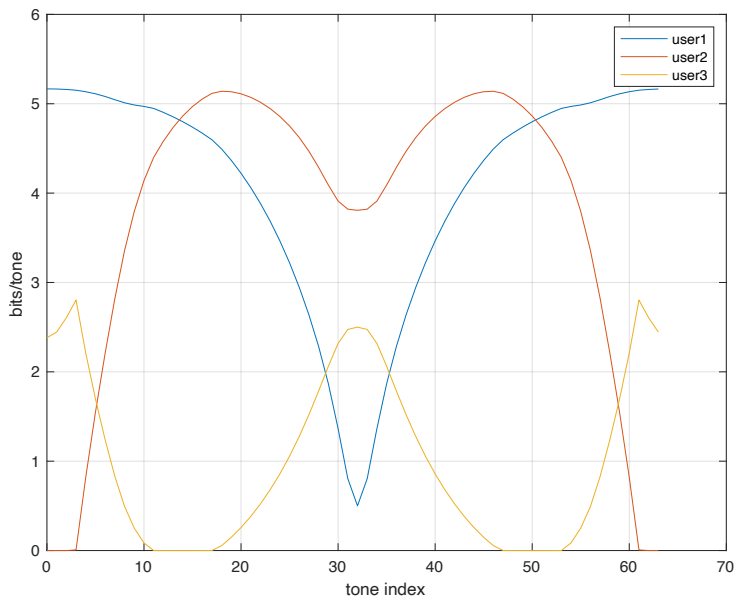
$$H(D) = \begin{bmatrix} 1 + .9 \cdot D & -.3 \cdot D + .2 \cdot D^2 & .8 \\ .5 \cdot D - .4 \cdot D^2 & 1 - D - .63 \cdot D^2 + .648 \cdot D^3 & 1 - D \end{bmatrix}$$



Example has ISI and MIMO together

- 3 user channels
- Any tone will maximally have rank $\rho_H=2$; $\mathcal{N}_0 = .01$

$$H(D) = \begin{bmatrix} 1 + .9D & -.3D + .2D^2 & .8 \\ .5D - .4D^2 & 1 - D - .63D^2 + .648D^3 & 1 - D \end{bmatrix}$$



```

h=cat(3,[1 0.8; 0 1 1],[.9 -.3 0; .5 -1 -1],[0 .2 0; .4 -.63 0],[0 0 0; 0 .648 0])*10;
h(:,:,1)=
    10    0    8
     0   10   10
h(:,:,2)=
     9   -3    0
     5  -10  -10
h(:,:,3)=
     0   2.0000    0
    4.0000 -6.3000    0
h(:,:,4)=
     0    0    0
     0   6.4800    0
N=8;
H = fft(h, N, 3)
>> H = fft(h, N, 3)
H(:,:,1) =
    19.0000 + 0.0000i  -1.0000 + 0.0000i   8.0000 + 0.0000i
    9.0000 + 0.0000i   0.1800 + 0.0000i   0.0000 + 0.0000i
H(:,:,2) =
    16.3640 - 6.3640i  -2.1213 + 0.1213i   8.0000 + 0.0000i
     3.5355 - 7.5355i  -1.6531 + 8.7890i   2.9289 + 7.0711i
And 6 more values, see text
    
```

← Increase to 64 – look ahead at
MAC with equal energy every dimension



Actual MAC/GDFE cacluations for L14:17

White-Input Tonal GDFE

```
Nmax=32;
U=3;
Ly=2;
cb=1;
Lxu=[1 1 1];
bsum=zeros(1,Nmax);
for index=1:Nmax
    i=2*index;
    H = fft(h, i, 3);
    GU=zeros(U,U,i);
    WU=zeros(U,U,i);
    S0=zeros(U,U,i);
    Bu=zeros(U,i);
    MSWMFU=zeros(U,Ly,i);
    AU=zeros(3,3,i);
    for n=1:i
        AU(:,n)=sqrt(i)/sqrt(i+3)*eye(3);
    end
    for n=1:i
        [Bu(:,n), GU(:,n), WU(:,n), S0(:,n), MSWMFU(:,n)] = ...
            mu_mac(H(:,n), AU(:,n), Lxu, cb);
    end
    bvec=sum(Bu');
    Bsum(index) = sum(bvec);
End
bvec = 445.1264 412.8794 132.7477
sum(bvec) = 990.7535
```

```
>> GU(:,23) =
    1.0000 + 0.0000i -1.3365 + 0.3447i -0.3093 + 0.3130i
    0.0000 + 0.0000i  1.0000 + 0.0000i  0.8108 + 0.4218i
    0.0000 + 0.0000i  0.0000 + 0.0000i  1.0000 + 0.0000i
>> MSWMFU(:,15) =
    0.0454 + 0.0341i -0.0105 + 0.0249i
    0.0183 + 0.0179i  0.0275 - 0.0468i
    0.0589 + 0.0199i  0.0179 - 0.0416i
>> SNRs = 10*log10(diag(S0(:,29)).^(64/67)-eye(3)) =

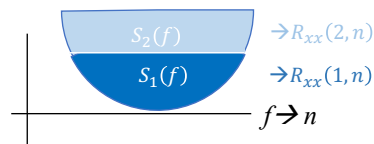
    12.1946
    20.7691
    8.8939
```

Feedback is sizeable



Simultaneous Water Filling with DMT

- Frequency $f \rightarrow$ tone index n



See also Section 2.7.4.2 and Lecture 8

- Find all noise and crosstalk

- $R_{noise}(u, n) = \sum_{i \neq u} H_{i,n} \cdot R_{XX}(i, n) \cdot H_{i,n}^* + R_{NN}(n)$

- Create a noise-equivalent that includes all other users as noise (no order, all)

- $\tilde{H}_{u,n} = R_{noise}^{-1/2}(u, n) \cdot H_{u,n} = F_{u,n} \cdot \Lambda_{u,n} \cdot M_{u,n}^*$

- Water-fill each user

- $\mathcal{E}_{u,l,n} + \frac{1}{g_{u,l,n}} = K_u \quad \forall n, l$ with $g_{u,l,n} = \lambda_{u,l,n}^2$

- Form resulting input autocorrelation matrices (energy distribution with $L_{x,u} = 1$)

- $R_{XX}^o(u, n) = M_{u,n} \cdot \text{Diag}\{\mathcal{E}_{u,n}\} \cdot M_{u,n}^* \quad \forall n = 0, \dots, \bar{N} - 1$

**With MT and Ly=1
There is always an FDM SWF solution**



SWF.m versus macmax.m

```
>> help SWF
function [Rxx, bsum , bsum_lin] = SWF(Eu, H, user_ind, Rnn, cb)
```

Simultaneous water-filling MAC max rate sum (linear and nonlinear GDFE)
The input is space-time domain h, and the user can specify a temporal block symbol size N (essentially an FFT size).

Inputs:

Eu U x 1 energy/SAMPLE vector. Single scalar equal energy all users

any $(N/N+nu)$ scaling should occur BEFORE input to this program.

H The FREQUENCY-DOMAIN $Ly \times \text{sum}(Lx(u)) \times N$ MIMO channel for all users.

N is determined from size(H) where $N = \# \text{ tones}$

(equally spaced over $(0,1/T)$ at N/T .

if time-domain h, $H = 1/\text{sqrt}(N) * \text{fft}(h, N, 3)$;

user_ind The start index for each user, in the same order as Eu

The Lxu vector of each user's number of antennas is computed internally. % U is determined from user_ind

Rnn The $Ly \times Ly \times N$ noise-autocorrelation tensor (last index is per tone)

cb cb = 1 for complex, cb=2 for real baseband

Outputs:

Rxx A block-diagonal psd matrix with the input autocorrelation for each

user on each tone. Rxx has size $(\text{sum}(Lx(u)) \times \text{sum}(Lx(u)) \times N$.

sum trace(Rxx) over tones and spatial dimensions equal the Eu

bsum the maximum rate sum.

bsum bsum_lin - the maximum sum rate with a linear receiver

b is an internal convergence sum rate value, not output

This program is modified version of one originally supplied by student

Chris Baca

Energy-Vector
MAC

```
function [Rxx, bsum , bsum_lin] = macmax(Eu, h, Lxu, N , cb)
```

Simultaneous water-filling Esum MAC max rate sum (linear & nonlinear GDFE)

The input is space-time domain h, and the user can specify a temporal block symbol size N (essentially an FFT size).

This program uses the CVX package

the inputs are:

Eu The sum-user energy/SAMPLE scalar.

This will be increased by the number of tones N by this program.

Each user energy should be scaled by $N/(N+nu)$ if there is cyclic prefix

This energy is the trace of the corresponding user Rxx (u)

The sum energy is computed as the sum of the Eu components internally.

h The TIME-DOMAIN $Ly \times \text{sum}(Lx(u)) \times N$ channel for all users

Lxu The number of antennas for each user $1 \times U$

N The number of used tones (equally spaced over $(0,1/T)$ at N/T .

cb cb = 1 for complex, cb=2 for real baseband

the outputs are:

Rxx A block-diagonal psd matrix with the input autocorrelation for each

user on each tone. Rxx has size $(\text{sum}(Lx(u)) \times \text{sum}(Lx(u)) \times N$.

sum trace(Rxx) over tones and spatial dimensions equal the Eu

bsum the maximum rate sum.

bsum bsum_lin - the maximum sum rate with a linear receiver

b is an internal convergence (vector, rms) value, but not sum rate

Energy-Sum
MAC

Up to N on h

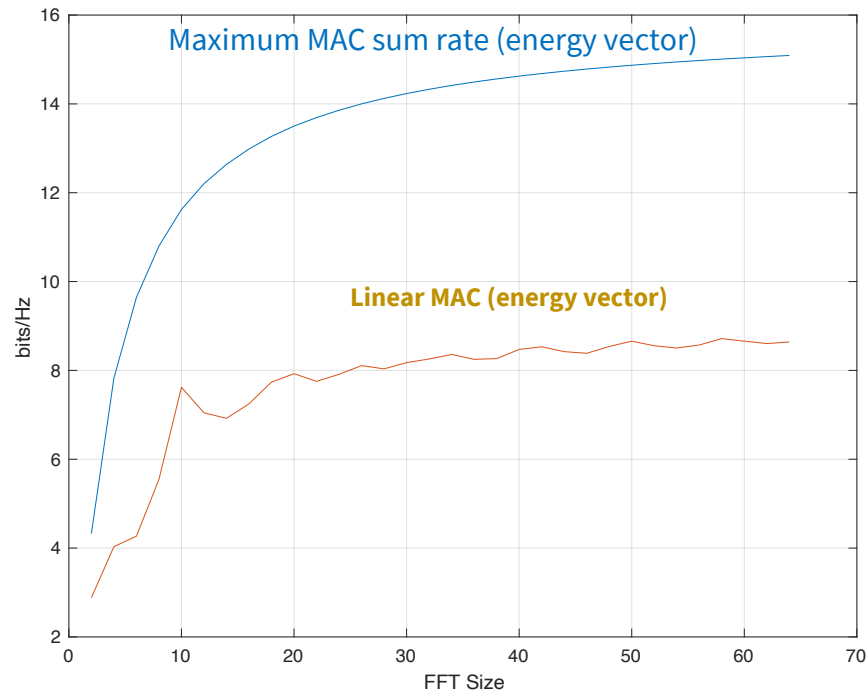
- SWF is frequency domain input (useful with non-white noise psd) and uses no CVX
- while macmax is time-domain (and uses Lxu instead of user_ind) and uses CVX -



Max Rate sum Example

```
h=cat(3,[1 0 .8 ; 0 1 1],[.9 -.3 0 ; .5 -1 -1],[0 .2 0 ; .4 -.63 0],[0 0 0 ; 0 .648 0])*10;  
bsum=zeros(1,Nmax);  
bsumlin=zeros(1,Nmax);  
  
for index=1:Nmax  
    i=2*index; % (don't need to plot a point for every number of tones)  
    H = fft(h, i, 3);  
    Rnn=zeros(Ly,Ly,i);  
    for n=1:i  
        Rnn(:, :, n) = eye(2);  
    end  
    [Rxx, bsum(index), bsumlin(index)] = SWF(i/(i+3)*[1 1 1], H, [1 1 1], Rnn(:, :, :), 1);  
    bsum(index)=bsum(index)/(i+3);  
    bsumlin(index)=bsumlin(index)/(i+3);  
end  
bsum(32)*67= 1011.1 > 990.8  
bsumlin(32)*67 = 578.8502  
plot(2*[1:Nmax], bsum, 2*[1:Nmax], bsumlin)
```

- Even with 3 users > 2 antennas, linear loses much
- ~ 20 dB (from “link budget)
- **Linear curve variation** is because \bar{N} is finite and the simultaneous water filling is not necessarily best solution under linear restriction
- When would “linear receiver be best?”



**If vector-coding could be used,
But not possible on MAC in general**

**The linear
max-sum prob
is not convex,
See OSB in Sec 5.6**



SWF energy/Rxx distribution

```

Rxx(:,1)
1.4504 0 0
0 0 0
0 0 1.3050
Rxx(:,2) =
1.4512 0 0
0 0 0
0 0 1.3120
Rxx(:,3) =
1.4528 0 0
0 0 0
0 0 1.3274
.....
Rxx(:,9) =
1.4419 0 0
0 0.0670 0
0 0 1.3303
Rxx(:,11) =
1.3170 0 0
0 1.0228 0
0 0 0.5748
Rxx(:,15) =
1.3889 0 0
0 1.4116 0
0 0 0.1513
Rxx(:,26) =
0.1384 0 0
0 1.4184 0
0 0 1.3192
    
```

```

.....
Rxx(:,27) =
0 0 0
0 1.4939 0
0 0 1.3767
Rxx(:,28) =
0 0 0
0 1.4885 0
0 0 1.3761
Rxx(:,31) =
0 0 0
0 1.4229 0
0 0 1.3689
Rxx(:,32) =
0 0 0
0 1.3394 0
0 0 1.3606
Rxx(:,39) =
0 0 0
0 1.4939 0
0 0 1.3767
Rxx(:,40) =
0.1384 0 0
0 1.4184 0
0 0 1.3192
Rxx(:,51) =
1.3889 0 0
0 1.4116 0
0 0 0.1513
Rxx(:,52) =
1.3871 0 0
0 1.3929 0
0 0 0.1700
    
```

```

Rxx(:,53) =
1.3678 0 0
0 1.3329 0
0 0 0.243
Rxx(:,57) =
1.4419 0 0
0 0.0670 0
0 0 1.3303
.....
Rxx(:,58) =
1.4577 0 0
0 0 0
0 0 1.3736
Rxx(:,59) =
1.4573 0 0
0 0 0
0 0 1.3693
Rxx(:,60) =
1.4567 0 0
0 0 0
0 0 1.3633
Rxx(:,61) =
1.4557 0 0
0 0 0
0 0 1.3548
Rxx(:,62) =
1.4544 0 0
0 0 0
0 0 1.3428
Rxx(:,63) =
1.4528 0 0
0 0 0
0 0 1.3274
    
```

$$\rho_{H,n} < U ??$$

With $\bar{N} > 1$, there can be some tones that use all 3 dimensions

These are equivalent to time-shared (dimension shared) of 2-user-only tones

Cannot happen when $\bar{N} = 1$ & $\rho_H < U$

**Also $L_y > 1$,
So FDM not assured**



Macmax

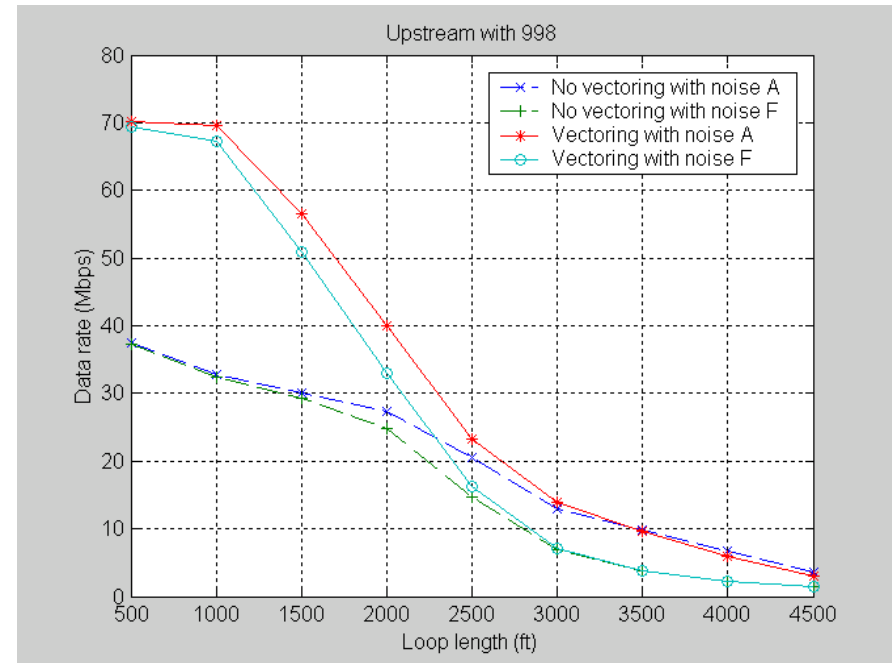
```
[RxxEsum, bsumEsum , bsum_linEsum] = macmax(3*64/67, h, [1 1 1], 64 , 1);  
  
bsumEsum = 1011.3 > 1011.2          (just slightly)  
bsum_linEsum = 571.7289 < 578.85    (no guarantee that linear version is best)  
  
>> sum(real(Rxx),3) =  
61.1343    0    0  
    0 61.1343    0  
    0    0 61.1343  
>> 64^2/67 = 61.1343 checks on each dimension  
>> trace(sum(real(Rxx),3)) = 183.4030 (clearly 3x single dimensional energy)
```

- The RxxEsum are very similar to those from SWF.m
- While many tones individually zero one user (consistent with secondary-component concept)
 - Not the same user for all such tones
 - Some energize all 3 users
- $\sum_n \rho_{H,n} > U$, significantly so. This means there is effectively dimension-sharing occurring over the 64 tones, at least for the rate-sum max.



Gain is larger when crosstalk is larger

- Binders of copper wires (think ethernet or your neighbor cable of telephone wires) crosstalk
 - Highly variable with twisting (even measuring point can lead to 20dB or more variation if moved an inch or two)
 - Probabilistic models (like wireless' distributions) used
 - Average xtalk is larger on SHORTER wires
 - Why?
 - They use higher frequencies that are less attenuated
- Example is vectored VDSL (upstream MAC)
- Each user has its own "link" that terminates (upstream) on a common receiver – by default all primary users (no time-sharing needed)
 - "perfect massive MIMO" all (used) tones (plot is for 25 links)
 - Can see up to $U=384$ links vectored (predates "massive MIMO" in invention and use by 10 years)
- The GDFE cancels the crosstalk
- It exhibits diagonal dominance too. Why?
 - So typically no feedback section used
- Actually, some "mgfast" (ITU G.9711) to 5 Gbps multiuser and 10 Gbps "fastback" (ITU G.9702), 2 pairs – 3 channels, single user can use some GDFE's at lowest frequencies



Wireless – uplink Cellular or Wi-Fi

- The C-OFDM systems are as in Lecture 6
- Common FFTs in the single MAC receiver (one for each spatial stream/dimension with MIMO)
- They share common frequencies
- Usually no feedback sections used Yet, so linear setting from computeGDFE provides performance

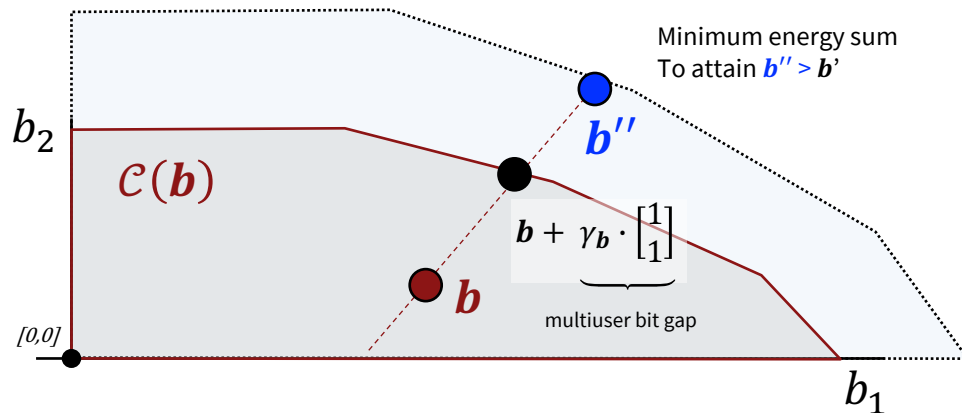
OK – All good, but what is $R_{xx}(u)$ when we don't maximize a rate sum??



Designs with weighted sums

Section 5.4.3

Capacity region(s)



- $\mathcal{C}(\mathbf{b})$ contains all possible weighted **rate** sums $\sum_{u=1}^U \theta_u \cdot b_u$ that meet **energy-vector** constraint $\boldsymbol{\varepsilon} \preceq \boldsymbol{\varepsilon}_x$
- The max-b-sum point is “highest” (tangent to plane $\mathbf{1}^t \cdot \mathbf{b}$) with \mathbf{b} in $\mathcal{C}(\mathbf{b})$, **but we want another \mathbf{b} !**
- If $\boldsymbol{\varepsilon} \preceq \boldsymbol{\varepsilon}_x$, **then \mathbf{b} is admissible**
- If not, we might still desire the minimum energy-sum that achieves \mathbf{b}



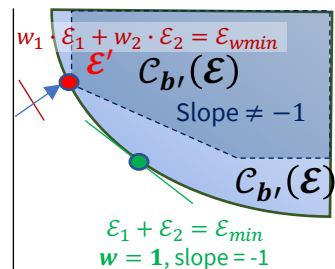
minimum weighted energy sum

- Minimize weighted energy sum \mathcal{E}_x , given \mathbf{b}
 - No energy limit (beyond minimum)
 - Energy weights \mathbf{w} given, non-negative

$$\min_{\{R\mathbf{x}\mathbf{x}(u)\}} \sum_{u=1}^U w_u \cdot \underbrace{\text{trace}\{R\mathbf{x}\mathbf{x}(u)\}}_{\mathcal{E}_u} \quad \mathcal{E}_2$$

$$ST: \quad \mathbf{b} \succeq [b_{1,\min} \ b_{2,\min} \ \dots \ b_{U,\min}]^* = \mathbf{b}_{\min}^* \succeq \mathbf{0}$$

$$\mathcal{E} \succeq \mathbf{0} \ .$$

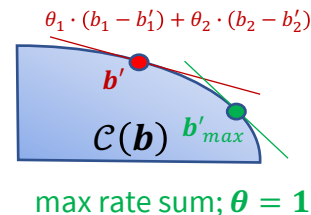


- Maximize weighted rate sum b , given \mathcal{E}
 - No rate limit
 - rate weights θ given, non-negative

$$\max_{\{R\mathbf{x}\mathbf{x}(u)\}} \sum_{u=1}^U \theta_u \cdot b_u$$

$$ST: \quad \mathcal{E} \preceq [\mathcal{E}_{1,\max} \ \mathcal{E}_{2,\max} \ \dots \ \mathcal{E}_{U,\max}]^* = \mathcal{E}_{\max}^* \succeq \mathbf{0}$$

$$\mathbf{b} \succeq \mathbf{0} \ .$$



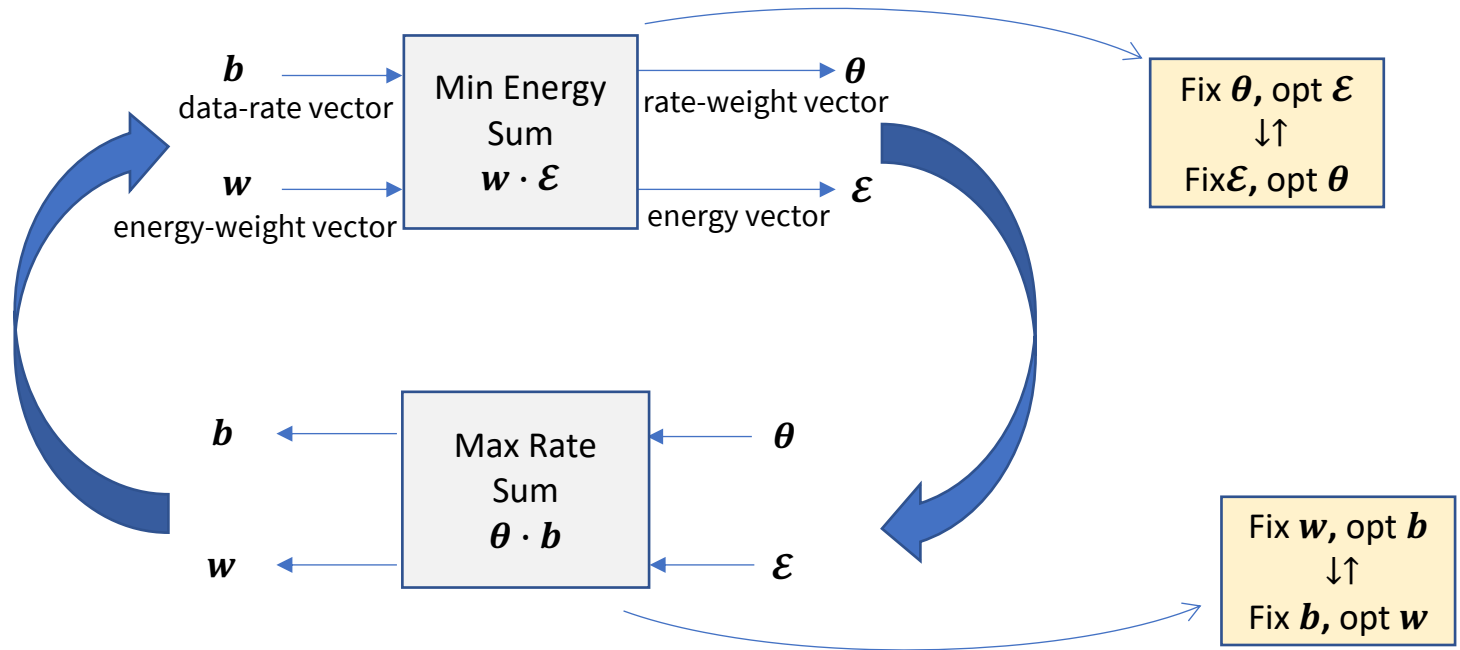
- These are “dual” problems

$$L_{\min E}(R\mathbf{x}\mathbf{x}, \mathbf{b}, \mathbf{w}, \boldsymbol{\theta}) = \max_{\boldsymbol{\theta}} \min_{R\mathbf{x}\mathbf{x}} \underbrace{\sum_{u=1}^U [w_u \cdot \text{trace}\{R\mathbf{x}\mathbf{x}(u)\} + \theta_u \cdot b_u]}_{\text{common term}} - \theta_u \cdot b_{\min,u}$$

$$L_{\max R}(R\mathbf{x}\mathbf{x}, \mathbf{b}, \mathbf{w}, \boldsymbol{\theta}) = \min_{\mathbf{w}} \max_{R\mathbf{x}\mathbf{x}} \underbrace{\sum_{u=1}^U [w_u \cdot \text{trace}\{R\mathbf{x}\mathbf{x}(u)\} + \theta_u \cdot b_u]}_{\text{common term}} - w_u \cdot \mathcal{E}_{\max,u}$$



Basic Solution Cycles



- Each of these “boxes” (subnetworks) can be intense calculation, but (\sim , see L14: 31) convex and convergent
- The overall recursive cycling also converges if $\mathbf{b} \in \mathcal{C}(\mathbf{b})$

Potential Project - approximate this with ML/AI method?



Tonal Lagrangian

- Minimize (over $R_{\mathbf{X}\mathbf{X}}(u)$) weighted sum at any given (think temporary) $\boldsymbol{\theta}$ where \mathbf{b} and \mathbf{w} are the specified values

$$L(R_{\mathbf{X}\mathbf{X}}, \mathbf{b}, \mathbf{w}, \boldsymbol{\theta}) = \sum_{n=0}^{\bar{N}-1} \left\{ \underbrace{\sum_{u=1}^U \left[w_u \cdot \text{trace} \{ R_{\mathbf{X}\mathbf{X}}(u, n) \} - \sum_{u=1}^U \theta_u \cdot b_{u,n} \right]}_{L_n(R_{\mathbf{X}\mathbf{X}}(n), \mathbf{b}_n, \mathbf{w}, \boldsymbol{\theta})} \right\} + \theta_u \cdot b_u$$

With fixed $\boldsymbol{\theta} \geq \mathbf{0}$
each tone can
be individually
minimized

- Which produces then for tone n

$$L_{min}(\boldsymbol{\theta}, n) \triangleq \min_{\{R_{\mathbf{X}\mathbf{X}}(u, n)\}, b_{u,n}} L_n(R_{\mathbf{X}\mathbf{X}}(n), \mathbf{b}_n, \mathbf{w}, \boldsymbol{\theta})$$

- Then max over $\boldsymbol{\theta}$

$$L^* = \max_{\boldsymbol{\theta}} \sum_{n=0}^{\bar{N}-1} L_{min}(\boldsymbol{\theta}, n) \triangleq \max_{\boldsymbol{\theta}} L_{min}(\boldsymbol{\theta})$$

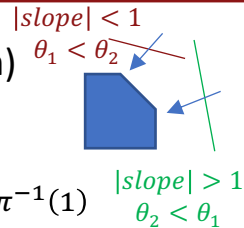
- and satisfy tonal GDFE (achievable region) constraint

$$\mathbf{b}_n \in \left\{ \mathbf{b}_n \mid 0 \leq \sum_{\mathbf{u} \subseteq U} b_{\mathbf{u},n} \leq \log_2 \left| \left(\sum_{u=1}^U \tilde{H}_{u,n} \cdot R_{\mathbf{X}\mathbf{X}}(u, n) \cdot \tilde{H}_{u,n}^* \right) + I \right| \right\} = \mathcal{A}_n(\{R_{\mathbf{X}\mathbf{X}}(n)\}, \bar{H}_n)$$



The tonal achievable-region constraint

- Maximum $\sum_{u=1}^U \theta_u \cdot b_{u,n}$ occurs at $\mathcal{A}_n(R_{XX}(u, n), \mathbf{b}_n)$ vertex (think slope -1 line and pentagon)
 - Given $R_{XX}(u, n) \rightarrow R_{XX}(u)$; equivalently max $\sum_{u=1}^U \theta_u \cdot b_u$ occurs at $\mathcal{A}(R_{XX}(u), \mathbf{b})$ vertex
- That max-weighted-sum vertex has specific θ_u , that must satisfy $\theta_{\pi^{-1}(U)} \geq \theta_{\pi^{-1}(U-1)} \geq \dots \geq \theta_{\pi^{-1}(1)}$
 - Proof see Theorem 5.4.1, and also discussion in Sec 5.4.4.1. (Same order all tones)
 - Don't need to test all orders – optimum order is inferred from the (converged) real vector θ !!**
- The user data rates in $\mathcal{A}_n(R_{XX}(u, n), \mathbf{b}_n)$ must satisfy the (sum of) **tonal-GDFE constraint(s)**:



$$b_{u,n} = \log_2 \left\{ \frac{|R_{yy}(u, n)|}{|R_{yy}(u-1, n)|} \right\} = \log_2 \left| \sum_{i=1}^u \tilde{H}_{\pi^{-1}(i),n} \cdot R_{\mathbf{X}\mathbf{X}}(\pi^{-1}(i), n) \cdot \tilde{H}_{\pi^{-1}(i),n}^* + I \right| - \log_2 \left| \sum_{i=1}^{u-1} \tilde{H}_{\pi^{-1}(i),n} \cdot R_{\mathbf{X}\mathbf{X}}(\pi^{-1}(i), n) \cdot \tilde{H}_{\pi^{-1}(i),n}^* + I \right|$$

- For given θ , min weighted rate sum over $R_{XX}(u, n)$ minimizes convex sum

$$\sum_{u=1}^U \theta_u \cdot b_{u,n} = \sum_{u=1}^U \left\{ \underbrace{[\theta_{\pi^{-1}(u)} - \theta_{\pi^{-1}(u+1)}]}_{\delta_{\pi^{-1}(u)} \leq 0} \cdot \log_2 \left| \sum_{i=u}^U \tilde{H}_{\pi^{-1}(i),n} \cdot R_{\mathbf{X}\mathbf{X}}(\pi^{-1}(i), n) \cdot \tilde{H}_{\pi^{-1}(i),n}^* + I \right| \right\}$$



Equal Theta

- Successive equal theta values
 - This can happen often
 - Usually happens when there are secondary user components
- The corresponding rate-sum difference term(s) is (are) zero
- Only the sum rate of the corresponding users can be varied $b_{\pi^{-1}(u)} + b_{\pi^{-1}(u)+1}$ is optimized
- The corresponding vertices for swapping the order (more generally varying when 3 or more) need to be “vertex-shared” in a proportion that causes the desired data rate to be achieved.
- Complicated program in matlab to do this, although concept is straightforward

Coming Attraction: The Stanford minPMAC program(s)





End Lecture 14

Two iterated steps

- $R_{XX}(u, n)$ step: With the given (current) $\theta, \mathbf{w}, \{b_{u,n}\}$, minimize the (neg) weighted rate sum over $R_{XX}(u, n)$
 - Each tone separately and sum

$$L_{min}(\theta, n) = \underbrace{\sum_{u=1}^U \left[w_u \cdot \text{trace} \{ R_{XX}(u, n) \} - \sum_{u=1}^U \theta_u \cdot b_{u,n} \right]}_{L_n(R_{XX}(n), \mathbf{b}_n, \mathbf{w}, \theta)}$$

e.g. $L_{k+1} = L_k - \mu \cdot (\nabla^2 L_k)^{-1} \cdot \nabla L_k$ Weighted steepest descent (“Newton”)

- Order step: With the given (current) $R_{XX}(u, n), \mathbf{w}, \{b_{u,n}\}$, maximize the Lagrangian over θ

$$L(\theta) = \sum_{n=1}^{\bar{N}} L_{min}(\theta, n)$$

Initialize (first time only) with FM SWF for given \mathbf{b}
This is the “find the vertex set” – elliptic algorithm, see text

