



Lecture 5

Spatial Modulation & Discrete Loading

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Announcements & Agenda

■ Announcements

- Problem Set #1 Solutions posted – see [PS1](#) (also link at course page and connects to canvas where actual solution is stored)
- Problem Set #2 Wed April 19 at 17:00
- Sections **1.6**, 4.4
- Problem Set #3 due April 26 at 17:00

■ Agenda

- Spatial Modulation
- Spatial Loading
- Discrete Loading

■ Problem Set 3 = PS3, due 4/26

1. 4.13 Coded-OFDM loading
2. 4.14 ergodic waterfill
3. 4.22 wireless spatial loading
4. 4.16 estimating gain distribution
5. 4.15 Wi-Fi Loading

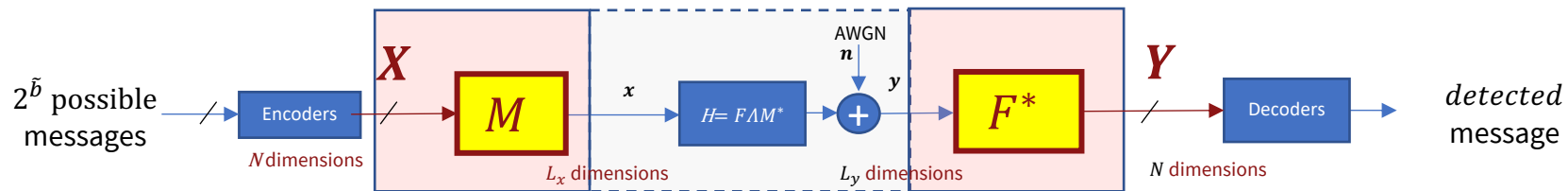


Spatial Modulation

“Space-Time Block Codes (STBC)”

Spatial Vector Coding is Optimal

- The symbols have crosstalk or inter-spatial-dimension interference.
- However, symbols otherwise have no intersymbol interference, $\nu = 0$ (or ISI is separately handled).
 - With Vector DMT/OFDM on all crosstalking channels, there is no ISI.
- Spatial Vector-Code channel partitioning remains for each tone n (index not shown).



- Parallel spatial channels index as:
 - $l = 1, \dots, L \leq \wp_H \leq \min(L_x, L_y)$.

$$y_l = \lambda_l \cdot x_l + n_l$$

$$SNR_l = \frac{\lambda_l^2 \cdot \bar{\epsilon}_l}{\sigma^2}$$

$$\mathbb{E}[\mathbf{n} \cdot \mathbf{n}^*] = R_{nn} = R_{nn}^{1/2} \cdot R_{nn}^{*/2}$$

Noise-Equivalent Channel

$$\mathbf{y} \leftarrow R_{nn}^{-1/2} \mathbf{y} = \left(R_{nn}^{-1/2} \cdot H \right) \cdot \mathbf{x} + \tilde{\mathbf{n}}$$

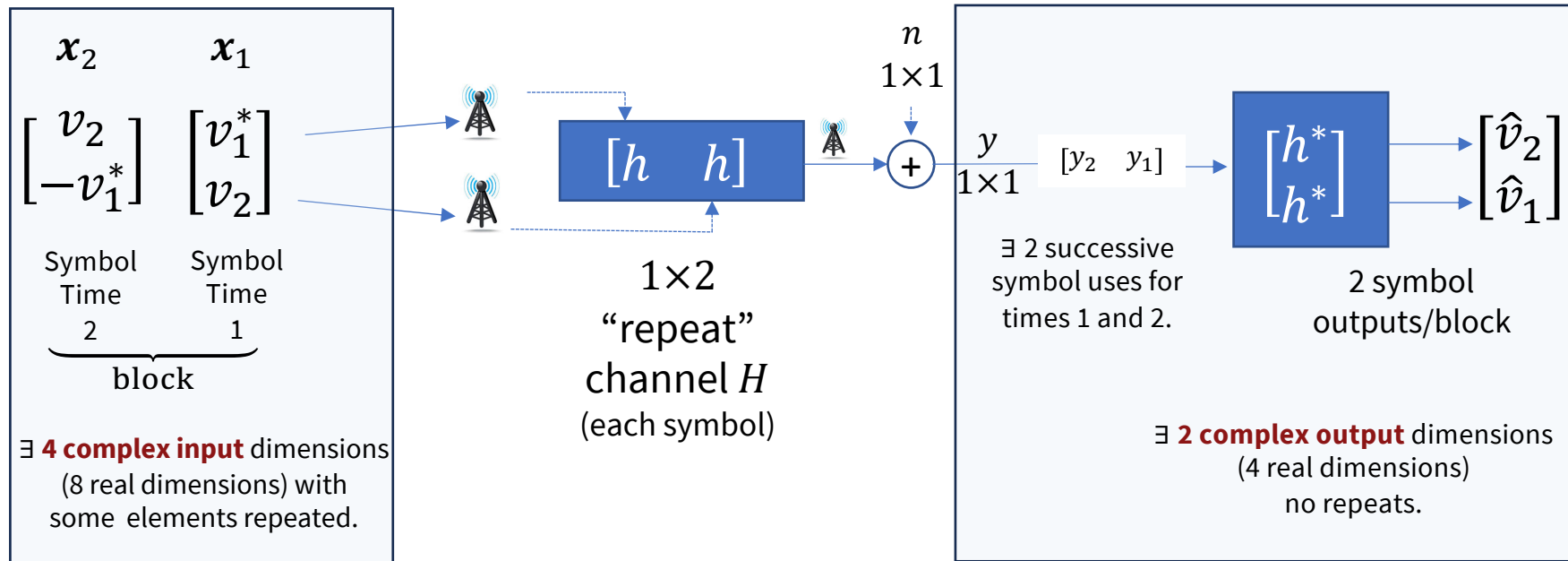


Spatial Modulator (Matrix)

- Best matrix modulator is M for any energy distribution.
- For this choice of M , it follows easily that the unbiased MMSE receiver matrix is F^* .
- In practice, it may be difficult for the transmitter to know M , since only the receiver can measure it.
 - This requires a reverse control channel.
 - The channel may change by the time it is reversed communicated.
- This leads to a variety of spatial approximations, among them Space-Time Block Codes (STBC).



Alamouti's Code (1998)



- **The trivial 1×2 "repeat" channel is the ONLY channel** for which Alamouti's code is Vector Coding.
 - It obviously does better by 3 dB than a single channel use $2 \cdot [h]^2$ instead of $[h]^2$
- Basically, two line-of-sight paths to the same single-antenna receiver that must have the same gain.



Alamouti with more general 2x2 H ??

- Symmetric matrices: $J_2 \triangleq \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$ $J_1 \triangleq \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$ $R \triangleq \begin{bmatrix} a & c \\ c & b \end{bmatrix}$

- Identity: $J_2 \cdot R \cdot J_2 + J_1 \cdot R \cdot J_1 = \begin{bmatrix} a + b & 0 \\ 0 & a + b \end{bmatrix}$

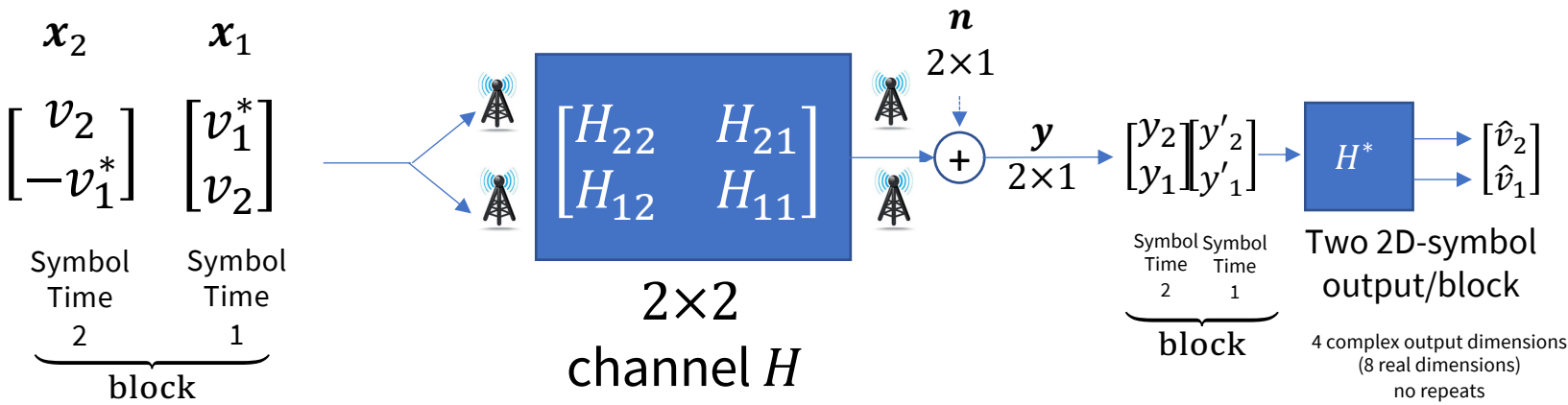
- Alamouti modulator: $\underbrace{\mathbf{x}}_{4 \times 1} = \underbrace{\begin{bmatrix} J_2 \\ J_1 \end{bmatrix}}_{4 \times 2} \cdot \underbrace{\begin{bmatrix} v_2 \\ v_1 \end{bmatrix}}_{\mathbf{v}, 2 \times 1}$ $\underbrace{\mathbf{y}}_{4 \times 1} = \underbrace{\begin{bmatrix} H & 0 \\ 0 & H \end{bmatrix}}_{\mathbf{H}, 4 \times 4} \cdot \mathbf{x} + \mathbf{n} = \begin{bmatrix} H \cdot J_2 \\ H \cdot J_1 \end{bmatrix} \cdot \mathbf{v} + \mathbf{n}$

- Forward channel autocorrelation is the block diagonal $\mathbf{R}_f = \mathbf{H}^* \cdot \mathbf{H} = \begin{bmatrix} R_f & 0 \\ 0 & R_f \end{bmatrix}$.

- Each 2x2 sub-block diagonal is $R_f = J_2^* \cdot H^* \cdot H \cdot J_2 + J_1 \cdot H^* \cdot H \cdot J_1$
 $= \begin{bmatrix} H_{22}^2 + H_{21}^2 + H_{12}^2 + H_{11}^2 & 0 \\ 0 & H_{22}^2 + H_{21}^2 + H_{12}^2 + H_{11}^2 \end{bmatrix}$



SUBOPTIMAL Alamouti's Code Use, 2 x 2 channel



4 complex input dimensions (8 real dimensions)
 some symbol values repeated

$$\begin{aligned}
 R_f &= J_2^* \cdot H^* \cdot H \cdot J_2 + J_1 \cdot H^* \cdot H \cdot J_1 \\
 &= \begin{bmatrix} H_{22}^2 + H_{21}^2 + H_{12}^2 + H_{11}^2 & 0 \\ 0 & H_{22}^2 + H_{21}^2 + H_{12}^2 + H_{11}^2 \end{bmatrix}
 \end{aligned}
 \qquad \gamma_{repeat} = \frac{1}{2}$$

- The transmitter remains channel independent, and the receiver remains simple matched matrix.
- The SNR is higher, BUT the data rate is halved. **Vector coding is better** ($\gamma_{repeat} = 1$).



STBC Codebooks

- Variety of different sizes, but rate loss $\gamma_{repeat} \geq \frac{1}{2}$ (with more than one receive antenna).
- They perform a lot worse than vector-coding in practice.

Example: $\bar{\mathcal{E}}_x = 1$; $\sigma^2 = 1$

```
>> H
H =
    1.0000    0.9000
    0.8000    1.0000
>> [F,L,M]=svd(H)
F =
   -0.7245   -0.6892
   -0.6892    0.7245
L =
    1.8512     0
     0    0.1512
M =
   -0.6892   -0.7245
   -0.7245    0.6892
bvc=log2(det(L^2+eye(2))) = 2.1790
bstbc=log2(sqrt(norm(H,'fro')^2+1)) = 1.0769
10*log10((2^bvc-1)/(2^bstbc - 1)) = 5.0245 dB!
```

Sqrt same as $\frac{1}{2}$ in front,
must include the repeat
Factor on the two inputs.

**At higher data rates, the VC
advantage grows;**

Wireless Raleigh fading

$$\langle P_e \rangle \propto (SNR)^{d_{free}}$$

but still large VC advantage.



Wireless field use has STBC as “option”

- STBC will essentially repeat symbols, so if the channel is very poor and the codes (nonideal) are fixed, then it can increase SNR and create a reliable link at significant data-rate loss.
- This may be acceptable if no connection is otherwise reliably possible.
- For ideal outer codes ($\Gamma = 0$ dB), there is no such repeat-energy advantage theoretically.
- Most wireless systems (Cellular and Wi-Fi) allow use of STBC as an option, but also permit use of vector-coding approximations to avoid the STBC losses.

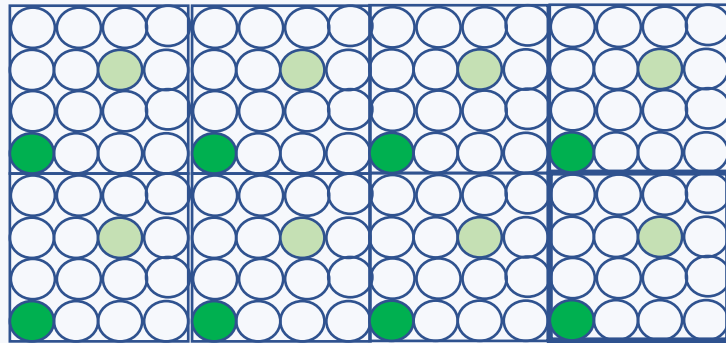


Spatial Loading

precoder-matrix and rank indications

Cellular: Type 1 (Linear) Precoders

$L_{x,2} \cdot O_2$ choices



$L_{x,1} \cdot O_1$ choices

O_i is oversampling factor (angle)

$L_x = L_{x,1} \cdot L_{x,2} = \text{number used antennas}$

Each $O_1 \times O_2$ rectangle is a “subarray” of choices.

$$O = O_1 \cdot O_2$$

- $Q_{L_{x,1} \cdot O_1}$ is a DFT matrix of size $L_{x,1} \cdot O_1$; $Q_{L_{x,2} \cdot O_2}$ is a DFT matrix of size $L_{x,2} \cdot O_2$.
 - These 2 DFT matrices' columns are then decimated by O_1 and O_2 respectively to generate respectively $L_{x,1} \times 1$ and $L_{x,2} \times 1$ column vectors
 - $\mathbf{q}_{L_{x,1} \cdot O_1}(l_1)$ for $l_1 \in [0: L_{x,1}]$, and
 - $\mathbf{q}_{L_{x,2} \cdot O_2}(l_2)$ for $l_2 \in [0: L_{x,2}]$.
- Cartesian (Kronecker) products create $L_x \times 1$ vectors $\mathbf{a}(l_1, l_2) = \mathbf{q}_{L_{x,1} \cdot O_1}(l_1) \otimes \mathbf{q}_{L_{x,2} \cdot O_2}(l_2)$, They reindex to $l = 1: (L_x \cdot O)$ such vectors.
- For the precoder matrix A , the rcvr specifies the
 - **Rank Index (RI)** $\leq L_x$, $L_x \times 1$ columns of these $\mathbf{a}(l_1, l_2)$
 - **Precoder Matrix Indicator (PMI)** \sim set of RI $(l_{1,l}, l_{2,l})$ and a phase $\phi_{l_{1,l}, l_{2,l}} \in \{1, j, -1, -j\}$ for each (chooses these as closest to M from SVD of H)
 - **Channel Quality Index (CQI)** $\sim [r, |C|]$



Cellular: Type 2 Precoders

- Type 2 uses reindexed Type 1 columns $\mathbf{a}_l = \mathbf{a}(l_{1,l}, l_{2,l})$ into a weighted sum.
- Weights $a_{l,ss}$ can have amplitudes $2^{-i/2}$ for $i \in \{0, \dots, 6\}$ and phases $\frac{2\pi m}{M}$ $m \in \{0, \dots, M - 1\}$.
- Receiver selects $L > RI$ beam vectors \mathbf{a}_l , from which RI new $L_x \times 1$ “beams” form as, per spatial stream (ss):

$$\mathbf{a}'_{ss} = \sum_{l=1}^{L > RI} a_{l,ss} \cdot \underbrace{\mathbf{a}(l_{1,l}, l_{2,l})}_{\mathbf{a}_l} \quad ss \in [1:RI]$$

$$a_{l,ss} = 2^{-i/2} \cdot e^{j\frac{2\pi m}{M}}$$

$$i \in [0:6], m \in [0:M-1]$$

- PMI includes beam indices $(l_{1,l}, l_{2,l})$ for $l \in [1:L]$ and the $(i_{l,ss}, m_{l,ss})$ for $l \in [1:L]$ & $ss \in [1:RI]$
 - Type 1 $\phi_{l_{1,l}, l_{2,l}}$ is subsumed in the Type 2 additional quantities, so does not need separate specification.

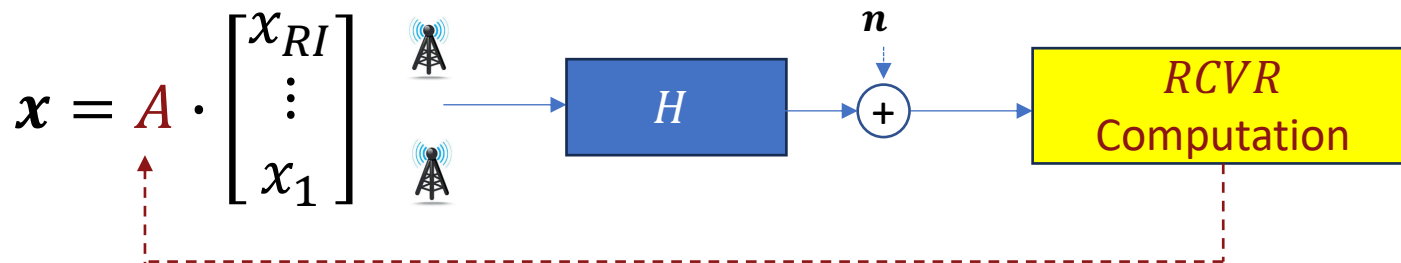
$$A = [\mathbf{w}_1 \cdots \mathbf{w}_{RI}] = A' \cdot C \quad A' = [\mathbf{a}'_{RI} \cdots \mathbf{a}'_1] \quad C = [a_{l,ss}]_{\substack{ss=RI:-1:1 \\ l=L:-1:1}}$$

$$L_x \times RI \quad L_x \times L \quad L \times RI$$

$$\text{rank}(A) \leq RI \leq L \leq L_x$$



Spatial Loading chooses the "A"



- The $\mathcal{I} = \sum_{n=0}^{N_{sc}-1} \log_2 |I + H_n \cdot A \cdot S_x \cdot A^* \cdot H_n^*|$ can be maximized over the choices for A .
 - The A and S_x do not vary with n , apart from the RI used spatial dimensions (in cellular).
 - Of course water-filling solves this in general when they can vary.
 - Indeed, the S_x is a constant diagonal and A a constant $L_x \times RI$ matrix independent of tone index n .
-
- One approach is to try all the possible \mathbf{a}_l, i, m, A possibilities and pick the largest one.
 - This has enormous complexity for reasonable $L_{x,1}$ and $L_{x,2}$.
- Spatial loading addresses this selection more efficiently.



A Spatial Loading Strategy

- **Step 1:** find RI and A : Form $R_{f,ave} = \frac{1}{N_{sc}} \cdot \sum_{n=0}^{N_{sc}-1} H_n^* \cdot H_n$, which will be square and of size $L_x \times L_x$.
 - Find the eigenvalue decomposition $R_{f,ave} = \sum_{l=1}^{L_x} \lambda_l \cdot \mathbf{v}_l \cdot \mathbf{v}_l^*$.
 - Compute waterfill for subchannels with gains λ_l and the total energy budget \mathcal{E}_x .
 - Set L to be waterfill's L^* , presume any sorting and unsorting of the gains and indices
 - Dominant subspace is $A_{wf} = [\mathbf{v}_1 \cdots \mathbf{v}_{L^*}]$ and $R_f = \sum_{l=1}^{L^*} \lambda_l \cdot \mathbf{v}_l \cdot \mathbf{v}_l^*$. (and $RI = L^*$)
- **Step 2:** Compute $L_x \cdot O$ candidates' scores $\gamma_k = \mathbf{a}_k^* \cdot R_f \cdot \mathbf{a}_k$ and keep the K top survivors from the $\{\mathbf{a}_k\}$.
 - $K > L^*$ but somewhat discretionary as to what the γ_k threshold is (looking for significant drop beyond).
 - Complexity reduced from $\binom{L_x \cdot O}{L^*}$ to $\binom{K}{L^*}$
- **Step 3:** Form $T = \binom{K}{L^*}$ candidate subsets, where each subset t selects L^* beams from K possible survivors \mathbf{a}_k :

$$\mathbf{a}'_{ss,t} = \sum_{l=1}^{L^*} a_{l,ss} \cdot \mathbf{a}_{l,t} \quad t \in [1:T] \quad A_t = [\mathbf{a}_{L^*,t} \cdots \mathbf{a}_{1,t}]$$

$$a_{l,ss} = 2^{-i/2} \cdot e^{j \frac{2\pi m}{M}}$$

$$i \in [0:6], m \in [0:M-1]$$

- **Step 4:** Final A is found as

$$A = \arg \max_t \text{tr}\{A_t^* \cdot R_f \cdot A_t\} \text{ or to maximize directly}$$

$$\mathcal{I} \cong \sum_{n=0}^{N_{sc}-1} \log_2 |I + H_n \cdot A_t \cdot S_x \cdot A_t^* \cdot H_n^*|$$



Wi-Fi Loading

- Fewer antennas and slower channels (less variation/Doppler)
- So Wi-Fi does the SVD per tone n (or per groups of tones like 4, 16, ..., with wider bands).
 - Sends back SVD's M or an eigenvector equivalent when groups of tones are used, and with either: $SNR_{geo,ss}$.
 - Or subset of M 's columns.
- The Wi-Fi is packet-based (CSMA) so trains/updates for each
 - Transmitter decides L^* (useful rank based on feedback) and the MCS $[r, |C|]$ per USER (so MCS common to all ss for single user)
 - Cellular is continuously on and changing more rapidly, and thus feedback would take too much bandwidth.
- The M is quantized by standardized series of “Complex Givens” rotations.
- But again, the water-fill energy is only approximated by silencing some weaker spatial streams.
- Cellular has Type 1 and Type 2, allowing for lots of antennas and oversampling in space.
 - This has dubious value in Wi-Fi as the AP could be placed anywhere.



Wi-Fi Steps (downlink)

- **Step 1:** Receiver identifies the channel H_n from training packets (see Chapter 9, L17).

$$H_n = F_n \cdot \Lambda_n \cdot M_n^* \quad M_n \text{ is the best linear precoder.}$$

For groups $R_{f,ave} = \frac{1}{N_{sc}} \cdot \sum_{n=0}^{N_{group}-1} H_n^* \cdot H_n = \sum_{l=1}^{L_x} \lambda_l \cdot \mathbf{v}_l \cdot \mathbf{v}_l^*$, and V_{group} is the selected linear precoder (pretend this is M_n for rest below)

- **Step 2:** Receiver does QR factorization of $M_n \Phi = Q_n \cdot R_n = Q_n$ for a unitary matrix.
 - The factorization process that leads to upper triangular $R_n = I$ matrix uses complex Givens Rotations
 - Starting column 1 bottom up, then column 1 up until only 1 (upper left) nonzero entry remains ($L_x - 1$) rotations.
 - Then columns 2 through $L_{max} \leq L_y$.
 - The **complex** rotations have **two** angles, each angle quantized.

$$Q_2(\phi, \varphi) = \begin{bmatrix} \cos(\varphi) & -e^{-j\phi} \cdot \sin(\varphi) \\ e^{-j\phi} \cdot \sin(\varphi) & \cos(\varphi) \end{bmatrix} \cdot \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} \sqrt{|x|^2 + |y|^2} \\ 0 \end{bmatrix}$$

High or Low SNR:

$$\phi = \angle x - \angle y \in [0: 2\pi] \quad (4-6 \text{ bits})$$

$$\varphi = \tan^{-1} \frac{|y|}{|x|} \in [0: \frac{\pi}{2}] \quad (2-4 \text{ bits})$$

For multiuser: (7-9 bits)
(5-7 bits)

- Return the angles for L_{max} columns (dominant subspace) to transmitter to implement as M_n .
- Transmitter (AP) may subsequently reduce L_{max} on later uses
 - (it pre-decides on each use – **don't like this, "standards mistake!"**)



Discrete Loading

Bit and Energy Distributions

- Bit distribution

$$\mathbf{b} = [b_1 \quad b_2 \quad \cdots \quad b_N]$$

- Energy distribution

$$\boldsymbol{\varepsilon} = [\varepsilon_1(b_1) \quad \varepsilon_2(b_2) \quad \cdots \quad \varepsilon_N(b_N)]$$

- Incremental energy

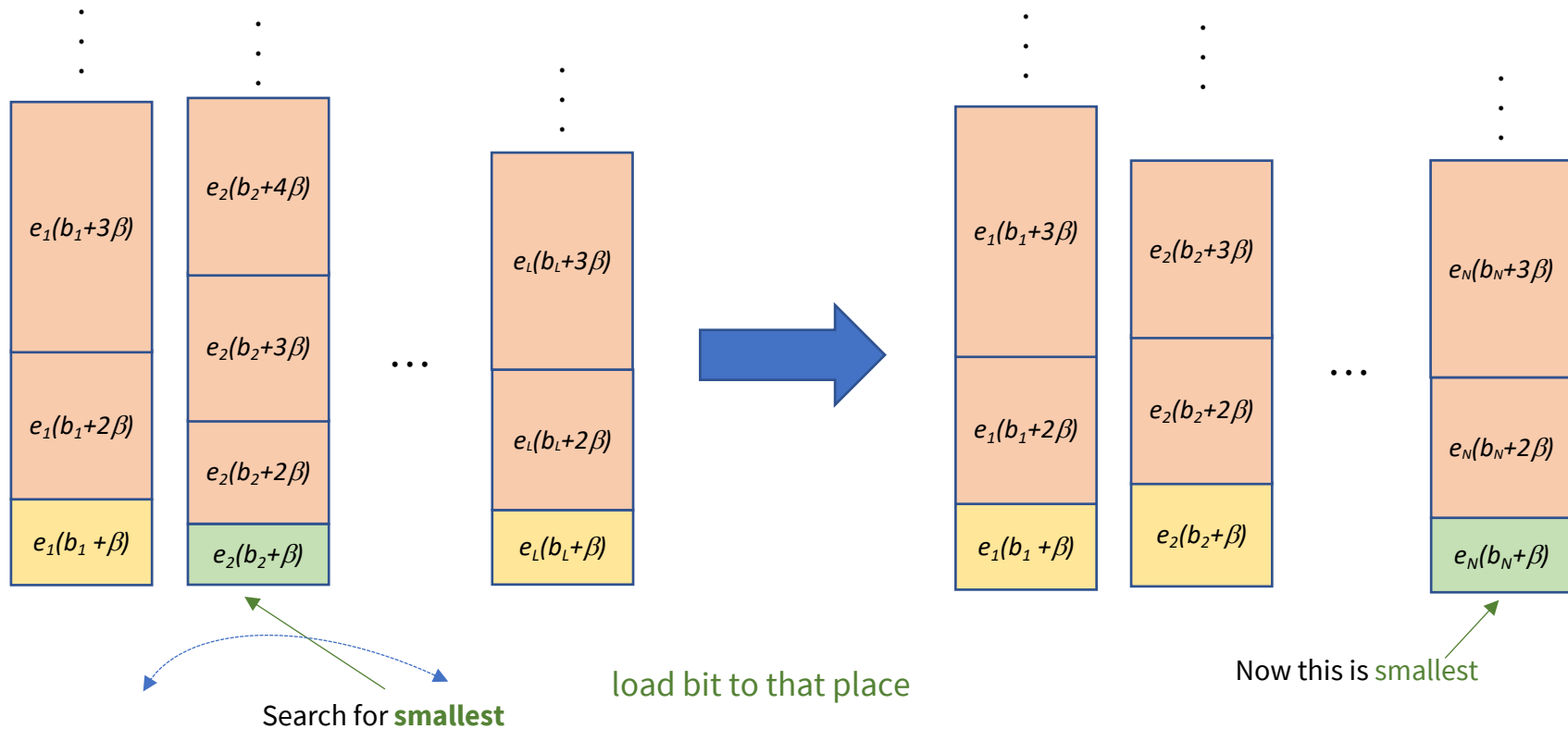
$$e_l(k \cdot \beta) \triangleq \varepsilon_l(k \cdot \beta) - (k \cdot \beta - \beta)$$

- β is smallest info unit (e.g., 1 bit)
- $\varepsilon_l(0) = 0, k = 1, \dots$



Incremental Energy Table (Greedy Algorithm)

- Create table of incremental energies for each dimension, some are better – some worse



- Repeat until RA (all energy used) or until MA (desired rate attained)



Some aspects of the incremental energy table

■ Dependencies

- Constellation, code/gap (can now be different on different dimensions if desired)
- Channel gain g_l
- Bit caps $b_l \leq b_{max}$ (any real system cannot carry infinite number of bits)
- Spectrum or antenna-energy masks

$$\mathcal{E}_n = \sum_{k=1}^{b_n} e_n(k \cdot \beta)$$

■ “easier” than water-filling for adding constraints

- Spectrum or antenna-energy masks
 - Set incremental energy to infinite (large) value if no more bits allowed
- Different dimensions can have different total energy constraints
 - (MIMO antennas)
- Bit caps $b_n \leq b_{max}$ (any real system cannot carry infinite number of bits)

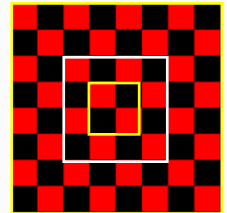


Example Common Table for SQ QAM

- Use Square QAM on all tones with $\beta=1$
 - Each tone's xmit distance d_n scales inversely by square root g_n to provide constant d^2 /noise at detector

Xmit Energy =

$$E_n(b_n) = \begin{cases} \frac{2^{b_n} - 1}{6} d_n^2 & b_n \text{ even} \\ \frac{2^{b_n+1} - 1}{12} d_n^2 & b_n \text{ odd} \end{cases}$$



- Incremental energy** can be computed generally as function of d_n also

$$e_n(b_n) = \begin{cases} 2^{b_n-1}/12 d_n^2 & b_n \text{ even} \\ 2^{b_n}/12 d_n^2 & b_n \text{ odd} \end{cases}$$

- Can tabulate for each tone/group after inverse-square-root-channel-gain scaling



Example continued

- Before Scaling:

b_n	0	1	2	3	4	5	6	7	8
$\mathcal{E}_n(b_n)$	0	$\frac{d_n^2}{4}$	$\frac{d_n^2}{2}$	$\frac{5d_n^2}{4}$	$\frac{5d_n^2}{2}$	$\frac{21d_n^2}{4}$	$\frac{21d_n^2}{2}$	$\frac{85d_n^2}{4}$	$\frac{85d_n^2}{2}$
$e_n(b_n)$	0	$\frac{d_n^2}{4}$	$\frac{d_n^2}{4}$	$\frac{3d_n^2}{4}$	$\frac{5d_n^2}{4}$	$\frac{11d_n^2}{4}$	$\frac{21d_n^2}{4}$	$\frac{43d_n^2}{4}$	$\frac{85d_n^2}{4}$

- The incremental energy is monotonic in this example. Why?
 - This is important for suggested algorithm to be optimum
 - Most rationally designed constellation approaches have this property
- The receiver stores only one column, but scales the next-out entry to be evaluated (the yellow/green ones earlier) by

$$\frac{1}{\sqrt{g_n}} \text{ or } \frac{1}{\sqrt{g_{geo,n}}}$$

Does this really work? Is it optimum? Yes & Yes!
 (when $e_n(b_n)$ function is monotonically non-decreasing with bits)

Works for $g_{geo,n}$ to find
 $[r, |C|]$ for different spatial
 dimension (or groups)



Efficiency Concept introduced by Campello

- Adding one more bit (unit of β) takes more energy than energy savings for deletion of any bit

- An **efficient** bit distribution
$$\max_n e_n(b_n) \leq \min_{m \neq n} e_m(b_m + \beta)$$

- If the bit distribution is efficient (and the incremental energy is monotonic):

- No other bit distribution (which would need to move bits) could use less energy \rightarrow optimum

- Rate Adaptive (RA) optimum solution if
$$\mathcal{E}_x = N \cdot \bar{\mathcal{E}}_x = \sum_{n=1}^N \mathcal{E}_n$$

- Margin Adaptive optimum solution if

$$b = N \cdot \bar{b} = \sum_{n=1}^N b_n$$



"Efficientize" a bit distribution (Campello)

EF Algorithm

① $m \leftarrow \arg \left\{ \min_{1 \leq i \leq N} [e_i(b_i + \beta)] \right\}$ position of least E among next
Incremental energy

② $n \leftarrow \arg \left\{ \max_{1 \leq j \leq N} [e_j(b_j)] \right\}$ position of most E among current
Incremental energy

③ while $e_m(b_m + \beta) < e_n(b_n)$
 swap "bit" from n to m
 $b_m \rightarrow b_m + \beta$
 $b_n \rightarrow b_n - \beta$
 update m, n from steps 1, 2

- Relies on monotonicity, but the algorithm will converge to an efficient bit distribution (always)



1+.9D⁻¹ Example Revisted for EF

- First Step? Compute the incremental energy table

$$\mathcal{E}_{PAM,n}(b_n) = \frac{10^{.88}}{g_n} (2^{2b_n} - 1) \quad n = 0, 4$$

$$\mathcal{E}_{QAM,n}(b_n) = 2 \cdot \frac{10^{.88}}{g_n} (2^{b_n} - 1) \quad n = 1, 2, 3$$

- $n=0$:

$$\left. \begin{aligned} \mathcal{E}_0 &= \frac{\pi}{g_0} (2^{2b_0} - 1) = \frac{10^{.88}}{20} (2^{2b_0} - 1) \\ e_0 &= \frac{10^{.88}}{20} (2^{2b_0} - 2^{2(b_0-1)}) \end{aligned} \right\} \text{PAM}$$

- $n=1,2,3$:

$$\left. \begin{aligned} \mathcal{E}_n &= 2 \frac{\pi}{g_n} (2^{b_n} - 1) = \frac{2(10^{.88})}{17,10, \text{ or } 3} (2^{b_n} - 1) \\ e_n &= \frac{2(10^{.88})}{17,10,3} (2^{b_n} - 2^{b_n-1}) \end{aligned} \right\} \text{QAM}$$

- $n=4$:

$$\left. \begin{aligned} \mathcal{E}_4 &= \frac{\pi}{g_4} (2^{b_4} - 1) \\ e_4 &= \frac{10^{.88}}{.055} (2^{b_4} - 2^{b_4-1}) \end{aligned} \right\} \text{SSB}$$

1 bit added is

1 bit/symbol (8 real dims)

or .125 bits per dimension

Whether added PAM or QAM

For QAM, 2 successive 3's are same



Incremental Energy Table for 1+.9D⁻¹ uncoded

- Table – note smallest energy on top here

n	0	1	2	3	4	
$\bar{e}_n(1)$	1.14	.891	1.50	5.112	412.3	note 6dB/bit in column 0 (4)
$\bar{e}_n(2)$	4.56	1.78	3.03	10.2	—	
$\bar{e}_n(3)$	18.3	3.56	6.07	20.4	—	3dB/bit in column 1-3
$\bar{e}_n(4)$	—	7.13	12.1	—	—	
$\bar{e}_n(5)$	—	14.2	24.3	—	—	

- Start with 8 bits allocated as [0 5 0 2 1]

- 5 iterations
- Energy =

$$.891+1.14+1.5+1.78+3.56+3.03+4.56+5.11=21.6 > 8!$$

1. $b = [0\ 5\ 0\ 2\ 1]$
2. $b = [1\ 5\ 0\ 2\ 0]$
3. $b = [1\ 4\ 1\ 2\ 0]$
4. $b = [1\ 4\ 2\ 1\ 0]$
5. $b = [2\ 3\ 2\ 1\ 0]$.

- Round MA Water-filling?
 $b_0 = 1.71 \rightarrow 2$
 $b_1 = 3.19 \rightarrow 3$
 $b_2 = 2.42 \rightarrow 2$
 $b_3 = .678 \rightarrow 1$

same
this time



Energy Tightness

- E-tight Definition for efficient distribution:

$$0 \leq N\bar{\mathcal{E}}_{\mathbf{x}} - \sum_{n=1}^N \mathcal{E}_n(b_n) \leq \min_{1 \leq i \leq N} [e_i(b_i + \beta)]$$

No more bits
can be added

- E-tight Algorithm:

WHILE $(N\bar{\mathcal{E}}_{\mathbf{x}} - S) < 0$ OR $N\bar{\mathcal{E}}_{\mathbf{x}} - S \geq \min_i e_i(b_i + \beta)$

IF $(N\bar{\mathcal{E}}_{\mathbf{x}} - S) < 0$

(a). $n \leftarrow \arg \left\{ \max_i e_i(b_i) \right\}$ index of costly

(b). $S \leftarrow S - e_n(b_n)$

(c). $b_n \leftarrow b_n - \beta$ } Delete "bit"

ELSE

(a). $m \leftarrow \arg \left\{ \min_i e_i(b_i + \beta) \right\}$ index of cheapest

(b). $S \leftarrow S + e_m(b_m + \beta)$

(c). $b_m \leftarrow b_m + \beta$ } Add "bit"



E-Tighten earlier RA Example

- Reduce most costly bits first until energy < 8

$\underline{b} = [2 \ 3 \ 2 \ 1 \ 0]$	21.6
$[2 \ 3 \ 2 \ 0 \ 0]$	16.5
$[1 \ 3 \ 2 \ 0 \ 0]$	11.9
$[1 \ 2 \ 2 \ 0 \ 0]$	8.3
$[1 \ 2 \ 1 \ 0 \ 0]$	5.3

$$\gamma = \frac{8}{5.3} = 1.8 \text{ dB} \quad \bar{b} = \frac{1}{2} \quad b = 4$$

note transmission has $P_e < 10^{-6}$ at $b=4$

- Note how such a system allows bits/dimension granularity of 1/8 bit dimension
- The symbol blocking (of 8 dimensions together) indirectly allows fractional bits



- Matlab software at the web site

```
function [gn,En,bn,b_bar]=LC(P,SNRmfb,Ex_bar,Ntot,gap)

% Levin Campello's Method
%
% P is the pulse response
% SNRmfb is the SNRmfb in dB
% Ex_bar is the normalized energy
% Ntot is the total number of real subchannels, Ntot>2
% gap is the gap in dB
%
% gn is channel gain
% En is the energy in the nth subchannel (PAM or QAM)
% bn is the bit in the nth subchannel (PAM or QAM)
% Nstar is the number of subchannel used
% b_bar is the bit rate
%
% The first bin and the last bin is PAM, the rest of them are QAM.
```

```
>> [gn,En,bn,b_bar]=LC([.9 1],10,1,8,8.8)

gn =
    19.9448    17.0320    10.0000    2.9680    0.0552

En =
    1.1410    2.6723    1.5172         0         0

bn =
     1     2     1     0     0

b_bar =
    0.5000
```



Bit Tightness

- T-tight definition for efficient distribution:

$$b = \sum_{n=1}^N b_n$$

- BT Algorithm:

$\tilde{b} = \sum b_n$
while $\tilde{b} \neq b$
if $\tilde{b} > b$

$n \leftarrow \arg \max_i [e_i(b_i)]$
 $\tilde{b} \leftarrow \tilde{b} - \beta$
 $b_n \leftarrow b_n - \beta$ } "bit" delete

ELSE

$m \leftarrow \arg \min_i [e_i(b_i)]$
 $\tilde{b} \leftarrow \tilde{b} + \beta$
 $b_m \leftarrow b_m + \beta$

bit add



1+.9D⁻¹ again for BT

- Reverse the previous example to get back to 8 bits / symbol (with -4.3 dB margin)
- From zero-bit start (which is always efficient trivially)

- $b = [0\ 0\ 0\ 0\ 0]$
- $b = [0\ 1\ 0\ 0\ 0]$
- $b = [1\ 1\ 0\ 0\ 0]$
- $b = [1\ 1\ 1\ 0\ 0]$
- $b = [1\ 2\ 1\ 0\ 0]$
- $b = [1\ 2\ 2\ 0\ 0]$
- $b = [1\ 3\ 2\ 0\ 0]$
- $b = [2\ 3\ 2\ 0\ 0]$
- $b = [2\ 3\ 2\ 1\ 0]$

n	0	1	2	3	4	
$e_n(1)$	1.14	.891	1.50	5.112	412.3	note 6dB/bit in column 0 (4)
$e_n(2)$	4.56	1.78	3.03	10.2	—	
$e_n(3)$	18.3	3.56	6.07	20.4	—	
$e_n(4)$	—	7.13	12.1	—	—	3dB/bit in column 1-3
$e_n(5)$	—	14.2	24.3	—	—	



- Matlab software at the web site

```
function [gn,En,bn,b_bar_check,margin]=MALC(P,SNRmfb,Ex_bar,b_bar,Ntot,gap)

%
% Levin Campello's Method
%
% P is the pulse response
% SNRmfb is the SNRmfb in dB
% Ex_bar is the normalized energy
% Ntot is the total number of real/complex subchannels, Ntot>2
% gap is the gap in dB
% b_bar is the bit rate

% gn is channel gain
% En is the energy in the nth subchannel (PAM or QAM)
% bn is the bit in the nth subchannel (PAM or QAM)
% b_bar_check is the bit rate for checking - this should be equal to b_bar
% margin is the margin

% The first bin and the last bin is PAM, the rest of them are QAM.
```

```
>> [gn,En,bn,b_bar_check,margin]=MALC([.9 1],10,1,1,8,8.8)

gn =
    19.9448    17.0320    10.0000     2.9680     0.0552

En =
     5.7051     6.2354     4.5515     5.1117         0

bn =
     2     3     2     1     0

b_bar_check =
     1

margin =
    -4.3144
```



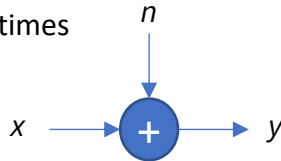
Finding an equivalent single AWGN

- Sum the bits – for total

$$\bar{b} = \frac{1}{2} \log_2 \left[\prod_{n=1}^N \left(1 + \frac{\text{SNR}_n}{\Gamma} \right) \right]^{1/N}$$
$$= 1 + \frac{\text{SNR}_{m,u}}{\Gamma}$$

- Geometric SNR** – for equivalent single channel

- Use this channel N times



Equivalent SNR_{geo}

$$\bar{b} = \frac{1}{2} \log_2 \left(1 + \frac{\text{SNR}_{m,u}}{\Gamma} \right)$$

$$\text{SNR}_{m,u} = \Gamma \cdot \left\{ \left[\prod_{n=1}^N \left(1 + \frac{\text{SNR}_n}{\Gamma} \right) \right]^{1/N} - 1 \right\}$$

When $\frac{\text{SNR}_n}{\Gamma} \gg 1$, then

$$\text{SNR}_{\text{geo}} = \sqrt[N]{\text{SNR}_1 \cdot \dots \cdot \text{SNR}_N}$$

- Allows comparison – an easier calculation than SNR_{geo} when loading is done?

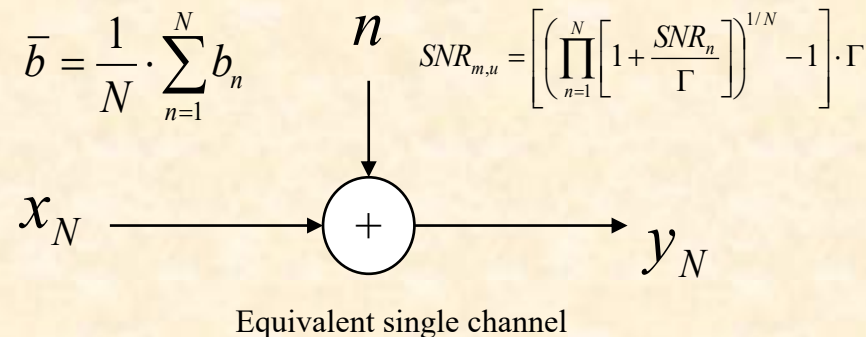
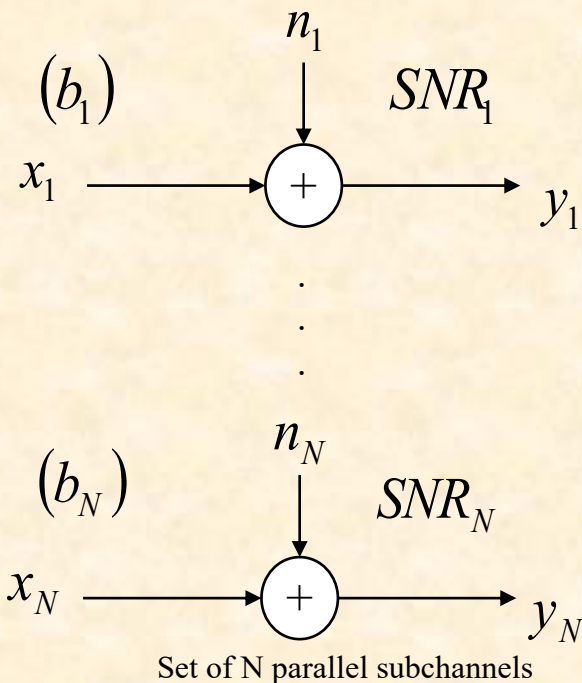
$$\text{SNR} = \Gamma \cdot (2^{2\bar{b}} - 1)$$

Just need total bits/N



Once Loading is Done: Important concept

- Set of dimensional channels can each be individually addressed (coded and designed)
 - But there is an equivalent single channel



With whatever bits and energy
on each subchannel





End Lecture 5