



STANFORD

*Lecture 2*

# **Channel Partitioning: Vector Coding & DMT**

*April 1, 2026*

**JOHN M. CIOFFI**

Hitachi Professor Emeritus (recalled) of Engineering

Instructor EE379B – Spring 2026

# Announcements & Agenda

- Announcements
  - Problem Set 1 due Wednesday, April 8 @ 18:00
  - Most relevant reading – Sections 2.5, 4.4-4.7
  - Syllabus fixed (mid 30, homework 30, final 40)
- Agenda
  - RA/MA water-fill flow charts (finish L1)
  - Vector Coding in Time-Frequency
    - $1+.9D^{-1}$  Vector-Code Example
  - DMT/OFDM partitioning
    - DMT Water-filling Software
    - Vector DMT/OFDM partitioning

**Question: Shannon conceived of water-filling, but who actually did it first? [link](#)**

**A. Collins: What else did he do and why important today?**

**See Appendix D.1/2 and S3 video supplementary lecture**

**BEFORE L3**

**Even if you've seen  
Least Squares or MMSE before!  
(yes, even if you thought you  
understood it in 379A).**



# RA Water-Fill Flow Chart

- RA WF may start with all channels energized:

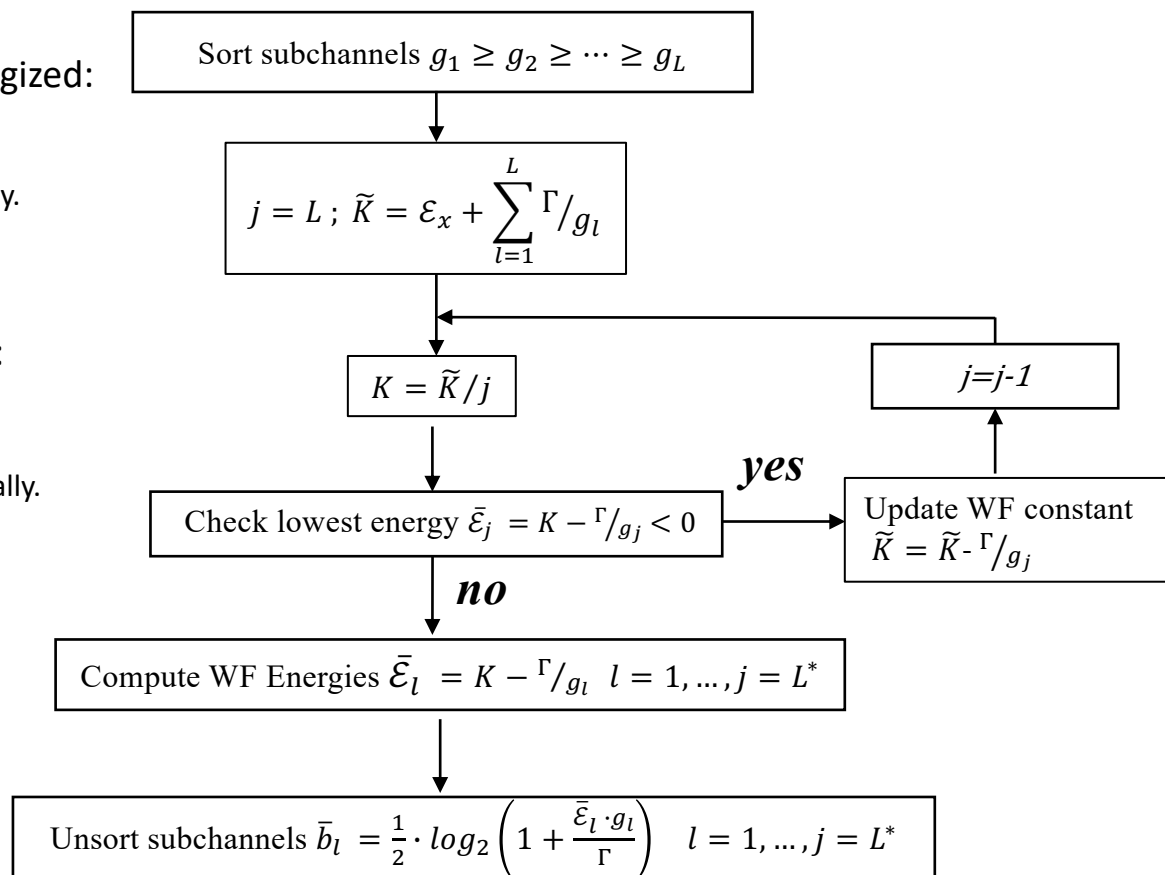
- computes  $K$ ,
- tests lowest energy, and
- reduces number of dimensions incrementally.

- RA WF may initially energize 1 channel:

- Computes  $K$ ,
- tests lowest energy, and
- Increases number of dimensions incrementally.

- The sort is most complex part.

- It can use pivots and bi-section,
- which reduces average run time.



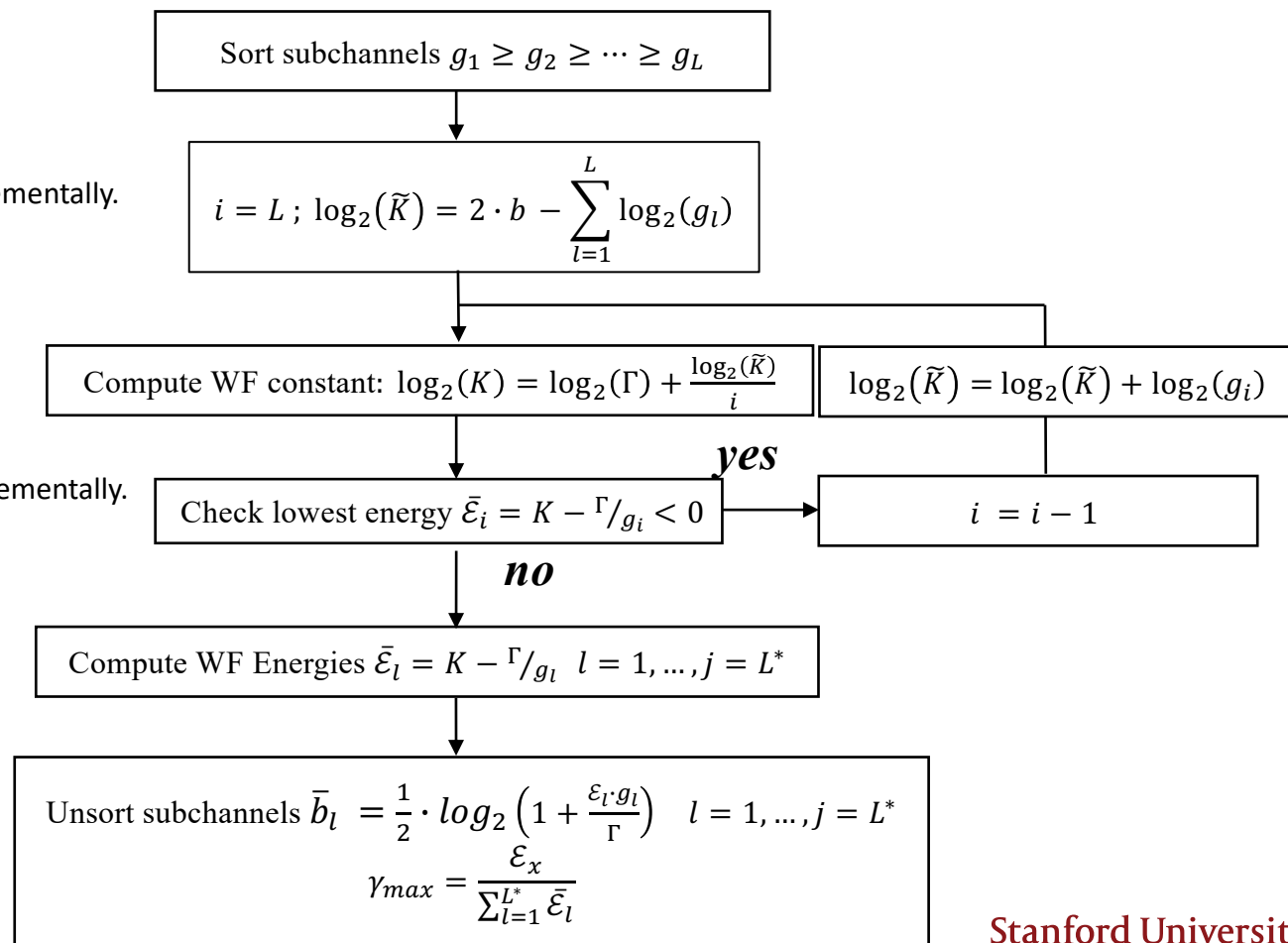
# Margin Adaptive Flowchart

- MA WF similarly:

- computes  $K$ ,
- tests lowest energy, and
- reduces number of dimensions incrementally.

- MA WF avoids large products

- Computes  $\log(K)$  instead of  $K$ ,
- tests lowest energy, and
- Increases number of dimensions incrementally.



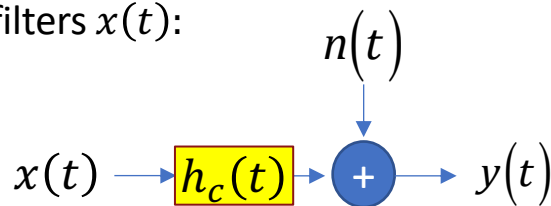
# Vector Coding in Time/Frequency

*Section 4.6.1*

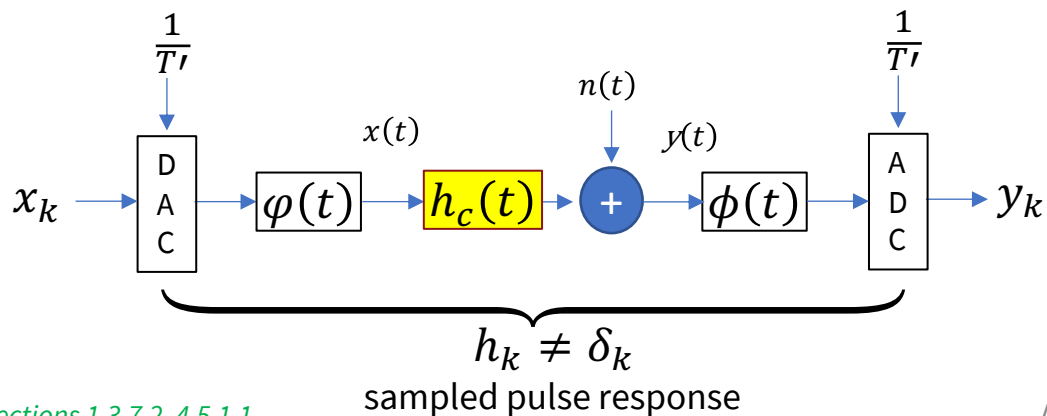
*See PS1.5 (Prob 4.25) (matrix AWGN and vector coding)*

# Scalar Time/Frequency (filtered) AWGN Channel

- Ideal AWGN channels just add noise, but if it also filters  $x(t)$ :
  - attenuation,
  - band-limits, &
  - spectrally shaped noise (See Sec 1.3.7).



- The  $h_c(t)$  causes interference between successive transmissions – complicates and changes performance;
  - see Chapter 3 in EE379A.
- Sampled equivalent has  $T' < T$  as the **sample period** – generalizes 379A’s “fractional spacing.”

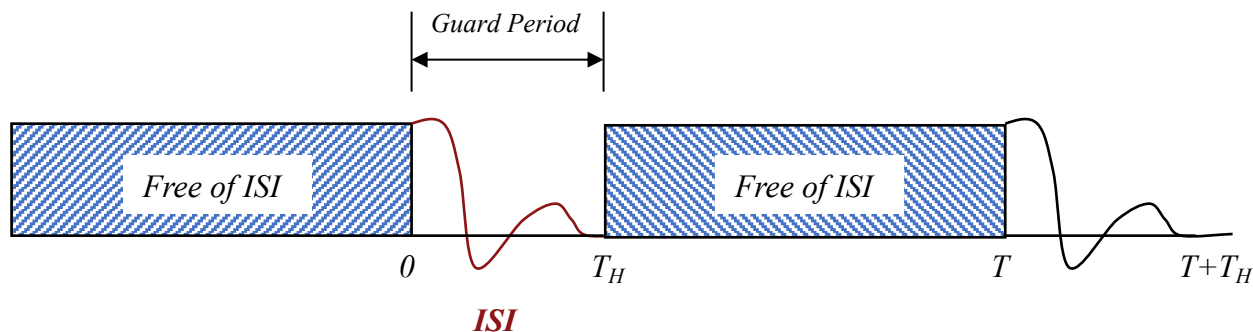


$$y_k = x_k * h_k + n_k$$



# Guard Periods for frequency-time

- The **guard period (GP)**  $T_H$ 
  - lets ISI abate before next symbol.

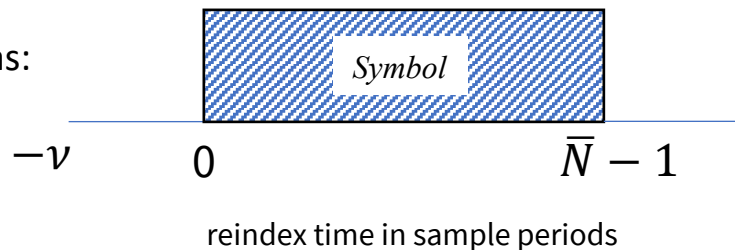


- This wastes  $T_H/T$  of resources (time dimensions):
  - If  $T \gg T_H$ , then the guard period may be worth it.
  - GP may be zeroed or anything the receiver ignores.

excess bandwidth

$$\alpha = \frac{T_H}{T - T_H}$$

- A (scalar / SISO) symbol with  $\bar{N}$  dimensions (samples) has:
  - $T_H = \nu \cdot T'$  so up to  $\nu+1$  non-zero samples/dimensions in  $h_k$ .
  - $\bar{N}$  works for real ( $\tilde{N} = 1$ ) or complex ( $\tilde{N} = 2$ ).



# SISO (time-dimension) Case

- Simple scalar convolutional matrix channel with guard band

$$\begin{bmatrix} y_{N-1} \\ y_{N-2} \\ \vdots \\ y_0 \\ \text{Ignore} \\ -1:-\nu \end{bmatrix} = \begin{bmatrix} h_0 & h_1 & \dots & h_\nu & 0 & \dots & 0 & 0 & 0 & 0 \\ 0 & h_0 & \ddots & h_{\nu-1} & h_\nu & \ddots & 0 & 0 & 0 & 0 \\ 0 & \ddots & \ddots & \ddots & \ddots & \ddots & 0 & 0 & 0 & 0 \\ \vdots & \ddots & \ddots & \ddots & \ddots & \ddots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \ddots & \ddots & \ddots & \ddots & \ddots & \vdots \\ 0 & \dots & 0 & 0 & 0 & 0 & h_0 & h_1 & \dots & h_\nu \end{bmatrix} \begin{bmatrix} x_{N-1} \\ \vdots \\ x_0 \\ x_{-1} \\ \vdots \\ x_{-\nu} \end{bmatrix} + \begin{bmatrix} n_{N-1} \\ n_{N-2} \\ \vdots \\ n_0 \end{bmatrix}$$

guard period could be anything, including 0 or cyclic.

$$\mathbf{y} = \mathbf{H} \mathbf{x} + \mathbf{n}$$

- Non-square shift “Toeplitz” matrix for convolution
  - More inputs than outputs when  $\nu \neq 0$



# SVD Again for the time-dimension case

- Singular Value Decomposition performs:

$$H = F \cdot \begin{bmatrix} \Lambda & \vdots \\ \underbrace{\quad}_{\bar{N} \times \bar{N}} & \underbrace{\mathbf{0}_{-1:-\nu}}_{\bar{N} \times \nu} \end{bmatrix} \cdot M^*$$

$$\begin{aligned} N &= \bar{N} \text{ if real subsymbols and } \tilde{N} = 1 \\ N &= 2 \cdot \bar{N} \text{ if complex subsymbols and } \tilde{N} = 2 \end{aligned}$$

$$\underbrace{FF^* = F^*F = I}_{\bar{N} \times \bar{N}}$$

$$\Lambda = \begin{bmatrix} \lambda_{\bar{N}-1} & 0 & \cdots & 0 \\ \vdots & \ddots & \ddots & \vdots \\ 0 & \cdots & \lambda_1 & 0 \\ 0 & \cdots & 0 & \lambda_0 \end{bmatrix}$$

$$\underbrace{MM^* = M^*M = I}_{(\bar{N}+\nu) \times (\bar{N}+\nu)}$$

unique (real) singular values  $\geq 0$

- The vector-coding input construction is:

$$\mathbf{x} = M \begin{bmatrix} \mathbf{X} \\ 0 \\ \vdots \\ 0 \end{bmatrix} = \underbrace{[\mathbf{m}_{\bar{N}-1} \ \mathbf{m}_{\bar{N}-2} \ \cdots \ \mathbf{m}_1 \ \mathbf{m}_0 \ \cdots \ \mathbf{m}_{-\nu}]}_{(\bar{N}+\nu) \times \bar{N}} \underbrace{\begin{bmatrix} X_{\bar{N}-1} \\ X_{\bar{N}-2} \\ \vdots \\ X_0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}}_{\text{zeroed}} = \sum_{n=0}^{\bar{N}-1} X_n \cdot \mathbf{m}_n$$

see svd 'econ'  
option (matlab)



# Vector-Coded Time Dimensions Only

- Channel output processed by matched vectors: 
$$\mathbf{Y} = \mathbf{F}^* \cdot \mathbf{y} = \begin{bmatrix} \mathbf{f}_{\bar{N}-1}^* \cdot \mathbf{y} \\ \vdots \\ \mathbf{f}_0^* \cdot \mathbf{y} \end{bmatrix}$$
- Vector-coded channel partitioning is :

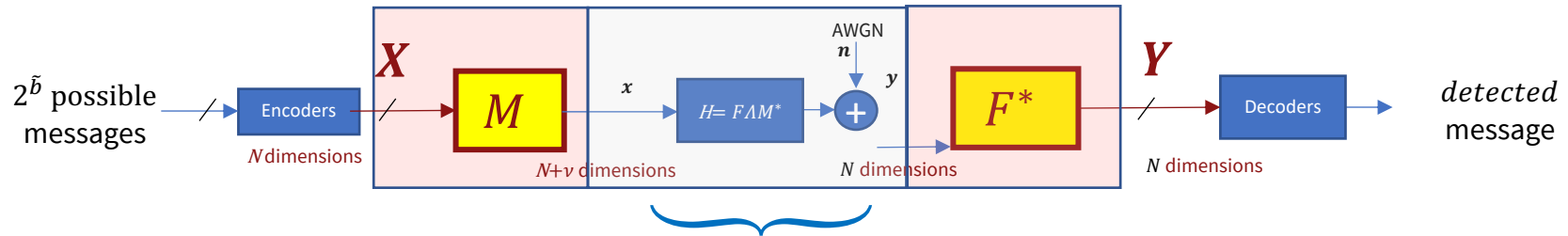
$\mathbb{E}[\mathbf{n} \cdot \mathbf{n}^*] = R_{nn} = R_{nn}^{1/2} \cdot R_{nn}^{*/2}$

Noise-Equivalent Channel

$\mathbf{y} \leftarrow R_{nn}^{-1/2} \mathbf{y} = (R_{nn}^{-1/2} \cdot H) \cdot \mathbf{x} + \tilde{\mathbf{n}}$

Replaces  $H$

Section 4.6.1.2



- Parallel Channels are then:

$$Y_n = \lambda_n \cdot X_n + N_n$$

$$SNR_n = \frac{\lambda_n^2 \cdot \bar{\epsilon}_n}{\sigma^2}$$



# Data Rates and Mutual Information

- For any energies and consequent SNR's
  - If **complex baseband**, replace  $\nu$  with  $2\nu$  for  $\bar{b}$  calculation.

$$\bar{b} = \frac{b}{N + \nu} = \frac{1}{2} \log_2 \left( 1 + \frac{SNR_{\nu C}}{\Gamma} \right)$$

- When the gap = 0 dB, this is the “mutual information”, reliable  $b \leq \mathcal{I}(\mathbf{x}; \mathbf{y})$ .
  - The **mutual information** bounds data rate, for (Gaussian) input with given autocorrelation  $R_{xx}$ , or any energy distribution (possibly not WF).
  - Good scalar-AWGN code applies “outside” the parallel channel set.

$$SNR_{\nu C} = 2^{2 \cdot \bar{\mathcal{I}}} - 1$$

- Maximized SNR, and thus mutual information, occur when energy is water-filling  $\rightarrow$  Capacity.

$$SNR_{\nu C, \text{water-fill}} = 2^{2 \cdot \bar{c}} - 1$$

- Highest reliable data rate that can be transmitted (Shannon 1948):
  - for the given block size  $\bar{N}$  and guard period  $\nu$ .



# $1+.9D^{-1}$ Vector-Code Example

*Section 4.6*

# Matlab 1+.9D<sup>-1</sup> example returns:

- Form  $H$  and do SVD:

```
>> C=[.9  
zeros(7,1)];  
>> R=[.9 1 zeros(1,7)];
```

```
>> H=toeplitz(C,R)
```

H =

```
0.9000 1.0000 0 0 0 0 0 0 0  
0 0.9000 1.0000 0 0 0 0 0 0  
0 0 0.9000 1.0000 0 0 0 0 0  
0 0 0 0.9000 1.0000 0 0 0 0  
0 0 0 0 0.9000 1.0000 0 0 0  
0 0 0 0 0 0.9000 1.0000 0 0  
0 0 0 0 0 0 0.9000 1.0000 0  
0 0 0 0 0 0 0 0.9000 1.0000
```

```
>> [F,L,M]=svd(H)
```

F =

```
-0.1612 0.3030 -0.4082 0.4642 -0.4642 0.4082 0.3030 -0.1612  
-0.3030 0.4642 -0.4082 0.1612 0.1612 -0.4082 -0.4642 0.3030  
-0.4082 0.4082 0.0000 -0.4082 0.4082 0.0000 0.4082 -0.4082  
-0.4642 0.1612 0.4082 -0.3030 -0.3030 0.4082 -0.1612 0.4642  
-0.4642 -0.1612 0.4082 0.3030 -0.3030 -0.4082 -0.1612 -0.4642  
-0.4082 -0.4082 -0.0000 0.4082 0.4082 0.0000 0.4082 0.4082  
-0.3030 -0.4642 -0.4082 -0.1612 0.1612 0.4082 -0.4642 -0.3030  
-0.1612 -0.3030 -0.4082 -0.4642 -0.4642 -0.4082 0.3030 0.1612
```

$f_0$

$f_7$

L =

```
1.8712 0 0 0 0 0 0 0 0  
0 1.7857 0 0 0 0 0 0 0  
0 0 1.6462 0 0 0 0 0 0  
0 0 0 1.4569 0 0 0 0 0  
0 0 0 0 1.2237 0 0 0 0  
0 0 0 0 0 0.9539 0 0 0  
0 0 0 0 0 0 0.6566 0 0  
0 0 0 0 0 0 0 0.3443 0
```

M =

```
-0.0775 0.1527 -0.2232 0.2868 -0.3414 0.3852 0.4153 -0.4214 0.4728  
-0.2319 0.4037 -0.4712 0.4182 -0.2608 0.0428 -0.1748 0.3238 -0.4255  
-0.3583 0.4657 -0.2480 -0.1415 0.4320 -0.4280 -0.1475 -0.1871 0.3830  
-0.4415 0.3099 0.2232 -0.4674 0.1108 0.3852 0.4008 0.0278 -0.3447  
-0.4714 0.0090 0.4712 -0.0208 -0.4705 0.0428 -0.4666 0.1348 0.3102  
-0.4445 -0.2960 0.2480 0.4602 0.0526 -0.4280 0.3140 -0.2812 -0.2792  
-0.3639 -0.4626 -0.2232 0.1806 0.4522 0.3852 -0.0146 0.3936 0.2513  
-0.2395 -0.4127 -0.4712 -0.3975 -0.2097 0.0428 -0.2917 -0.4586 -0.2261  
-0.0862 -0.1697 -0.2480 -0.3187 -0.3794 -0.4280 0.4615 0.4683 0.2035
```

$m_0$

$m_7$



# Matlab continued

- Use singular values<sup>2</sup> for channel gains:  $SVs = [ 1.87 \ 1.78 \ 1.64 \ 1.45 \ 1.22 \ .95 \ .66 \ .34 ]$

- The gains then are:  $g_n = \frac{\lambda_n^2}{\sigma^2(=.181)} = [19.3 \ 17.6 \ 15.0 \ 11.7 \ 8.3 \ 5.0 \ 2.4 \ 0.66]$

- Water-filling (RA) with 0 dB gap  $K = \frac{1}{7} \cdot \left( 9 + \sum_{n=0}^6 \frac{\Gamma}{g_n} \right) = 1.43$

- Energies  $[ 1.38 \ 1.37 \ 1.36 \ 1.34 \ 1.30 \ 1.23 \ 1.01 \ 0 ]$   $\mathcal{E}_n = K - \frac{\Gamma}{g_n}$

- SNRs  $[ 26.2 \ 24.2 \ 20.4 \ 15.8 \ 10.6 \ 6.2 \ 2.4 \ 0 ]$   $\mathcal{E}_n \cdot g_n$



# Overall performance and rate

- Product SNR

$$SNR_{VC} = \left[ \prod_{n=0}^6 (SNR_n + 1) \right]^{1/9} - 1 = 6.46 = 8.1 \text{ dB}$$

- Rate = capacity

$$\bar{C}(N = 9) = \frac{1}{9} \cdot \sum_{n=0}^6 \frac{1}{2} \cdot \log_2(1 + SNR_n) = 1.45 \text{ bits/dimension}$$

```
>> R=[.9 1 zeros(1,99)];  
>> C=[.9 zeros(1,99)];  
>> H=(1/sqrt(.181))*toeplitz(C,R);  
>> [F,L,M]=svd(H);  
>> g=diag(L).*diag(L);
```

```
>> K=(1/89)*(101+sum(ones(1,89)./g(1:89)'))
```

```
K = 1.3294
```

```
>> K-1/g(89) = -0.0219
```

```
>> K=(1/88)*(101+sum(ones(1,88)./g(1:88)'))
```

```
K = 1.3292
```

```
>> K-1/g(88) = 0.1627
```

So **N\* = 88**

```
>> E=K*ones(1,88)-ones(1,88)./g(1:88)';
```

```
>> snr=E.*g(1:88)';
```

```
>> b=(0.5/101)*(1/log(2))*sum(log(ones(1,88)+snr))
```

```
b =
```

**1.5360**

$\bar{N} \rightarrow \infty$ , then  $\frac{\bar{N} + \nu}{\bar{N}} \rightarrow 1$ , so no loss (max is 1.55)



# DMT/OFDM Partitioning

*Section 4.7.1-5*

[See PS1.3 \(Prob 4.18\)](#)

# Cyclic Extension

- Remember this convolution from vectoring coding?

$$\begin{bmatrix} y_{\bar{N}-1} \\ y_{\bar{N}-2} \\ \vdots \\ y_0 \end{bmatrix} = \begin{bmatrix} h_0 & h_1 & \dots & h_\nu & 0 & \dots & 0 \\ 0 & h_0 & \ddots & h_{\nu-1} & h_\nu & \ddots & 0 \\ 0 & \ddots & \ddots & \ddots & \ddots & \ddots & 0 \\ 0 & \dots & 0 & h_0 & h_1 & \dots & h_\nu \end{bmatrix} \begin{bmatrix} x_{\bar{N}-1} \\ \vdots \\ x_0 \\ \text{guard period} \\ x_{-1} \\ \vdots \\ x_{-\nu} \end{bmatrix} + \begin{bmatrix} n_{\bar{N}-1} \\ n_{\bar{N}-2} \\ \vdots \\ n_0 \end{bmatrix}$$

Now it is cyclic

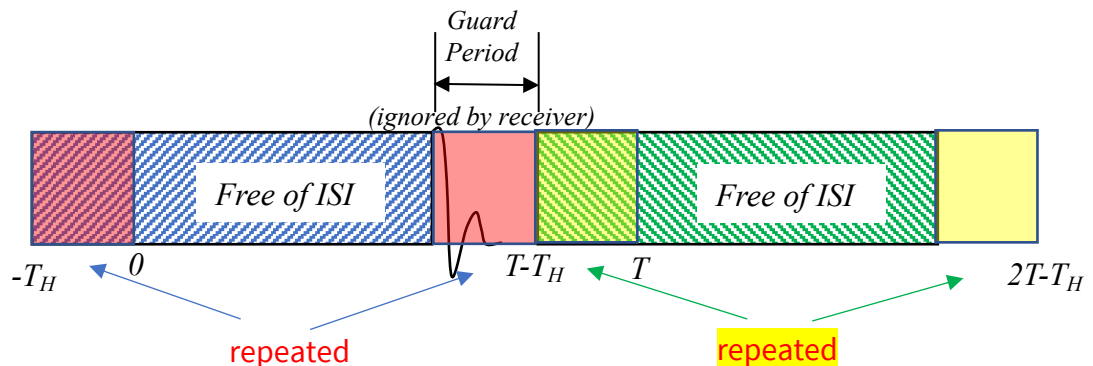
$$\mathbf{y} = \tilde{\mathbf{H}} \mathbf{x} + \mathbf{n}$$

- Let the guard period be such that  $x_{-i} = x_{\bar{N}-i}$  for  $i=1, \dots, \nu \rightarrow$  **CYCLIC PREFIX** or **CYCLIC EXTENSION**.
  - The channel now appears periodic!

- “Toeplitz-distribution” limiting results use this cyclic-extension concept,  $T = (\bar{N} + \nu) \cdot T'$ .

Ideally  $\bar{N} \gg \nu$

So small loss of dimensions



# Cyclic Convolution

- The matrix expression now uses an  $N \times N$  circulant matrix:

$$\begin{bmatrix} y_{\bar{N}-1} \\ y_{\bar{N}-2} \\ \vdots \\ y_0 \end{bmatrix} = \begin{bmatrix} h_0 & h_1 & \dots & h_\nu & 0 & \dots & 0 \\ 0 & h_0 & \ddots & h_{\nu-1} & h_\nu & \ddots & 0 \\ 0 & \ddots & \ddots & \ddots & \ddots & \ddots & 0 \\ 0 & \dots & 0 & h_0 & h_1 & \dots & h_\nu \\ h_\nu & 0 & \dots & 0 & h_0 & \dots & h_{\nu-1} \\ \vdots & \ddots & \ddots & \ddots & \ddots & \ddots & \vdots \\ h_1 & \dots & h_\nu & 0 & \dots & 0 & h_0 \end{bmatrix} \begin{bmatrix} x_{\bar{N}-1} \\ \vdots \\ x_0 \end{bmatrix} + \begin{bmatrix} n_{\bar{N}-1} \\ n_{\bar{N}-2} \\ \vdots \\ n_0 \end{bmatrix}$$

$\tilde{H}$  is circulant  
 $\bar{N} \times \bar{N}$

$$\mathbf{y} = \tilde{H} \cdot \mathbf{x} + \mathbf{n}$$

- As far as output  $\mathbf{y}$  is concerned, the input is periodic with the same period  $\bar{N}$  as the output.
- The cyclic prefix is added for each and every symbol.
- $\nu$  dimensions are lost (both in terms of energy lost and no new information).



# Cyclic Convolution and the DFT

- DFT = Discrete Fourier Transform

- Normalized DFT maintains squared norm, energy from time  $\leftrightarrow$  frequency.
- $N$  or  $\bar{N}$

$$X_n = \frac{1}{\sqrt{\bar{N}}} \cdot \sum_{k=0}^{\bar{N}-1} x_k \cdot e^{-j\frac{2\pi}{\bar{N}} \cdot kn} \quad \forall n \in [0: \bar{N} - 1]$$

$$\sum_{n=0}^{\bar{N}-1} |X_n|^2 = \sum_{k=0}^{\bar{N}-1} |x_k|^2$$

- IDFT = Inverse Discrete Fourier Transform

- has symmetrical form

$$x_k = \frac{1}{\sqrt{\bar{N}}} \cdot \sum_{n=0}^{\bar{N}-1} X_n \cdot e^{+j\frac{2\pi}{\bar{N}} \cdot kn} \quad \forall k \in [0: \bar{N} - 1]$$

- Subsymbol channel  $Y_n = \tilde{H}_n \cdot X_n (+ N_n)$

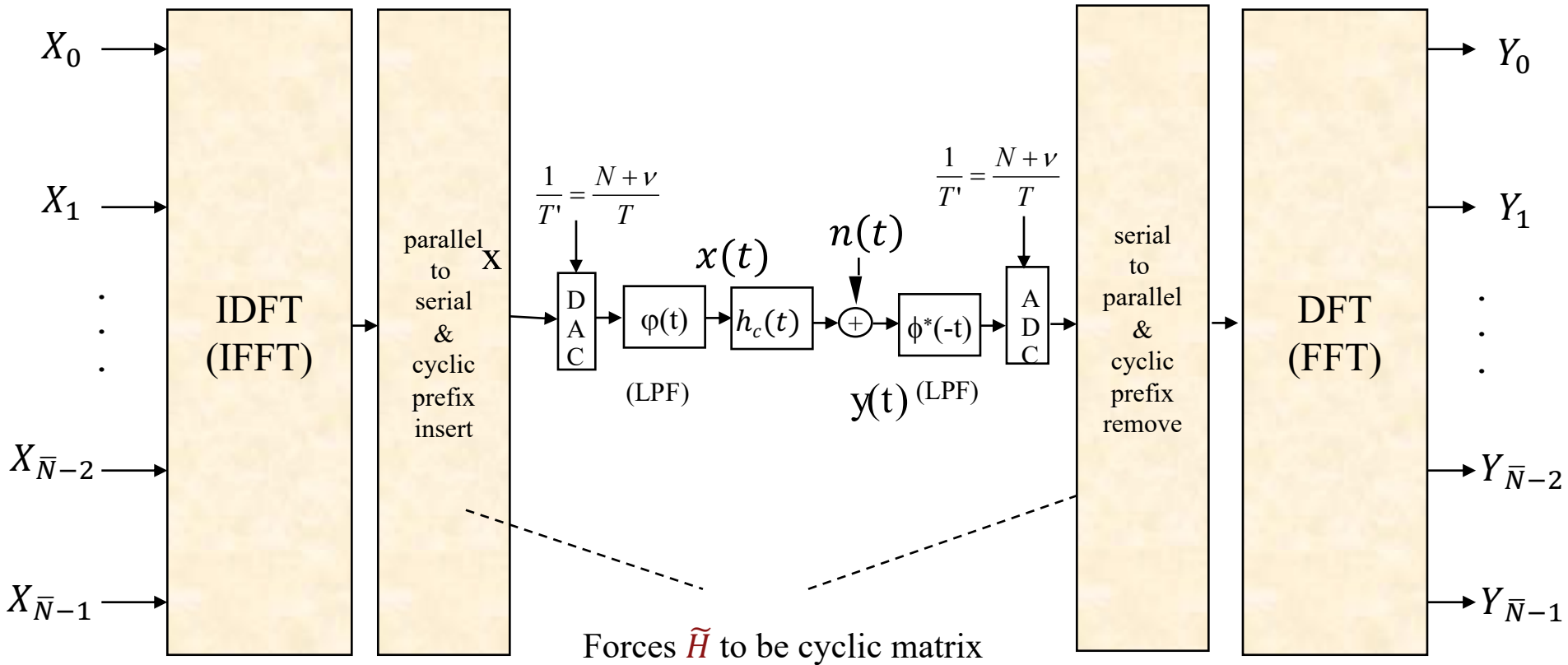
- Vector coding with  $M = F^* = Q$ , but diagonal can be complex,
- *and the guard period must be cyclic.*
- This remains a parallel set of AWGN subchannels.

$$\tilde{H} = Q \cdot \Lambda \cdot Q^*$$

$$\Lambda = \begin{bmatrix} \tilde{H}_{N-1} & 0 & 0 \\ 0 & \ddots & 0 \\ 0 & 0 & \tilde{H}_0 \end{bmatrix} = \text{DFT values on diagonal}$$



# DMT / OFDM Transmission



$$X_{N-i} = X_i^* \text{ if } x(t) \text{ is real}$$

**Heavily used, wireline & wireless**



# Product SNR

- DMT uses 7 subchannels, DC plus 3 two-dimensional QAM subchannels, of a total of 9 dimensions.

$$\text{SNR}_{DMT} = \left[ \prod_{n=0}^6 (1 + \text{SNR}_n) \right]^{1/9} - 1 = 7.6 \text{ dB} < \text{SNR}_{vc}$$

- But **no** channel-dependent partitioning, and much easier to implement ( $N \log(N)$  vs  $N^2$ ).

- How can we exploit this??

**INCREASE  $N$  !**

- DMTra and DMTma will help.



# 1+.9D<sup>-1</sup> revisited

- Circulant Channel is 8 x 8 (but wastes 1 dimension in cyclic extension, and loses its energy).

$$\tilde{H} = \begin{bmatrix} .9 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & .9 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & .9 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & .9 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & .9 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & .9 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & .9 & 1 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & .9 \end{bmatrix} \quad 8 \times 8$$

Water-fill ( $\Gamma=0$  dB) with  $\mathcal{E}_x = 8$

- Channel FFT (size 8) leads to:

$n$	$\lambda_n =  P_n $	$g_n = \frac{ P_n ^2}{.181}$	$\mathcal{E}_n$	$\text{SNR}_n$	$b_n$
0	1.90	20	1.24	24.8	2.34
1	1.76	17	1.23	20.9	2.23
6	1.76	17	1.23	20.9	2.23
2	1.35	9.8	1.19	11.7	1.85
5	1.35	9.8	1.19	11.7	1.85
3	.733	3	.96	2.9	.969
4	.733	3	.96	2.9	.969
7	.100	.05525	0	0	0

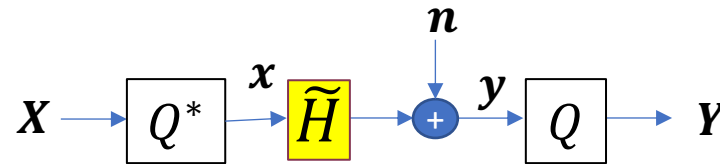
- $\bar{b} = 1.38$

[See PS1.4 \(Prob 4.7\)](#)



# Partitioning with DFT

- DFT Partitioning is:



- DFT creates a set of parallel channels – A “Discrete MultiTone” partitioning.
  - Some call it OFDM, but there is a difference in loading (DMT optimizes loaded energy, OFDM fixes equal energy).

$$SNR_n = \frac{\epsilon_n \cdot |\tilde{H}_n|^2}{\sigma^2}$$

Noise-Equivalent Channel

$$E[\mathbf{n}\mathbf{n}^*] = R_{nn}\sigma^2 = R_{nn}^{1/2}R_{nn}^{-1/2}\sigma^2$$

$$\mathbf{y} \leftarrow R_{nn}^{-1/2}\mathbf{y} = (R_{nn}^{-1/2}H)\mathbf{x} + \tilde{\mathbf{n}}$$

- Receiver is DFT (and noise remains white).
- Transmitter is IDFT (no power increase).

Neither is a function of the channel.

Can use efficient “FFT”



# *DMT Water-Filling Software*

## Subsection 4.7.4

*See PS1.4 (Prob 4.7) and PS1.5 (Prob 4.9)*

# Rate Adaptive DMT

```
function [gn,en_bar,bn_bar,Nstar,b_bar,SNRdmt]=DMTra(H,NoisePSD,Ex_bar,N,gap)
```



OUTPUTS

INPUTS

- `>> [gn,en_bar,bn_bar,Nstar,b_bar,SNRdmt]=DMTra([.9 1],.181,1,8,0)`
- gn = 19.9448 17.0320 10.0000 2.9680 0.0552 2.9680 10.0000 17.0320
- en\_bar = 1.2415 1.2329 1.1916 0.9547 0 0.9547 1.1916 1.2329
- bn\_bar = 2.3436 2.2297 1.8456 0.9693 0 0.9693 1.8456 2.2297
- Nstar = 7
- b\_bar = 1.3814
- SNRdmt = 7.6247 dB



In using the program, know if your channel is truly baseband or complex baseband equivalent.

**In real case, each dimension shown is a real dimension.**



# Increase N

- `[gn,en_bar,bn_bar,Nstar,b_bar,SNRdmt]=DMTra([.9 1],.181,1,16,0);`
  - `>> SNRdmtSNRdmt = 8.1152`
- `[gn,en_bar,bn_bar,Nstar,b_bar,SNRdmt]=DMTra([.9 1],.181,1,1024,0);`
  - `>> SNRdmtSNRdmt = 8.7437`
- Feel free to experiment, PS1.4 goes better if you use this.



# How about non-zero gap?

- SNR can look higher, but bit rate is overall lower

```
>> [gn,En,bn_bar,Nstar,b_bar,SNRdmt]=DMTra([.9 1],,181,1,8,8.8)
```

```
gn = 19.9448 17.0320 10.0000 2.9680 0.0552 2.9680 10.0000 17.0320
```

```
En = 1.7773 1.7123 1.3991 0 0 0 1.3991 1.7123
```

```
bn_bar = 1.2521 1.1382 0.7540 0 0 0 0.7540 1.1382
```

```
Nstar = 5
```

```
b_bar = 0.5596
```

```
SNRdmt = 9.4904 dB (remember this gets divided by the gap)
```

```
>> En.*gn = 35.4481 29.1634 13.9907 0 0 0 13.9907 29.1634  
24.7613 20.9991 11.9163 2.8336 0 2.8336 11.9163 20.9991 ( $\Gamma=0$ )
```

```
>> 10*log10(ans) = 15.4959 14.6484 11.4584 -Inf -Inf -Inf 11.4584 14.6484  
(these subchannel SNR's also get divided by gap)
```

Data rate is  
roughly 1/3 of  
before.

**Note SNRdmt  
increase for  
nonzero gap.**



# Suppose $1+.9D^{-1}$ were complex baseband?

- The channel effectively has twice as many dimensions.
  - The same results would be for 8 complex dimensions.
  - So  $b_{bar}$ ,  $e_{bar}$  are really bits/tone and energy/tone.
  - Same values, but the constellations on each tone are two dimensional.



```
>> [gn,En,bn,Nstar,b,SNRdmt]=DMTra([.9 1],.181,2,8,0)
```

```
gn = 19.9448 17.0320 10.0000 2.9680 0.0552 2.9680 10.0000 17.0320
```

```
En = 2.3843 2.3758 2.3345 2.0976 0 2.0976 2.3345 2.3758
```

```
bn = 2.8008 2.6869 2.3028 1.4266 0 1.4266 2.3028 2.6869
```

```
Nstar = 7
```

```
b = 1.7370
```

```
SNRdmt = 10.0484 dB
```

```
>> sum(En) = 16.0000 ; >> sum(bn) = 15.6332
```

- The bits/tone though is slightly larger.
  - $1.73 > 1.38$
- What happened?
- The “DC” tone is now complex and has an additional good dimension.



# Suppose $1+.9jD^{-1}$ - must be complex baseband

- The channel definitely has twice as many real dimensions

```
>> [gn,En,bn,Nstar,b,SNRdmt]=DMTra([.9*i 1],.181,2,8,0)
```

```
gn = 10.0000 17.0320 19.9448 17.0320 10.0000 2.9680 0.0552 2.9680
```

```
En = 2.3345 2.3758 2.3843 2.3758 2.3345 2.0976 0 2.0976
```

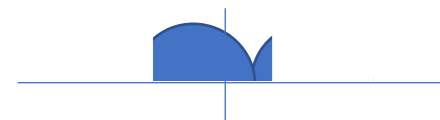
```
bn = 2.3028 2.6869 2.8008 2.6869 2.3028 1.4266 0 1.4266
```

```
Nstar = 7
```

```
b = 1.7370
```

```
SNRdmt = 10.0484
```

```
>> sum(En) = 16.0000 ; >> sum(bn) = 15.6332
```

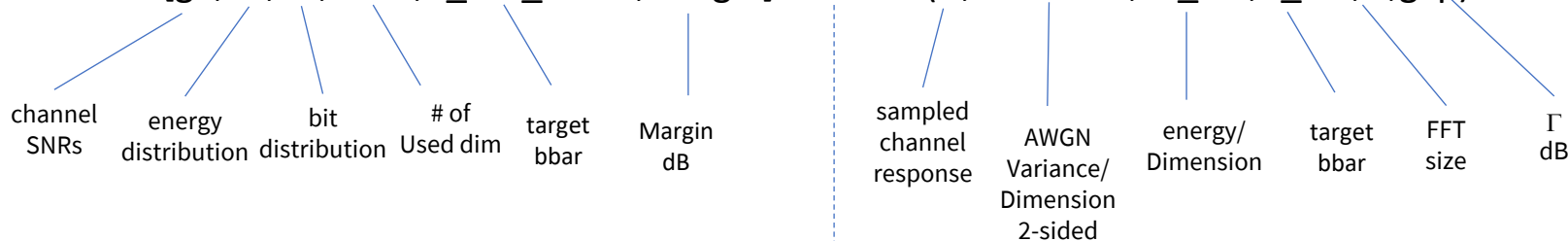


This channel rotates the earlier one in time, so circular shift in frequency



# Margin Adaptive DMT

▪ function [gn,en,bn,Nstar,b\_bar\_check,margin]=DMTma(H,NoisePSD,Ex\_bar,b\_bar,N,gap)



OUTPUTS

INPUTS

- `>> [gn,en,bn,Nstar,b_bar_check,margin]=DMTma([.9 1],.181,1,1,8,0)`
- `gn = 19.9448 17.0320 10.0000 2.9680 0.0552 2.9680 10.0000 17.0320`
- `en = 0.6043 0.5958 0.5545 0.3175 0 0.3175 0.5545 0.5958`
- `bn = 1.8532 1.7393 1.3552 0.4790 0 0.4790 1.3552 1.7393`
- `Nstar = 7`
- `b_bar_check = 1`
- `margin = 3.5410`

**It works real or complex,  
but (again) be careful.**



# Continuing

- `>> [gn,en,bn,Nstar,b_bar_check,margin]=DMTma([.9 1],.181,1,1,8,8.8)`
- `gn = 19.9448 17.0320 10.0000 2.9680 0.0552 2.9680 10.0000 17.0320`
- `en = 4.5844 4.5193 4.2061 2.4088 0 2.4088 4.2061 4.5193`
- `bn = 1.8532 1.7393 1.3552 0.4790 0 0.4790 1.3552 1.7393`
- `Nstar = 7`
- `b_bar_check = 1.0000`
- `margin = -5.2590` Negative margin – can't do it!

```
[gn,en,bn,Nstar,b_bar_check,margin]=DMTma([.9 1],.181,1,1,16,0);
```

```
>> margin = 4.1445 (equivalently, code with gain >8.8-4.1=4.5 will work at  $P_e < 1e-6$ )
```

```
[gn,en,bn,Nstar,b_bar_check,margin]=DMTma([.9 1],.181,1,1,1024,0);
```

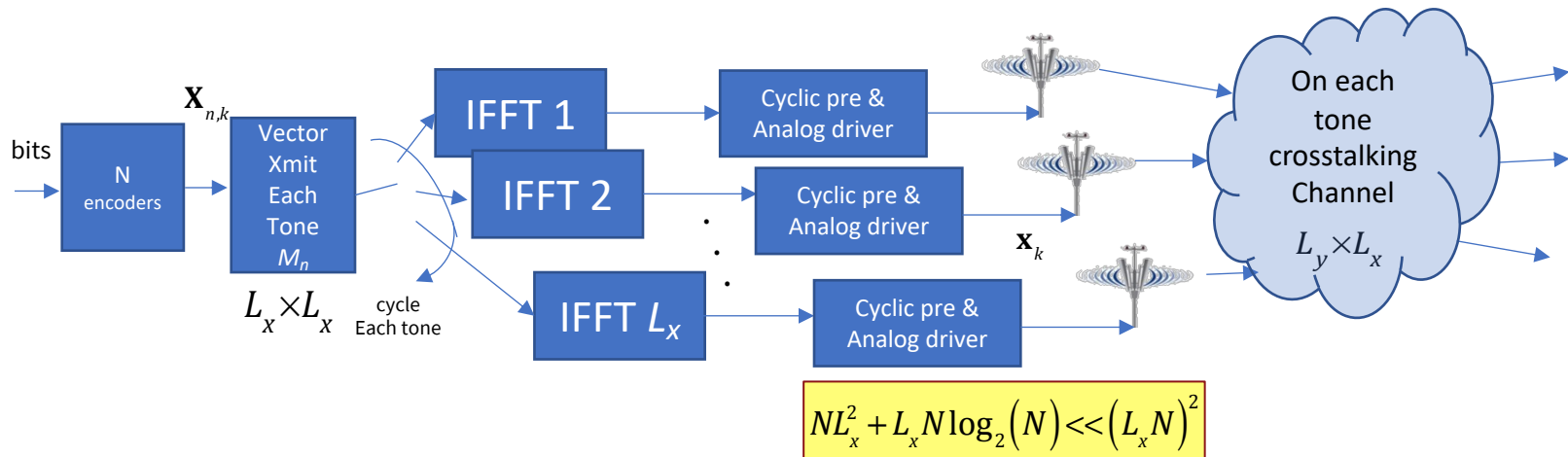
```
>> margin = 4.7267 (save .6 dB on code and use longer FFT)
```



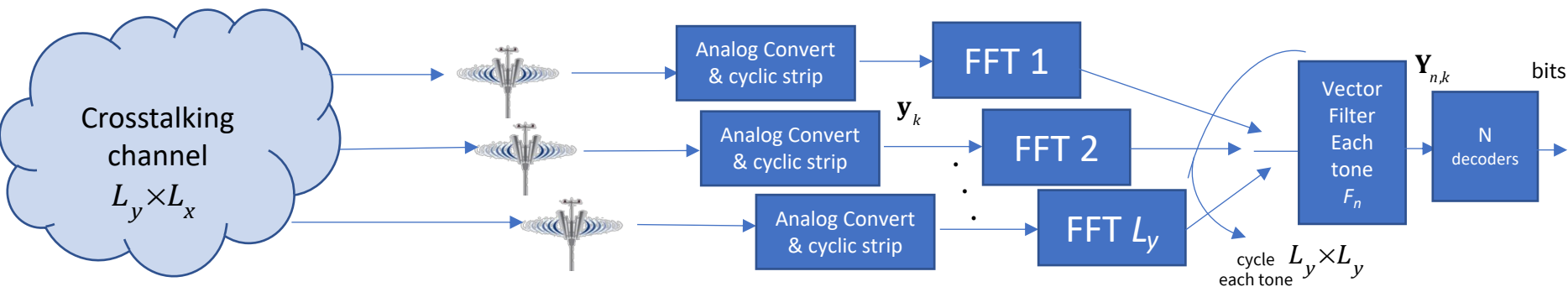
# *Vector DMT/OFDM*

## Section 4.7

# Vector DMT/OFDM Transmitter



# Vector DMT/OFDM Receiver



$$\tilde{H}_n = F_n \cdot \Lambda_n \cdot M_n^*$$

$$NL_y^2 + L_y N \log_2(N) \ll (L_y N)^2$$

- Just much larger number of dimensions, each a scalar AWGN,  $L = \min(L_x, L_y)$
- $L \cdot N$  dimensions
- Can water-fill over them all (if total energy constraint, which is common)

**N=1024, L=8 --> 64k+80k=144k versus 64M !!!**





# End Lecture 2