



STANFORD

**WELCOME TO EE379A !!**  
***Data Transmission Design***  
**2024 Winter Quarter**

**JOHN M. CIOFFI**

Hitachi Professor Emeritus (recalled) of Engineering

Instructor EE379A – Winter 2024



STANFORD

*Lecture 1*

# **Discrete Message Encoding/Decoding**

*January 9, 2024*

**JOHN M. CIOFFI**

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# Announcements & Agenda

## Announcements

- People Introductions
- Web site [EE379A](#) (see also canvas)
- Chapters 1-8 on-line at this class web site (Course Reader)
- Sections 1.1 and 1.2 today
- See last/backup slide today for matlab toolboxes I use
- Qualcomm and/or Samsung internships (send me email)
  - Apple, Intel, Ericsson



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Welcome Course Info Course Reader Lectures Handouts Homework Matlab Additional Topics

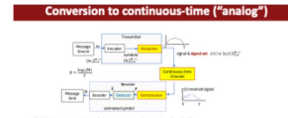
Winter Quarter 2023-2024

## EE 379A - Data Transmission Design

Instructor : Prof. John Cioffi

Teaching Assistant : Ethan Liang

Lectures : Course offered winter 2024.



## Today

- Course introduction
- Discrete Data Transmission & Examples (1.1)
- Modulation and Demodulation (1.2)
- Detection(1.1.2)
- Vector Channels (1.1.1)
  - Detection and Decision Regions (1.1.3)

## Problem Set 1 = PS1 due Wednesday Jan 17 at 17:00

1. 1.1 a constellation
2. 1.2 inner products
3. 1.3 same constellation, different modulators
4. 1.7 Irrelevancy and decision regions
5. 1.10 constellation invariances

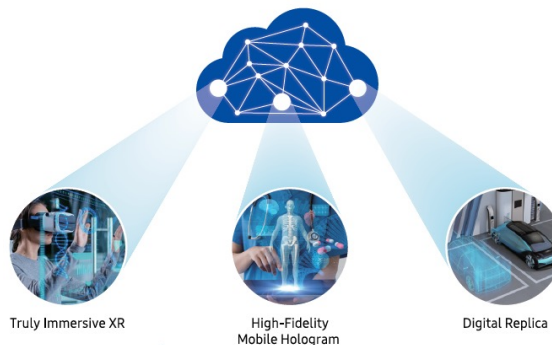


# Intro: Why Communications?

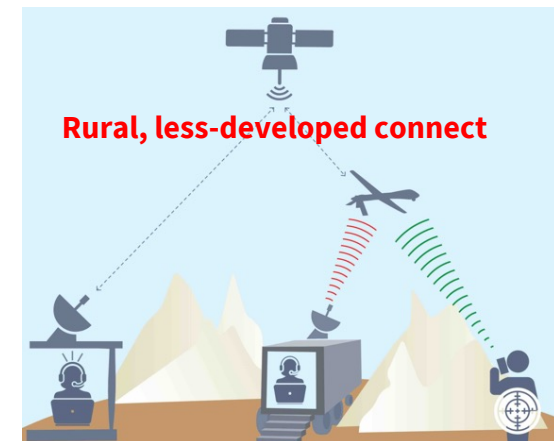
This fundamental area is always needed.  
Many decades: it surges at times

**If you love it, it is absolutely great area to enjoy working for your decades ahead.**

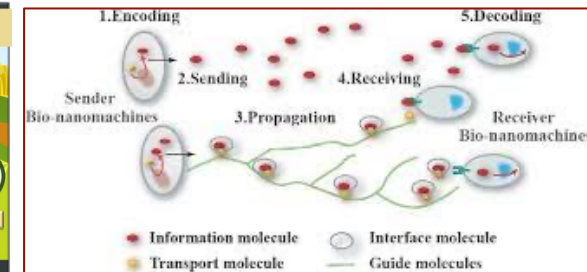
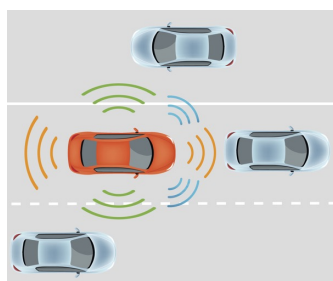
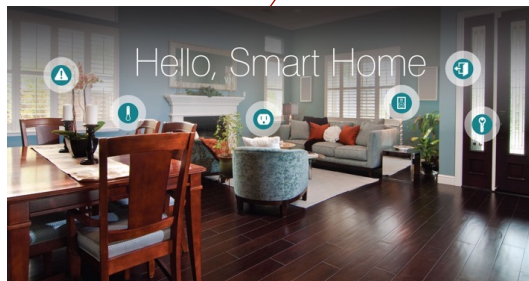
# Next Generation Connectivity



Beam "me" there, Scotty



Digital Twins used to forecast/emulate each



Defense ("5/6G.mil")  
Clothing, Computing, ...

Samsung: 6G "hyper connected"

L1:5

Stanford University

January 9, 2024

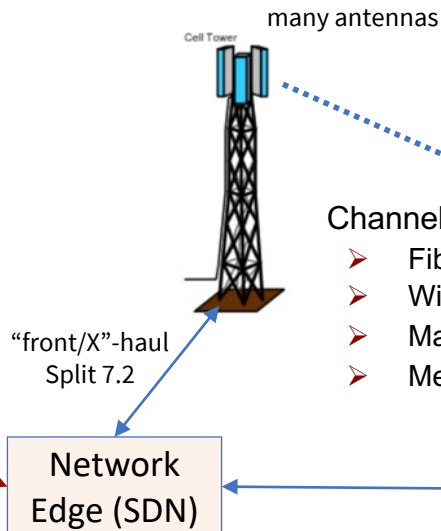


# Broadband Internet Access (\$1.5T/year)

## Messages

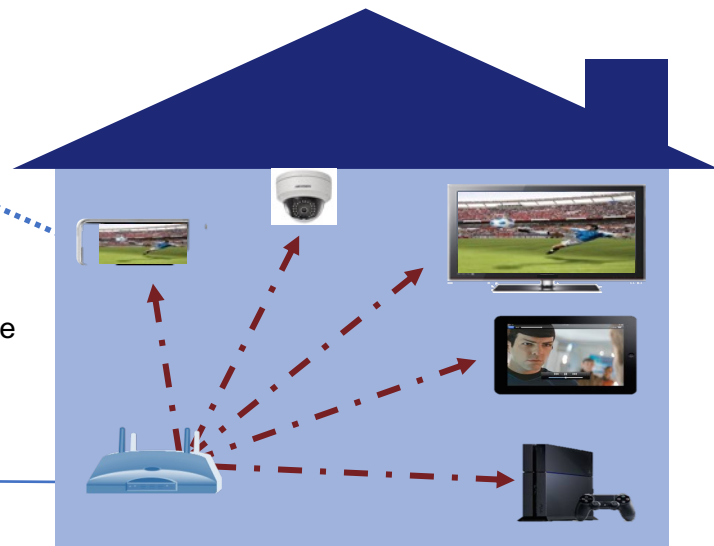
- Internet
- Email
- Text
- video, audio
- Sensor/camera images

(almost) All signal processing, modulation, and coding done in software at edge with shared computing facility



### Channel

- Fiber, copper
- Wireless
- Many or single
- Mesh



### OSI Model

Layer	Function	Example Protocols	
7	Application Layer	network process to application	HTTP, SFTP, SSH
6	Presentation Layer	data representation & encryption	XML, JSON
5	Session Layer	interhost communication	Mostly theoretical
4	Transport Layer	end-to-end connections & reliability	TCP, UDP
3	Network Layer	path determination & logical addressing	IP Addresses
2	Data Link Layer	physical addressing	MAC Addresses
1	Physical Layer	medial signal & transmission	Ethernet, Bluetooth, Wireless

OSI = **Open** Systems Interconnect

SDN = **Software** Defined Network

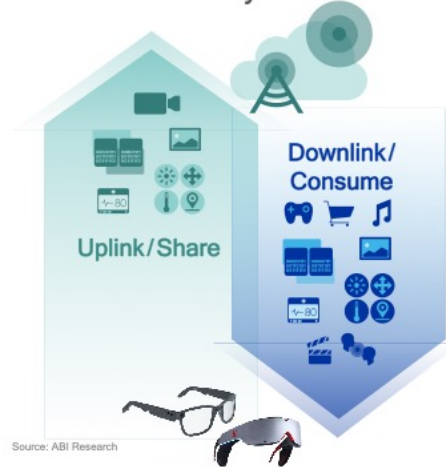
this class



# Metaverse - VR/AR focus and Bandwidth

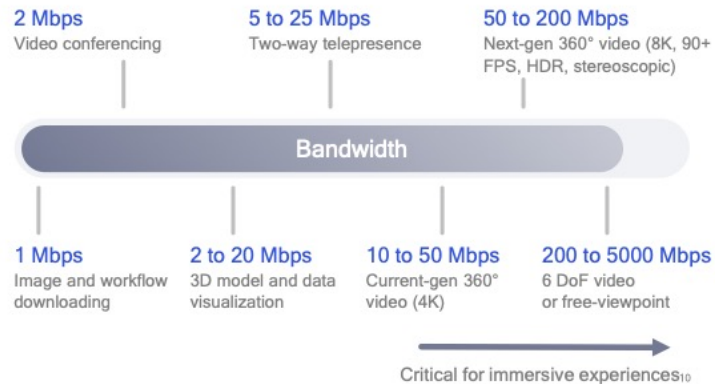
## VR and AR require efficient increase in wireless capacity

Constant up/download on an all-day wearable



Richer visual content

- Higher resolution, higher frame rate
- Stereoscopic, High Dynamic Range (HDR), 360° spherical content, 6 DoF



Latency:

Edge ~ 1 ms

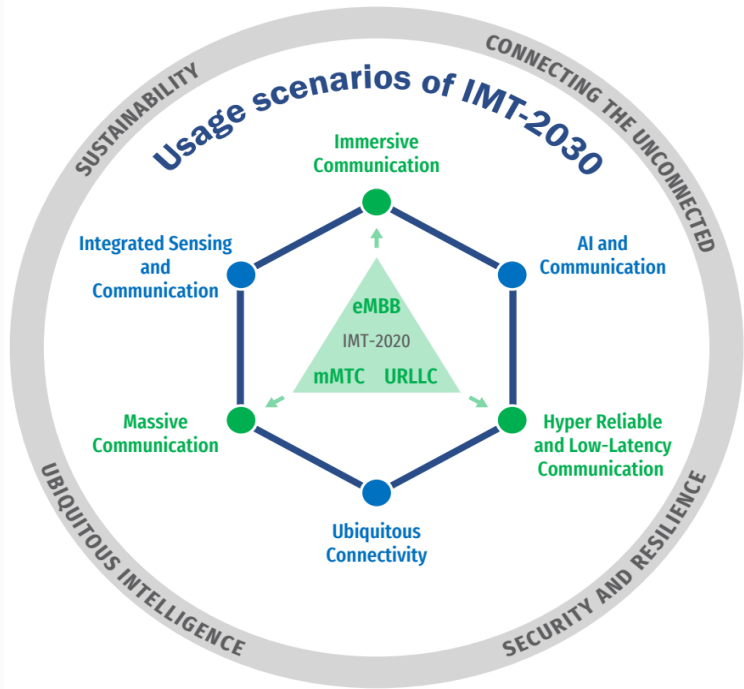
ISP Cloud 20-50 ms

Public Cloud 100 ms



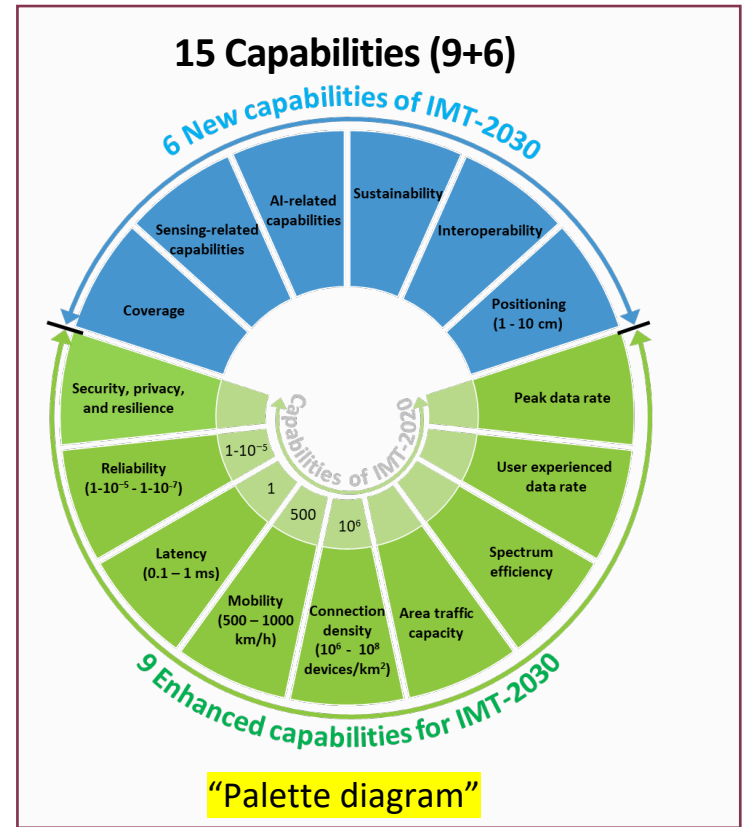
# International Mobile Telecommunications (IMT)

## 6 Usage Scenarios (3+3)



“Wheel diagram”

## IMT-2030 ITU-R M.2160-0 (11/2023)

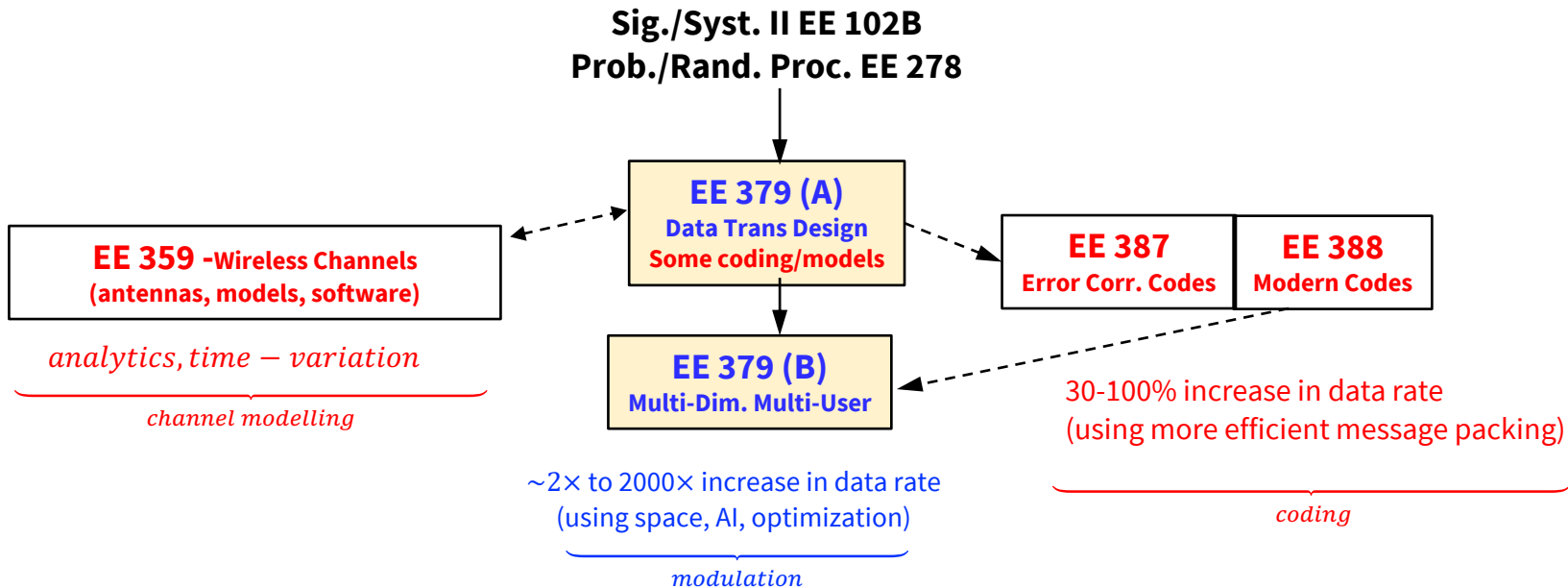


“Palette diagram”





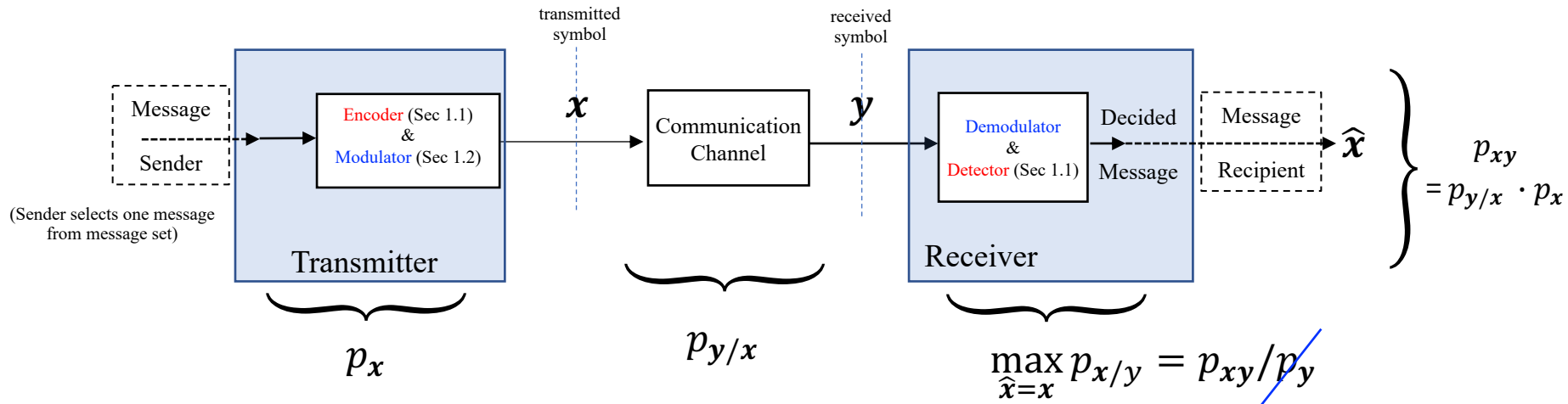
# Communications Depth Sequence



- **Modulation and Coding** compliment one another
  - **Modulation** = energy assignment to time/frequency/space, is separate from:
  - **Coding** = distinct message mapping.
  - If both done well, they separate.



# Basic Communication (digital)



- The symbol  $x$  and messages are in a 1-to-1 relationship.
- Finding the best  $\hat{x}$  and designing  $x$  well  $\rightarrow$  this class.
- Most general channel is represented by the conditional probability  $p_{y/x}$ .
- Partial source description is  $p_x$  - together,  $p_{xy}$ . (Mapping to  $x$  is important.)
- Optimum detector (minimizes ave error probability) is Maximum a Posteriori (MAP),  $\max p_{x/y} \sim p_{xy} = p_{y/x} \cdot p_x \cdot (1.1.2.1)$ 
  - When input distribution is uniform (constant)  $\rightarrow$  ML (maximum likelihood),  $\max_x p_{y/x} \cdot (1.1.2.2)$

**EE 379A is single  $x$  user (time-domain);**

**EE 379B expands to multiuser, MIMO, multicarrier**



# 3 Basic Problems to Solve

- **CHANNEL IDENTIFICATION** - what is  $p_{y/x}$  ?
- **CODING & MODULATION** - What are good (best)  $x$  and  $p_x$  for a given channel?
- **DETECTION** – What is a good (best) receiver for deciding which  $x$  ?



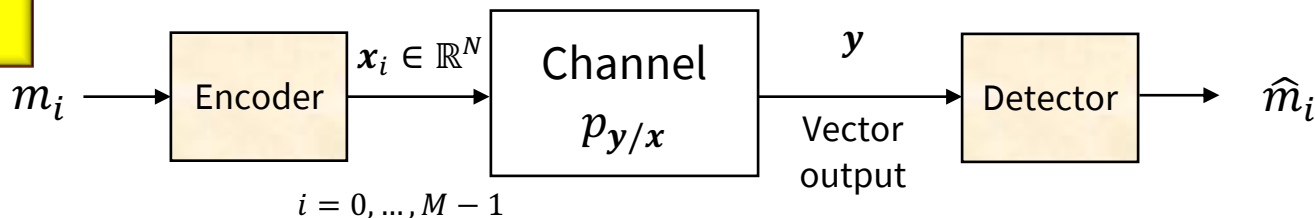
# Discrete Data Transmission & Examples

## *Section 1.1.1*

# Discrete Message Transmission

Temporarily omit  
modulator/demodulator

$M = 2^b$   
possible messages



Channel  $\in$  {fiber, copper, wireless, disk/SSD, flesh, qubit, ... }

- Designers identify a channel's vector conditional-probability description  $p_{y/x}$ .
  - This allows a common design framework across different channel types/models.
- $m_i$ , one of  $M < \infty$  discrete messages (a vector “**symbol**”  $x$ ), is sent every **symbol period** of  $T$  seconds.
  - Messages are represented by symbol vectors, 1-to-1 mapping from messages.
  - Later  $m_i \rightarrow m$ .
  - $b = \log_2(M) =$  **number of bits (in message)**.
- Conversion to/from actual (often continuous-time “analog”) is “**modulation**,”
  - and left unspecified in this general discrete-message-transmission model.
  - Many different modulation methods can conform to the same discrete message-transmission system.



# Transmitted-Symbol Quantities

Name	Definition
$M = 2^b \in \mathbb{Z}^+$	<b>number of messages</b> , corresponding to $b \geq 0$ information bits
$T \in \mathbb{R}$	<b>symbol period</b> ; $1/T$ is the <b>symbol rate</b>
$R = \frac{b}{T} \in \mathbb{R}$	<b>data rate</b> .
$\mathbf{x}$	transmitted <b>symbol</b> value (typically a real or complex vector)
$C \subset \mathbb{R}^N$	<b>constellation</b> that consists of all possible symbol values $\{\mathbf{x}_i \mid i = 0, \dots,  C  - 1\}$ with $ C  \geq M$ and in this chapter, always equal.
$p_m(i) \in \mathbb{R}$	<b>message's probability distribution</b> , $i = 0, \dots, M - 1$
$p_{\mathbf{x}}(i) \in \mathbb{R}$	<b>symbol value's probability distribution</b> = $p_m(i)$
$N \in \mathbb{Z}^+$	<b>number of real temporal dimensions</b> per transmit symbol the receive symbol has $N + \nu$ dimensions with default $\nu = 0$ and $\nu \in \mathbb{Z}$
$L_x \in \mathbb{Z}^+$	number of <b>transmit spatial dimensions</b>
$L_y \in \mathbb{Z}^+$	number of <b>receive spatial dimensions</b>

Table 1.1: Table of transmitted-symbol quantities' definitions.

- Derived:

**Energy**

**Power**

$$\mathcal{E}_x = \mathbb{E}[\|\mathbf{x}\|^2] = \sum_{i=1}^{64} p_x(i) \cdot \|\mathbf{x}_i\|^2$$

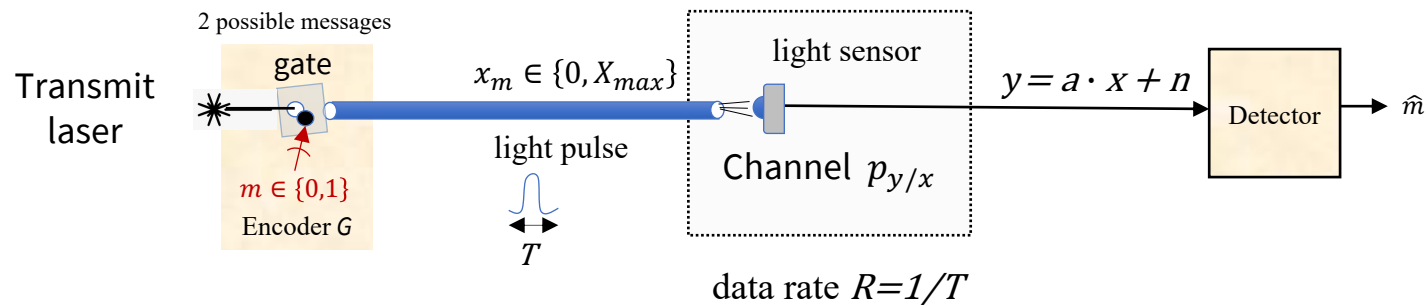
$$P_x = \frac{\mathcal{E}_x}{T}$$

1.1.1.2

dB (decibels) are measured as  
 $10 \cdot \log_{10}$  *energy or power*  
 $= 20 \cdot \log_{10}$  *amplitude*  
 often relative to 1 mW (dBm)



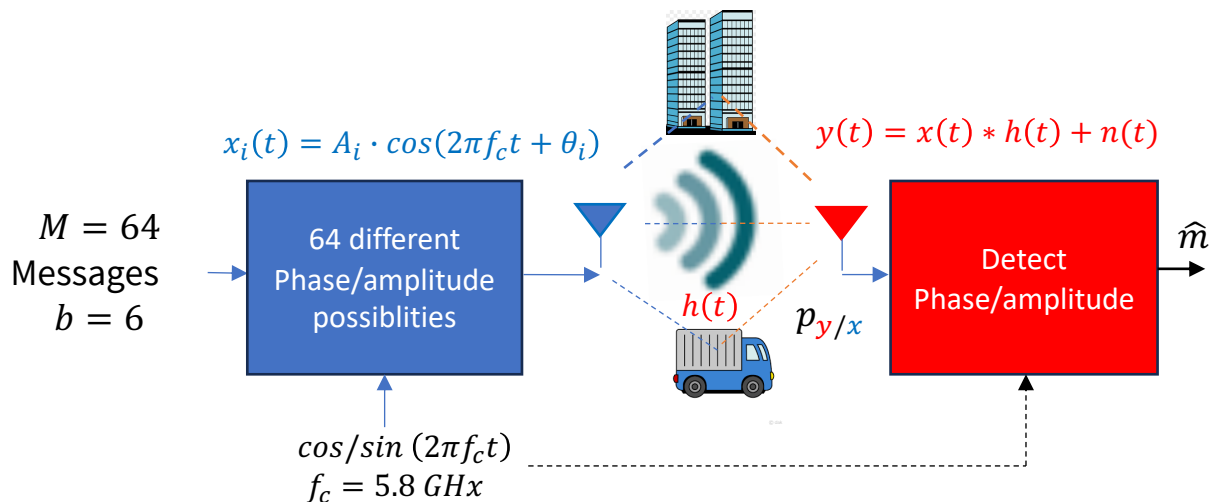
# Example 1: Light-Pulse Bit Transmission



- On/off -  $M = 2$  and  $b = 1$  bit.
- If  $T = 10 \text{ ps}$ , then  $R = 100 \text{ Gbps}$  ( $10^{11}$ ) bits/second.
- $x \in \{0, X_{max}\}$ .
- “non-coherent” or “direct-detection” optical transmission.



# Example 2: Wireless

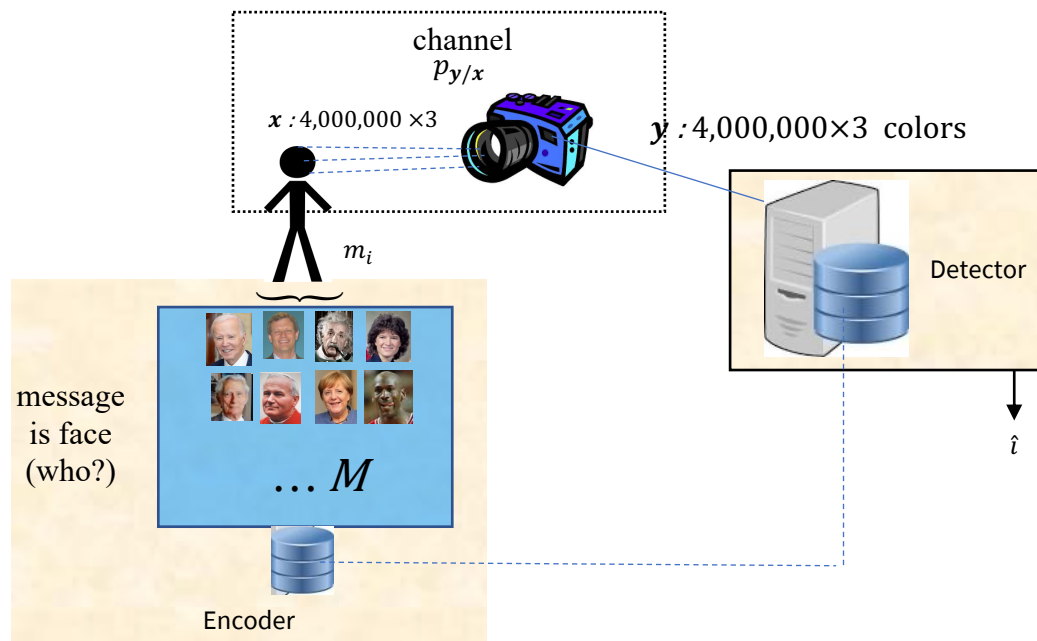


- Channel adds noise and has multiple paths that can align positively or negatively.
- Discrete modulator  $\mathbf{x} = A \cdot e^{j\theta}$  (**64 complex vectors, one for each message**); while  $\mathbf{y} = H \cdot \mathbf{x} + \mathbf{n}$ .
- $1/T = 100 \text{ MHz}$ , so  $R = 600 \text{ Mbps}$ .





# 4 megapixel photograph

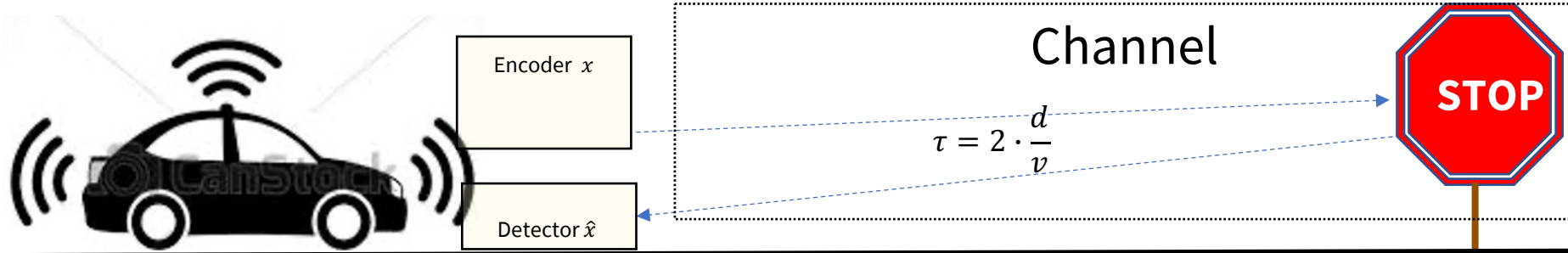


- Number of dimensions  $N = 2280 \times 1640 \times 3$  (exactly 11,217,600).
- $M = 8$  ;  $b = 3$ .
- $R = 3$  bits/photo, where  $T = 1$  photo.

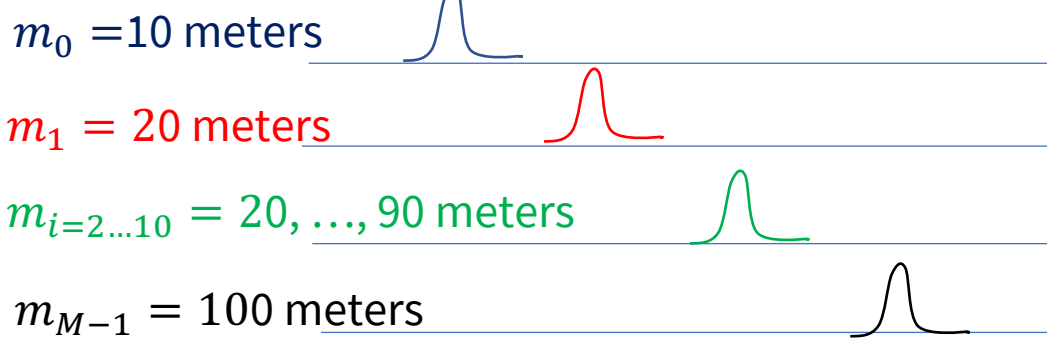
**Today's machine-learned facial ID reduces to this basic system, with perhaps large  $M$**



# distance measurement (radar, lidar)



$v = \text{velocity}$        $d = \text{distance}$



lidar pulse position  
is the message,  
equivalent to distance  
where decoder maps  $\tau$   
to the message index or  $d$

$$\mathbf{x}_m = [x(0) \quad x(T') \quad \dots \quad x([M - 1]T')]$$

**Radar, lidar, ..., sensors  
Are basic com systems**

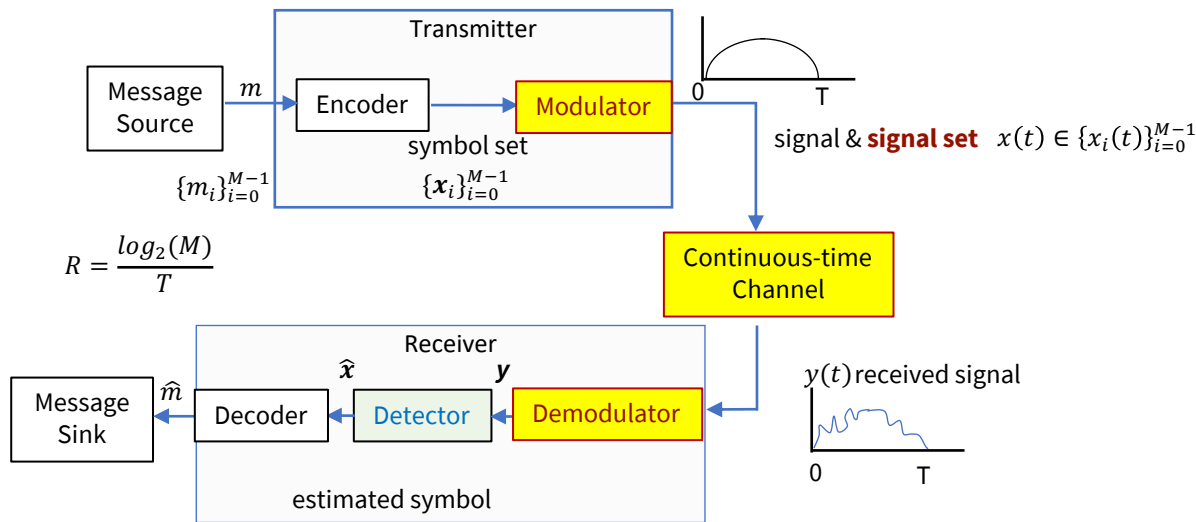


# Modulation and Demodulation

*(a foundation: Sections 1.1-1.2)*

[See PS1.1 and PS1.2](#)

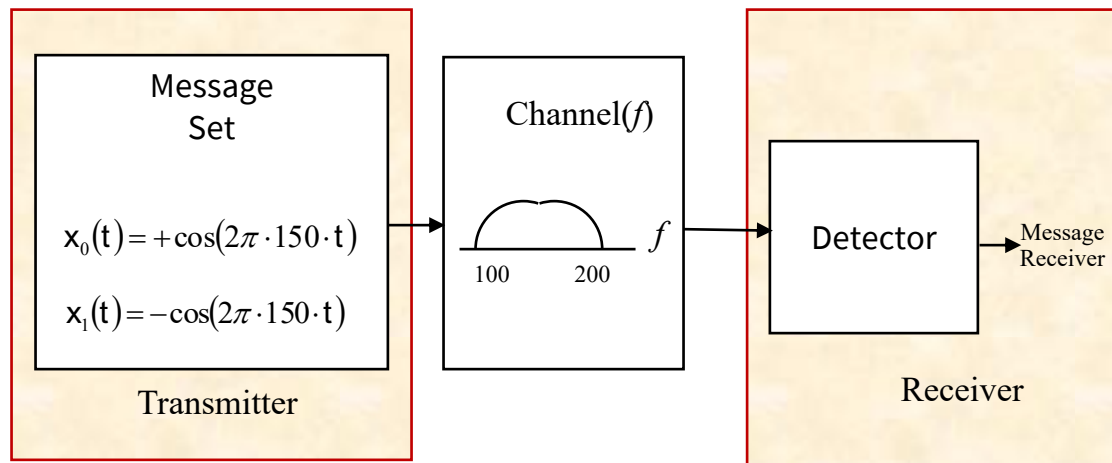
# Conversion to continuous-time (“analog”)



- **Modulator** – converts the symbol vector  $x$  to a continuous-time signal  $x(t)$ .
- **Demodulator** - reverses continuous time channel output  $y(t)$  to the vector  $y$ .
- **Detector** - decides which symbol decision  $\hat{x}$  minimizes the error probability that  $\hat{x} \neq x$ .



# Example BPSK (wireless revisited)



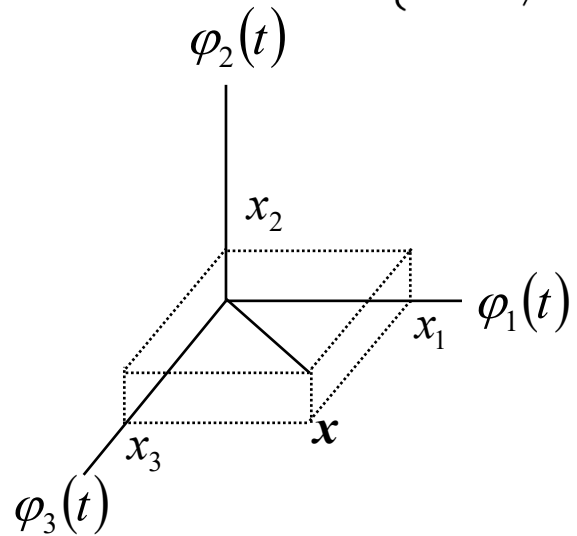
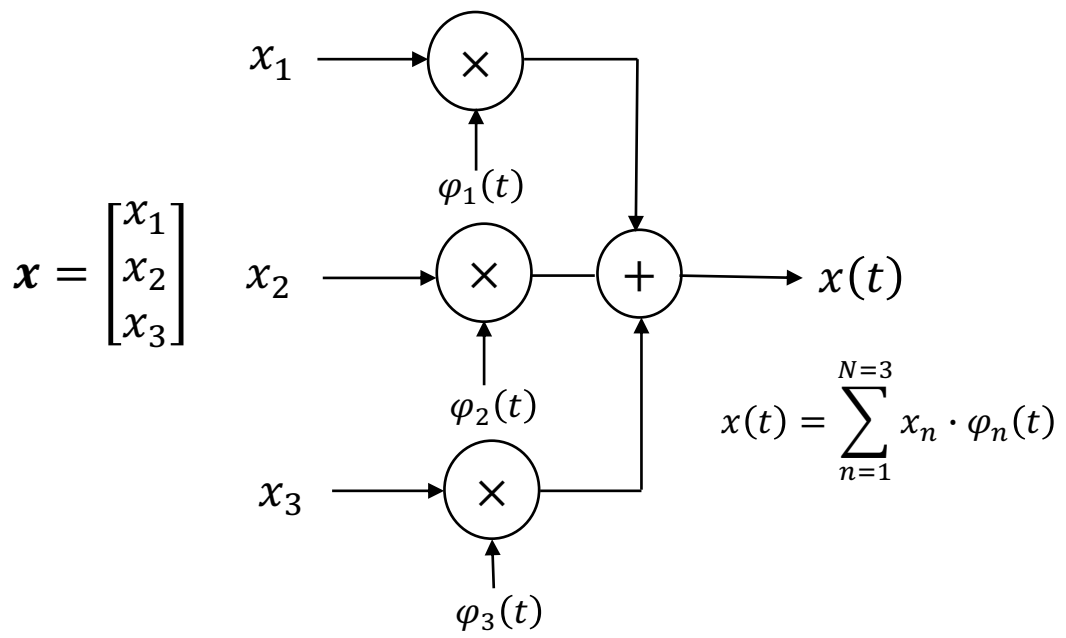
- Simple  $\pm 1$  inputs are not good for this channel, why?
- The modulator tries to match the signal vector to the channel;
  - while the discrete optical-pulse channel appears similar, it has a different modulator.
- However, designers may apply the same analysis to both, as we'll see.



# Formal Modulation – math model

## Modulator's basis functions $\varphi_n(t)$

$$\int_{-\infty}^{\infty} \varphi_m(t) \cdot \varphi_n(t) dt = \delta_{mn} = \begin{cases} 1 & m = n \\ 0 & m \neq n \end{cases}$$



- The basis functions match what the channel can pass well (in good designs).
- Symbol vector has a scalar component  $x_n$  for each dimension (one basis function/dimension, so  $N$  dimensions).
- The constellation  $C = \{\mathbf{x}_1, \mathbf{x}_2 \dots \mathbf{x}_M\}$  (note set of *boldface* vectors, one for each message).



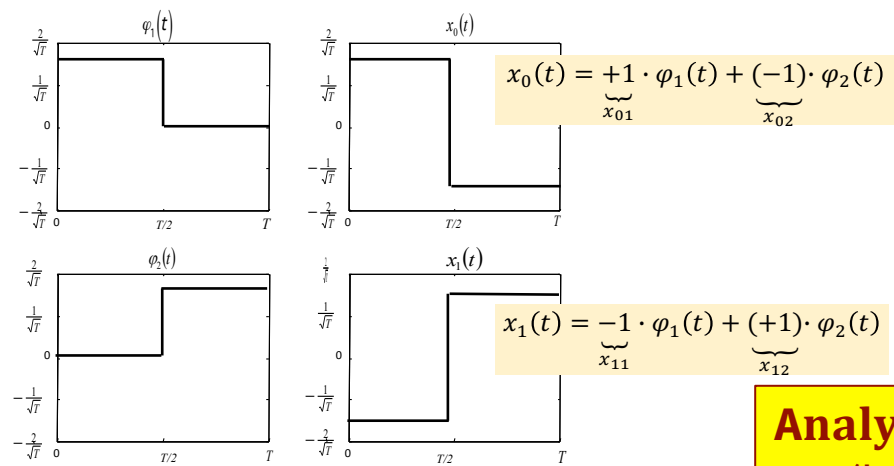
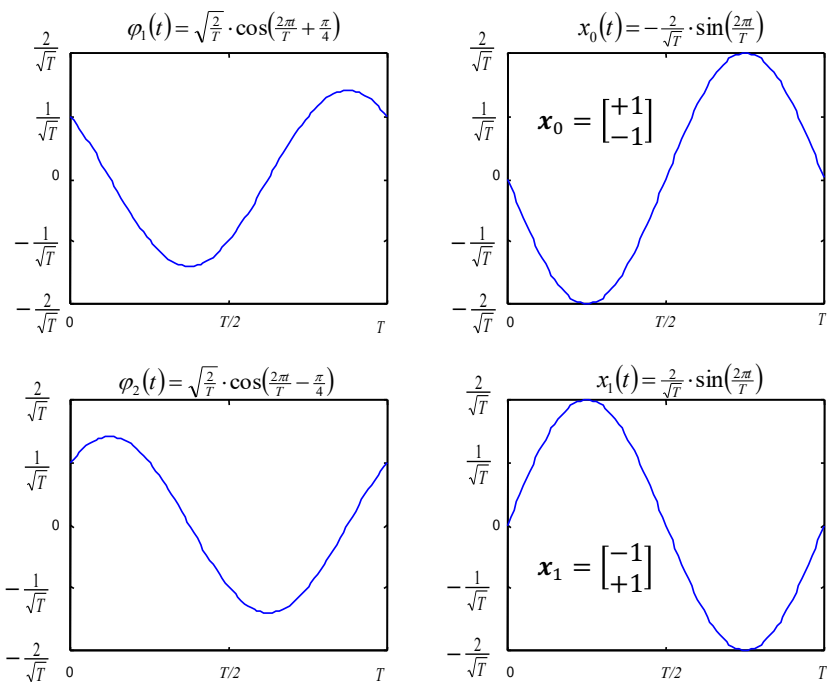
# Binary Phase-Shift Keying (BPSK) and Manchester Examples

- **BPSK** with  $T = 100\text{ms}$  (10 bits/second):

$$\varphi_1(t) = \sqrt{\frac{2}{T}} \cdot \cos\left(\frac{2\pi t}{T} + \frac{\pi}{4}\right) \quad 0 \leq t \leq T$$

$$\varphi_2(t) = \sqrt{\frac{2}{T}} \cdot \cos\left(\frac{2\pi t}{T} - \frac{\pi}{4}\right) \quad 0 \leq t \leq T$$

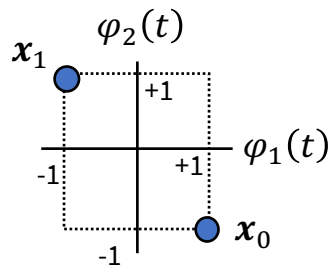
- **Manchester Code** with  $T = 100\text{ms}$  (10 bits/second) is better for simple channels with “binary” transmission:



**Analysis will be same, but modulators differ (because symbols  $x_0$  and  $x_1$  are the same).**



# Common Constellations

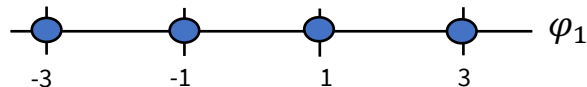


- Common constellation:

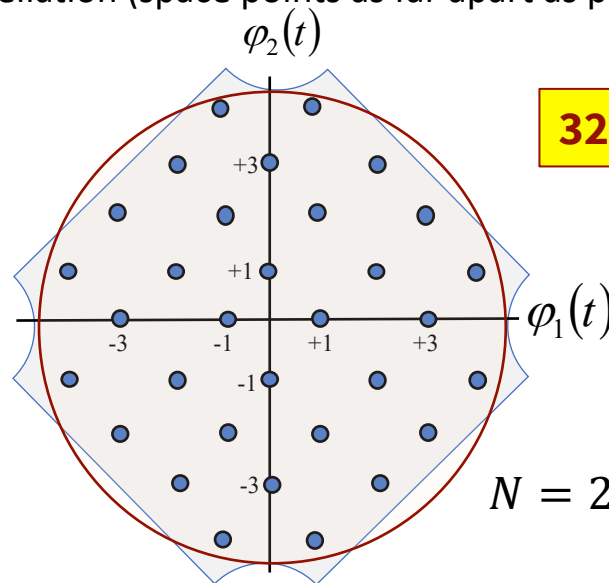
- All such systems' performance follows from the constellation (space points as far apart as possible within limited energy constraint).

- Other Examples:

**4PAM or 2B1Q**



$$N = 1 ; b = 2 ; M = 4$$



**32CR or 32SQ**

$$N = 2 ; b = 5 ; M = 32$$



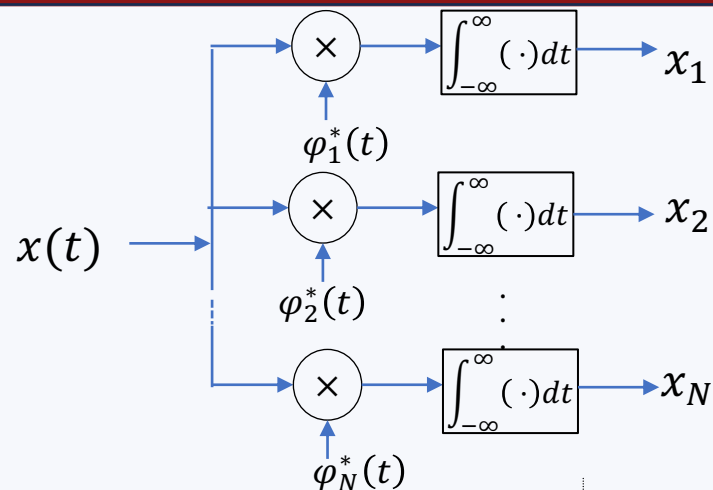


# Demodulator

- **Correlative** demodulator

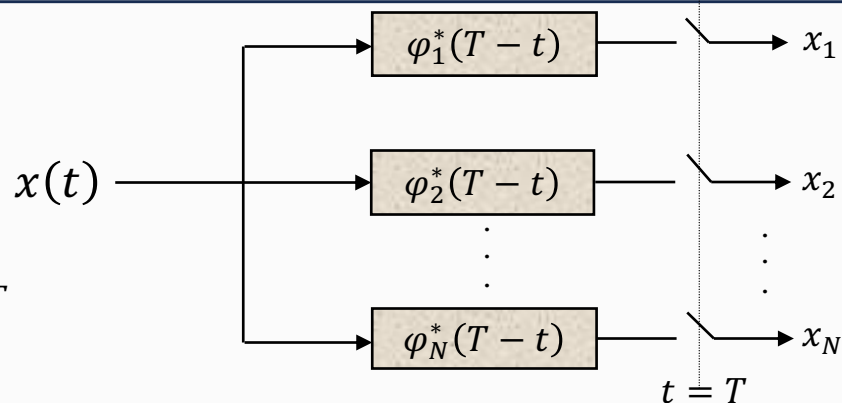
$$\int_{-\infty}^{\infty} x(t) \cdot \varphi_n^*(t) \cdot dt = x_n$$

Conjugate of real equals itself



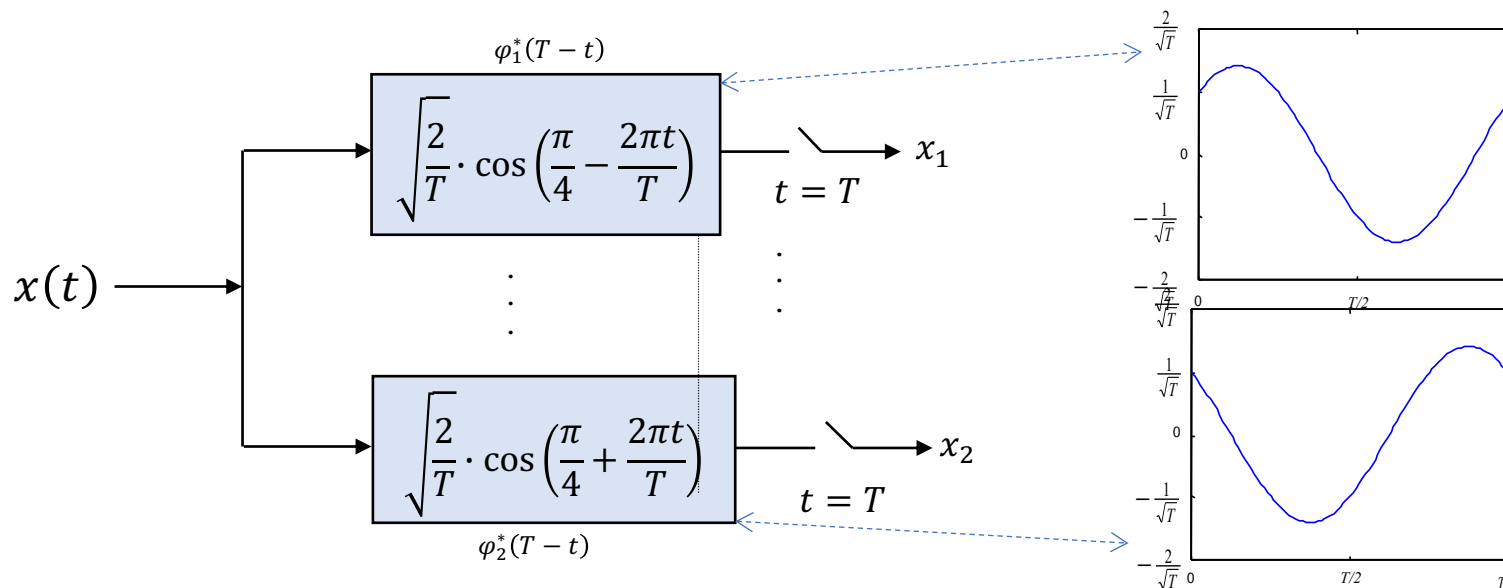
- **Matched-filter** demodulator

$$\int_{-\infty}^{\infty} x(t) \cdot \varphi_n^*(t) \cdot dt = x(t) * \varphi_n^*(T - t)|_{t=T}$$



# BPSK matched-filter demodulator

- The BPSK modulator from slide 22 has corresponding matched-filter demodulator:



- The matched filter's convolution with original basis function produces unity norm at time  $T$ .
- The convolution is perfectly matched to maximize signal energy output at sampling time  $T$ .
- No other (unit-norm) filter sampled at any time can produce a larger SNR (see section 1.3.1.3 proof).



# Inner Products

**Definition 1.2.2 [Inner Product]** The inner product of two (real) functions of time  $u(t)$  and  $v(t)$  is

$$\langle u(t), v(t) \rangle \triangleq \int_{-\infty}^{\infty} u(t) \cdot v(t) dt . \quad (1.41)$$

The inner product of two (real) vectors  $\mathbf{u}$  and  $\mathbf{v}$  is

$$\langle \mathbf{u}, \mathbf{v} \rangle \triangleq \mathbf{u}^* \mathbf{v} = \sum_{n=1}^N u_n \cdot v_n , \quad (1.42)$$

$$u(t) = \sum_{n=1}^N u_n \cdot \varphi_n(t)$$

$$v(t) = \sum_{n=1}^N v_n \cdot \varphi_n(t)$$

where  $*$  denotes vector transpose (and conjugate vector transpose later when complex signals are introduced).

$$\|\mathbf{u}\|^2 = \langle \mathbf{u}, \mathbf{u} \rangle$$

- Easy to prove that

$$\langle u(t), v(t) \rangle = \langle \mathbf{u}, \mathbf{v} \rangle$$

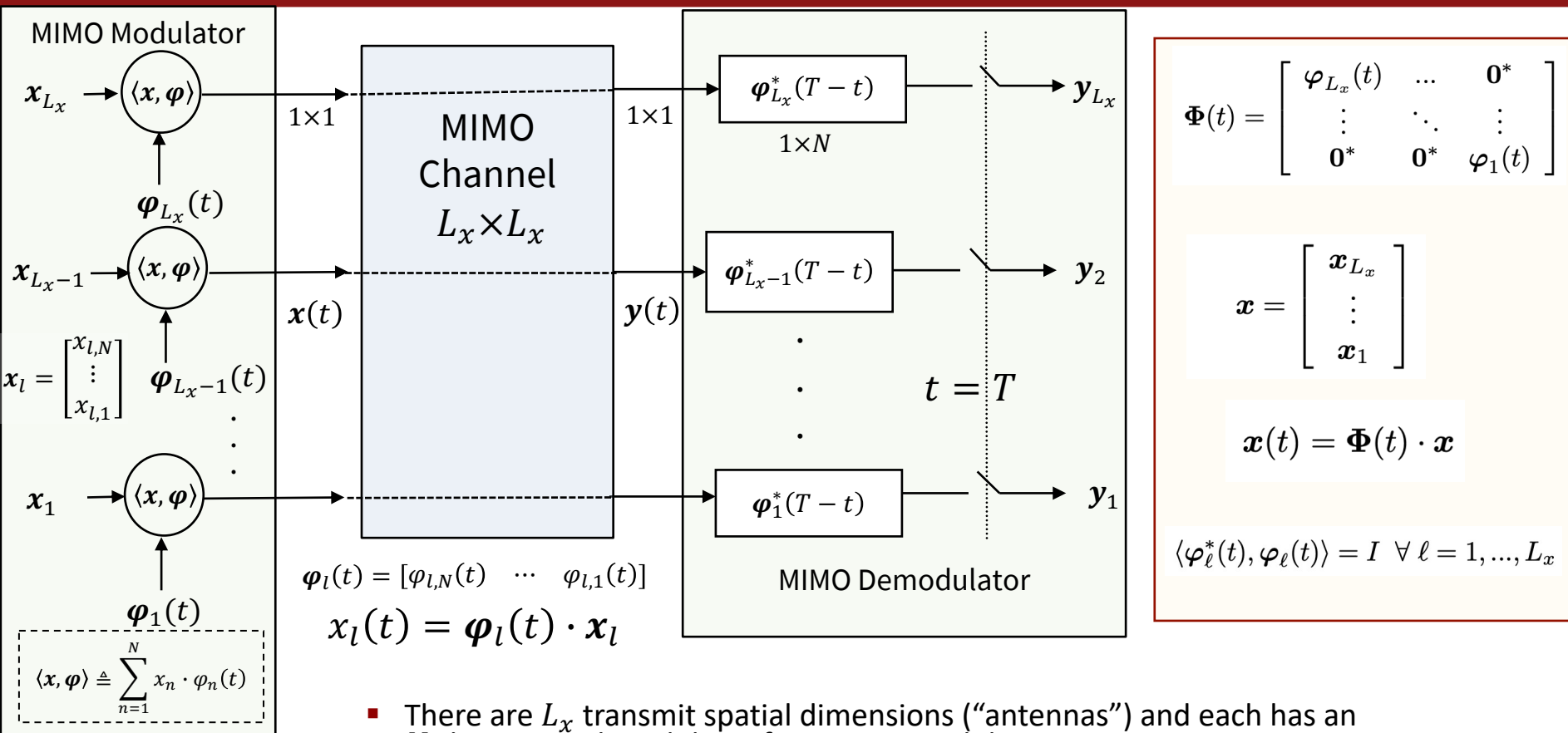
- And further that

**Theorem 1.2.2 [Parseval's Identity]** The following relation holds true for any modulated waveform

$$\mathcal{E}_{\mathbf{x}} = \mathbb{E} [\|\mathbf{x}\|^2] = \mathbb{E} \left[ \int_{-\infty}^{\infty} x^2(t) dt \right] . \quad (1.48)$$



# MIMO Channels



- There are  $L_x$  transmit spatial dimensions (“antennas”) and each has an  $N$ -dimensional modulator for its temporal dimensions.



# Optimum Detection

## *Section 1.1.2*

*See PS1.3 (Prob 4.18), PS1.4 (Prob 4.7), and PS1.5 (Prob 4.25)*

# Minimum Error Probability

**Definition 1.1.3 [Error Probability]** *The Error Probability is*

$$P_e \triangleq P\{\hat{m} \neq m\} .$$

*The corresponding probability of being correct is therefore*

$$P_c = 1 - P_e = 1 - P\{\hat{m} \neq m\} = P\{\hat{m} = m\} .$$

- maximum a posteriori (MAP) detector – given some observed channel output  $\mathbf{y} = \mathbf{v}$  is  $p_{\mathbf{x}/\mathbf{y}}$ .

$$P_c(\hat{m} = m_i, \mathbf{y} = \mathbf{v}) = p_{m/\mathbf{y}}(m_i, \mathbf{v}) \cdot p_{\mathbf{y}}(\mathbf{v}) = \underbrace{p_{\mathbf{x}/\mathbf{y}}(\mathbf{x}_i, \mathbf{v})}_{\text{MAP}} \cdot \cancel{p_{\mathbf{y}}(\mathbf{v})} = \underbrace{p_{\mathbf{y}/\mathbf{x}}(\mathbf{x}_i, \mathbf{v})}_{\text{ML}} \cdot \cancel{p_{\mathbf{x}_i}}$$

Not function of  $\mathbf{x}_i$

- If  $p_{\mathbf{x}_i} = \frac{1}{M}$ , then Maximum Likelihood (ML) is  $p_{\mathbf{y}/\mathbf{x}}$ .



# The MAP and ML Rules

## Rule 1.1.1 [MAP Detection Rule]

$$\hat{m} \Rightarrow m_i \text{ if } p_{\mathbf{y}/m}(\mathbf{v}, i) \cdot p_m(i) \geq p_{\mathbf{y}/m}(\mathbf{v}, j) \cdot p_m(j) \quad \forall j \neq i \quad (1.8)$$

If equality holds in (1.8), then the decision can be assigned to either message  $m_i$  or  $m_j$  without changing the minimized error probability.

## Rule 1.1.2 [ML Detection Rule]

$$\hat{m} \Rightarrow m_i \text{ if } p_{\mathbf{y}/m}(\mathbf{v}, i) \geq p_{\mathbf{y}/m}(\mathbf{v}, j) \quad \forall j \neq i \quad (1.10)$$

If equality holds in (1.10), then the decision can be assigned to either message  $m_i$  or  $m_j$  without changing the error probability.

- Assume that all messages are equally likely, use ML (almost always).
- If the inputs have unequal probabilities, they can be compressed to lower rate with equally likely probabilities.

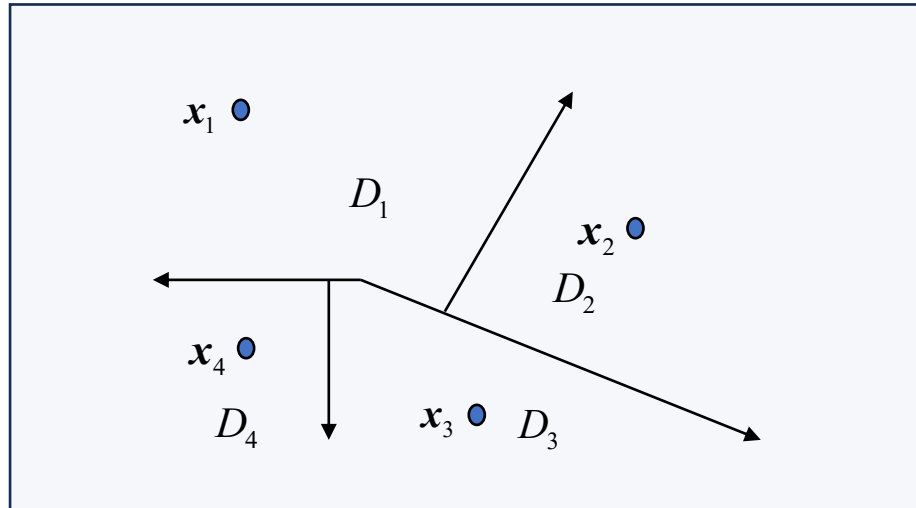
Examples in Lecture 2 and beyond.



# Decision Regions

**Definition 1.1.4 [Decision Region]** The decision region using a MAP detector for each message  $m_i$ ,  $i = 0, \dots, M - 1$  is defined as

$$\mathcal{D}_i \triangleq \{ \mathbf{v} \mid p_{\mathbf{y}/m}(\mathbf{v}, i) \cdot p_m(i) \geq p_{\mathbf{y}/m}(\mathbf{v}, j) \cdot p_m(j) \quad \forall j \neq i \} \quad . \quad (1.12)$$



- Detector “precomputes” the associated decision for every specific value of  $\mathbf{y} = \mathbf{v}$ .





# Decision Regions and Error Probability

- For any decision region

$$\mathbb{E}[P_c] = \sum_{i=0}^{M-1} \sum_{\mathbf{v} \in \mathcal{D}_i} P_c(\hat{m} = m_i, \mathbf{y} = \mathbf{v} \in \mathcal{D}_i)$$

- For MAP

$$P_{c,max} = \mathbb{E}[P_c] = \sum_{i=0}^{M-1} \left\{ \sum_{\mathbf{v} \in \mathcal{D}_i} P_{\mathbf{y}/m_i}(\mathbf{v}, m_i) \right\} \cdot p_{m_i}$$

$$P_{e,min} = 1 - P_{c,max}$$

These (double) sums often simplify greatly, as we'll see.
















# End Lecture 1

- Discrete Data Transmission & Applications
- Encoding and Detection (decoding)
- Modulation and Demodulation
- Vector Channels
- Probability (see Appendix A) – happy to help, off hours, help

Cioffi uses these toolboxes

Name	
	<b>5G Toolbox</b> version 2.6
	<b>Communications Toolbox</b> version 8.0
	<b>Curve Fitting Toolbox</b> version 3.9
	<b>DSP System Toolbox</b> version 9.16
	<b>Optimization Toolbox</b> version 9.5
	<b>Parallel Computing Toolbox</b> version 7.8
	<b>SerDes Toolbox</b> version 3.0
	<b>Signal Processing Toolbox</b> version 9.2
	<b>Statistics and Machine Learning Toolbox</b> version 12.5
	<b>Symbolic Math Toolbox</b> version 9.3
	<b>WLAN Toolbox</b> version 3.6